



# 1D Judge - GS1 US

## Optical Design and User Methodology

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### 1) Lens Calculation (N lens assembly)

$$X_I(X_O, X_L, f) := \begin{cases} \text{"Calculate Image X coordinate for a lens"} \\ \text{"X.O = object coordinate in front of the lens"} \\ \text{"X.L = lens coordinate"} \\ XI \leftarrow \frac{X_O \cdot X_L - X_L^2 + X_O \cdot f}{X_O - X_L + f} \end{cases} \quad \frac{1}{X_I - X_L} + \frac{1}{X_L - X_O} = \frac{1}{f}$$

$$MAG(X_I, X_L, f) := \begin{cases} \text{"Calculate Image Magnification for a lens"} \\ \text{"X.I = image coordinate past the lens"} \\ \text{"X.L = lens coordinate"} \\ MAG \leftarrow \frac{f - (X_I - X_L)}{f} \end{cases} \quad mag = \frac{f - (X_I - X_L)}{f}$$

$$XHIM(X_O, H_O, MLA) := \begin{cases} \text{"X.O = object X coordinate in front of the lens"} \\ \text{"H.O = object height"} \\ \text{"MLA = Matrix Lens Assembly"} \\ \text{"Output: Subsequent Intermediary Images X, H coordinates"} \\ \text{"Last Image is the one on the CCD - if in focus"} \\ XL \leftarrow MLA^{(0)} \\ F \leftarrow MLA^{(1)} \\ XI_0 \leftarrow X_I(X_O, XL_0, F_0) \\ HI_0 \leftarrow H_O \cdot MAG(XI_0, XL_0, F_0) \\ \text{for } I \in 1 \dots \text{rows}(MLA) - 1 \\ \quad \left| \begin{array}{l} XI_I \leftarrow X_I(XI_{I-1}, XL_I, F_I) \\ HI_I \leftarrow HI_{I-1} \cdot MAG(XI_I, XL_I, F_I) \end{array} \right. \\ XH \leftarrow \text{augment}(XI, HI) \end{cases}$$

```

OPTICS(MLA) := "Optical Characteristics"
XL ← MLA<0>
F ← MLA<1>
N ← rows(MLA)
"HP and X.O are arbitrary values"
HP ←  $\frac{F_0}{16}$ 
XO ←  $\frac{F_0}{2}$ 
"Back Focal Point BFP from 0 to N-1"
XBFP0 ← XL0 + F0
for I ∈ 1..rows(MLA) - 1
  XBFPI ← XI(XBFPI-1, XLI, FI)
"Image of Lens position"
XLI0 ← XL0
for I ∈ 1..rows(MLA) - 1
  XLII ← XI(XLII-1, XLI, FI)
"Parallel ray (from infinite) at the pupil at lens 0,1, etc..)"
H0 ← HP
for I ∈ 1..rows(MLA) - 1
  HI ← HI-1 -  $\frac{H_{I-1} \cdot (XL_I - XL_{I-1})}{XBFP_{I-1} - XL_{I-1}}$ 
"Effective Focal Length EFL"
"XHIM Output: Subsequent Intermediary Images X, H coordinates "
"XL(N-1) and N(N-1) position of last lenth and height of the ray"
EFL ← H0 ·  $\frac{\left[ \left( XHIM(XO, H_0, MLA)^{\langle 0 \rangle} \right)_{N-1} - XL_{N-1} \right]}{\left( XHIM(XO, H_0, MLA)^{\langle 1 \rangle} \right)_{N-1} - H_{N-1}}$ 
augment(XBFP, H)
( EFL )
( XBFP )
( H )

```

## 2) Miscellaneous Graphing

```

GRALENS(MLA, pc, daa) :=
  "Graph Lens and Apertures position"
  "Front limiting and lens clear"
  DiaLens ← 1.035·in
  "daa distance lens apex - HA"
  "HA limiting aperture"
  "dfa = distance flange - lens apex - given by manufacturer"
  dfa ← 4.8·mm
  HA ← pc· $\frac{\text{DiaLens}}{2}$ 
  "HP = lens clear aperture - given by manufacturer "
  HP ← 0.9· $\frac{\text{DiaLens}}{2}$ 
  XL ← MLA(0)
  out ← 2·HP
  PUL0 ←
    (
      XL0 - daa -HA
      XL0 - daa -out
      XL0 - dfa -out
      XL0 - dfa -HP
      XL0 - dfa -out
      XL0 -out
      XL0 out
      XL0 - dfa out
      XL0 - dfa HP
      XL0 - dfa out
      XL0 - daa out
      XL0 - daa HA
      XL0 - daa out
    )
  for I ∈ 0..rows(MLA) - 2
    LEX2·I,0 ← XLI+1
    LEX2·I+1,0 ← XLI+1
    LEX2·I,1 ← (-1)I·out
    LEX2·I+1,1 ← (-1)I+1·out
  stack(PUL0, LEX)

```

```

GRASUP( $X_O$ , pc, daa, MLA) := | ""Graph WP Points and Pseudo Marginal Rays at focus"
                               N ← rows(MLA)
                               DiaLens ← 1.035·in
                               out ← DiaLens
                               HA ← pc· $\frac{\text{DiaLens}}{2}$ 
                               HAp ←  $\frac{\text{HA} \cdot X_O}{X_O}$ 
                               ZOB ← [
                                        $X_O$       0·mm
                                        $X_O$       out
                                        $X_O$       -out
                                        $X_O$       0·mm
                                        $(\text{MLA}^{(\theta)})_0$    $\frac{\text{HAp} \cdot X_O}{X_O + \text{daa}}$ 
                                        $(\text{MLA}^{(\theta)})_{N-1}$   $\frac{\text{HAp} \cdot X_O}{X_O + \text{daa}}$ 
                                        $(\text{MLA}^{(\theta)})_{N-1} - X_O$   0·mm
                                        $(\text{MLA}^{(\theta)})_{N-1} - X_O$   out
                                        $(\text{MLA}^{(\theta)})_{N-1} - X_O$   -out
                                        $(\text{MLA}^{(\theta)})_{N-1} - X_O$   0·mm
                                        $(\text{MLA}^{(\theta)})_{N-1}$    $-\frac{\text{HAp} \cdot X_O}{X_O + \text{daa}}$ 
                                        $(\text{MLA}^{(\theta)})_0$    $-\frac{\text{HAp} \cdot X_O}{X_O + \text{daa}}$ 
                                        $X_O$       0·mm
                                   ]
                               ""
                               LRAYS ← ZOB
    
```

$$\text{MOBIM}(X_O, H_O) := \begin{pmatrix} X_O & -H_O \\ X_O & H_O \\ X_O - \frac{H_O}{16} & H_O \cdot \frac{3}{4} \\ X_O + \frac{H_O}{16} & H_O \cdot \frac{3}{4} \\ X_O & H_O \end{pmatrix}$$

```

APIM(X, HO) := "Graph Back Aperture and Sensor"
DiaLens ← 1.035·in
HP ← 0.9· $\frac{\text{DiaLens}}{2}$ 
out ← 2·HP
 $\begin{pmatrix} X & -H_O \\ X & -\text{out} \\ X + 8\cdot\text{mm} & -\text{out} \\ X + 8\cdot\text{mm} & \text{out} \\ X & \text{out} \\ X & H_O \end{pmatrix}$ 

```

### 3) Graphing Chief Rays

```

RAYS(XO, HO, α, MLA) := "Light Rays from the tip of the object passing through Lens 0 at height α H.O"
""
XL ← MLA<0>
F ← MLA<1>
N ← rows(MLA)
XI ← XHIM(XO, HO, MLA)<0>
HI ← XHIM(XO, HO, MLA)<1>
"====="
HA0 ← HO·α
for I ∈ 1..rows(MLA) - 1
    HAI ← HAI-1 +  $\frac{HI_{I-1} - HA_{I-1}}{XI_{I-1} - XL_{I-1}} \cdot (XL_I - XL_{I-1})$ 
XLHA ← augment(XL, HA)
OBJECT ← (XO HO)
IMAGE ← (XIN-1 HIN-1)
stack(OBJECT, XLHA, IMAGE)

```

```

FUNRAYS(XO, HO, pc, daa, MLA) := ""
DiaLens ← 1.035·in
"For CHIEF RAYS"
αA1 ← 1 + ( (pc / 2) · (DiaLens / HO) - 1 ) · (XO / (XO + daa))
αA2 ← 1 - ( (pc / 2) · (DiaLens / HO) + 1 ) · (XO / (XO + daa))
ARAYS ← stack(RAYS(XO, HO, αA1, MLA), reverse(RAYS(XO, -HO, αA1, MLA)))
BRAYS ← stack(RAYS(XO, HO, αA2, MLA), reverse(RAYS(XO, -HO, αA2, MLA)))
""
"For MARGINAL RAYS (Formula to be checked)"
ε ← 0.001
αM ← ( (pc / 2) · (DiaLens / HO) ) · (XO / (XO + daa)) · (1 / ε)
MRAYS ← stack(RAYS(XO, HO, ε, αM, MLA), reverse(RAYS(XO, -HO, ε, αM, MLA)))
SUMRAYS ← stack(ARAYS, BRAYS, MRAYS)

```

```

CALE(XO, MLA) := "Calculate Lens Characteristics:"
"Effective Focal Length"
"Back lens apex to CCD distance"
"Magnification"
XL ← MLA<0>
F ← MLA<1>
N ← rows(MLA)
HO ← 15·mm
XI ← (XHIM(XO, HO, MLA)<0>)N-1
HI ← (XHIM(XO, HO, MLA)<1>)N-1
FL ← -OPTICS(MLA)0
[
"Effective Focal Length" " (FL / mm) " "mm"
"Back lens apex to Image" ( (XI - XLN-1) / mm ) "mm"
"Magnification" " (HI / HO) " ""
]

```

## 4) Managing Graphs

```

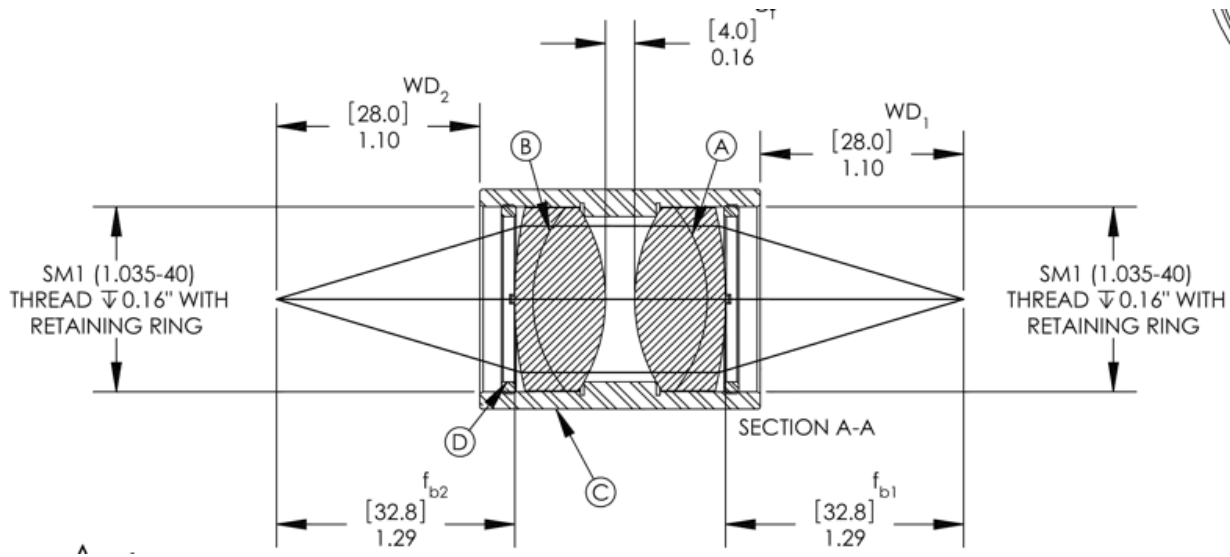
GOLIR( $X_O, H_O, pc, daa, MLA$ ) :=
  ""Graph Object, Lens, Image, and Light Rays"
  HP ←  $H_O$ 
  N ← rows(MLA)
  XL ←  $MLA^{(0)}$ 
  F ←  $MLA^{(1)}$ 
   $X_{OINF}$  ←  $-50 \cdot m$ 
  "Normalize pupil size at H.O"
   $H \leftarrow OPTICS(MLA)_2 \cdot \left( \frac{16}{F_0} \cdot H_O \right)$ 
  RAYP ← augment(XL, H)
   $XBFP \leftarrow XHIM(X_{OINF}, H_O, MLA)^{(0)}$ 
   $XBIM \leftarrow XHIM(X_O, H_O, MLA)^{(0)}$ 
   $HI \leftarrow XHIM(X_O, H_O, MLA)^{(1)}$ 
  POB ←  $(X_O \ H_O)$ 
  RAYP ← augment(XL, H)
   $IMAGE \leftarrow \begin{pmatrix} XBIM_{N-1} & HI_{N-1} \\ XBIM_{N-1} & -HI_{N-1} \end{pmatrix}$ 
  RAYN ← augment(reverse(XL), -reverse(H))
  NOB ←  $(X_O \ -H_O)$ 
   $CENLIN \leftarrow \begin{pmatrix} X_O & 0 \\ XBIM_{N-1} & 0 \\ X_O & 0 \end{pmatrix}$ 
  LRAYS1 ← stack(POB, RAYP, IMAGE, RAYN, NOB, CENLIN)
  LRAYS2 ← FUNRAYS( $X_O, H_O, pc, daa, MLA$ )
  MOB ← MOBIM( $X_O, H_O$ )
  MIM ← MOBIM( $XBIM_{N-1}, HI_{N-1}$ )
  LENS ← GRALENS(MLA, pc, daa)
  X ←  $XBIM_{N-1}$ 
   $\begin{pmatrix} LENS \\ LRAYS_1 \\ MOB \\ MIM \\ LRAYS_2 \end{pmatrix}$ 

```

$$\text{GOTALL}(f_b, x_{22}, H_O, H_{AP}, pc, daa, MLA_1, \Delta X_O, \Delta X_{AP}) := \left\{ \begin{array}{l} \text{"Graph ALL"} \\ X_O \leftarrow -f_b - \Delta X_O \\ \left( \begin{array}{l} \text{ML} \\ \text{MR} \\ \text{MOB} \\ \text{MIM} \\ \text{MRA} \end{array} \right) \leftarrow \text{GOLIR}(X_O, H_O, pc, daa, MLA_1) \\ DFW \leftarrow \text{GRASUP}(-f_b, pc, daa, MLA_1) \\ AS \leftarrow \text{APIM}(f_b + x_{22} + \Delta X_{AP}, H_{AP}) \\ \left( \begin{array}{l} \text{ML} \\ \text{MR} \\ \text{MOB} \\ \text{MIM} \\ \text{DFW} \\ \text{AS} \\ \text{MRA} \end{array} \right) \end{array} \right.$$



## 5) The THORSLABS INC. Paired Doublets



### From the data sheet part number MAP104040-A

D = flange to flange distance = 38.6 mm (1.52 in)

WD = working distance = 28 mm **(That's the distance from back flange to image or front flange to object)**

ΔD = flange to apex = 4.8 mm

f1 = focal length of doublet #1 = 40 mm

f2 = focal length of doublet #2 = 40 mm

**Apex to apex = 29.0 mm**

Lens thickness d.L = 12.5 mm

Lens separation d.s = 4 mm

**The Thorlabs achromatic pair is made of 2 doublets (doublet 1 & 2), each having a focal length f = 40 mm and being separated by a distance d.s ...**

**Each doublet is represented by 2 thin lenses separated by a distance d.L that is the thickness of the doublet at the apex.**

$$\frac{1}{f_1} = \frac{1}{f_{11}} + \frac{1}{f_{12}} - \frac{d_L}{f_{11} \cdot f_{12}} \quad f := 40 \cdot \text{mm} \quad d_L := 12.5 \cdot \text{mm} \quad d_s := 4 \cdot \text{mm} \quad \beta \equiv \frac{1}{6} \quad f_b := 32.8 \cdot \text{mm}$$

$$f_{11} := f \cdot \frac{[2 \cdot f + (\beta - 2) \cdot d_L]}{[f + (\beta - 1) \cdot d_L]} \quad f_{12} := 2 \cdot f + (\beta - 1) \cdot d_L$$

$$f_c(f_{11}, f_{12}, d_L) := \left( \frac{1}{f_{11}} + \frac{1}{f_{12}} - \frac{d_L}{f_{11} \cdot f_{12}} \right)^{-1} \quad f_c(f_{11}, f_{12}, d_L) = 40 \cdot \text{mm} \quad \text{DiaLens} := 1.035 \cdot \text{in}$$

Position of the 4 thin lenses: (lens # 0 at position 0 mm)

$$x_{11} := 0 \cdot \text{mm} \quad x_{12} := d_L \quad x_{21} := d_L + d_s \quad x_{22} := d_L + d_s + d_L$$

$$\text{MLA}_1 := \begin{pmatrix} x_{11} & f_{11} \\ x_{12} & f_{12} \\ x_{21} & f_{12} \\ x_{22} & f_{11} \end{pmatrix} \quad \text{MLA}_1 = \begin{pmatrix} 0 & 77.1831 \\ 12.5 & 69.58333 \\ 16.5 & 69.58333 \\ 29 & 77.1831 \end{pmatrix} \cdot \text{mm}$$

$$pc := \frac{2 \cdot f_b}{\text{DiaLens}} \cdot \tan\left(\frac{7.5}{180} \cdot \pi\right)$$

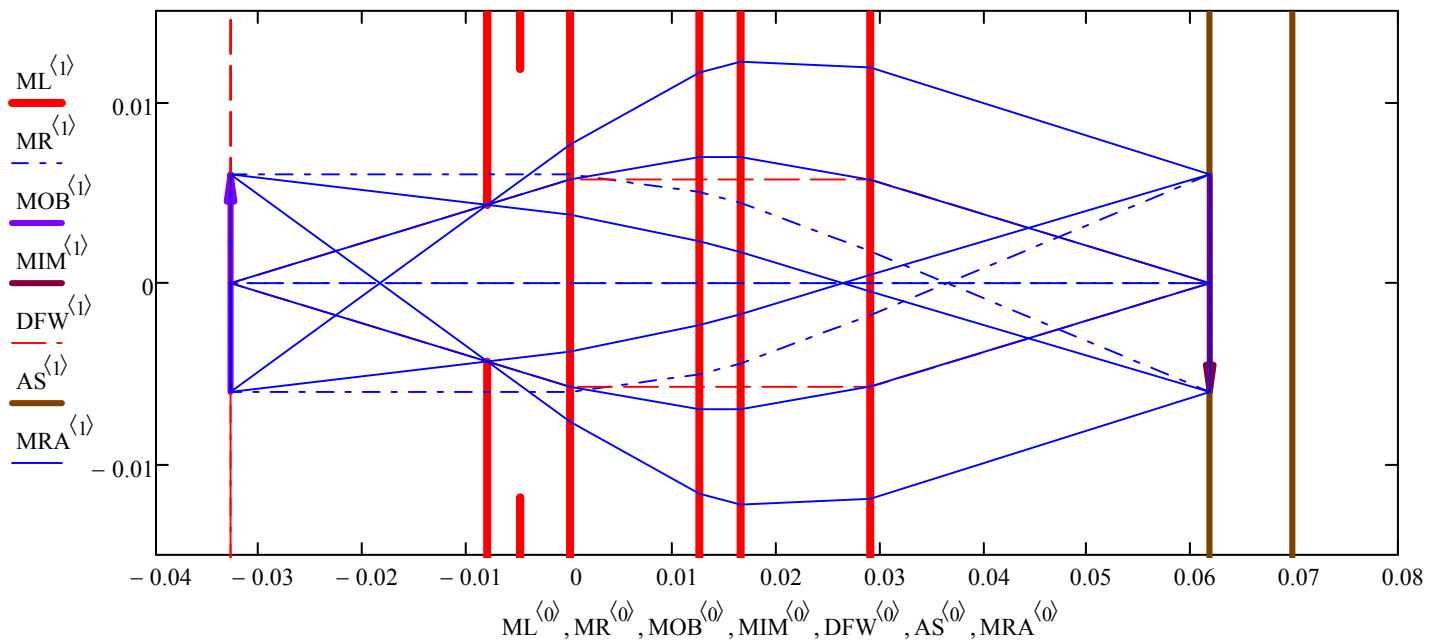
## 6) The Functioning System

$$H_O := 6 \cdot \text{mm} \quad H_{AP} := 6 \cdot \text{mm} \quad \Delta X_O := -0 \cdot \text{mm} \quad \Delta X_{AP} := -0 \cdot \text{mm} \quad pc = 0.329 \quad daa := 8 \cdot \text{mm}$$

$$X_O = -f_b - \Delta X_O$$

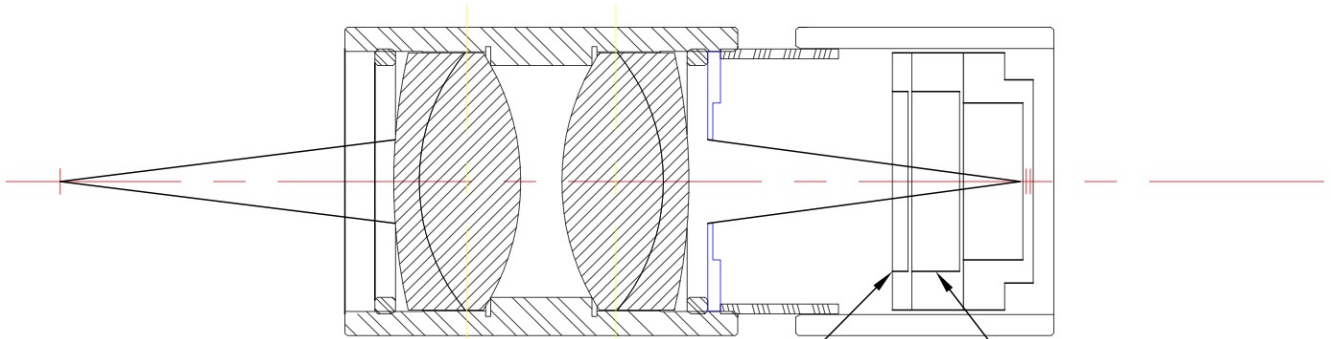
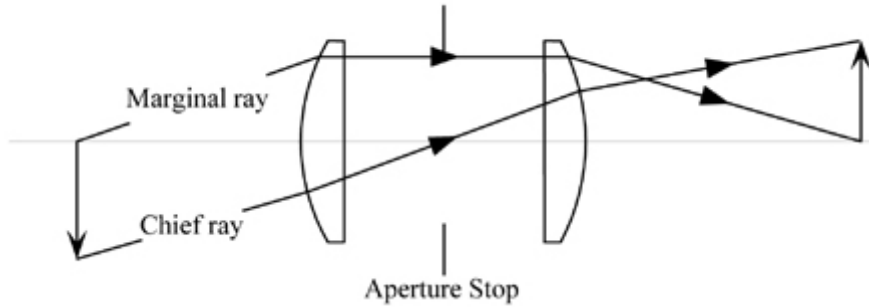
$$\begin{pmatrix} \text{ML} \\ \text{MR} \\ \text{MOB} \\ \text{MIM} \\ \text{DFW} \\ \text{AS} \\ \text{MRA} \end{pmatrix} := \text{GOTALL}(f_b, x_{22}, H_O, H_{AP}, pc, daa, \text{MLA}_1, \Delta X_O, \Delta X_{AP})$$

$$\text{CALE}(-f_b + \Delta X_O, \text{MLA}_1) = \begin{pmatrix} \text{"Effective Focal Length"} & \text{" 25.379 "mm"} \\ \text{"Back lens apex to Image"} & \text{" 32.829 "mm"} \\ \text{"Magnification"} & \text{" -1.001 """} \end{pmatrix}$$

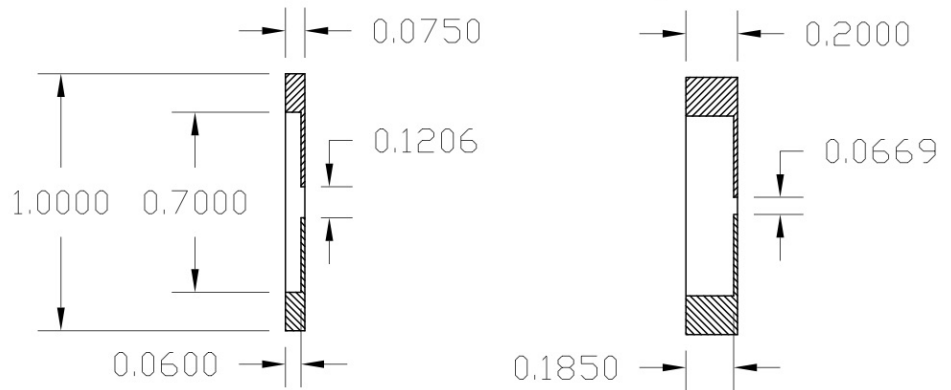


The red vertical lines are located at the apexes of the lens (front and back). I moved the blue object on the left and calculated the position of the brown image and the magnification. Placing the apex of the first lens at zero, I found that for the object position at -32.8 mm (as specify by the manufacturer) I have the sensor surface position at 32.829 and a magnification of -1.001.

That proves that the Working Distance is indeed the distance fb (from back lens apex to sensor surface and from front end apex to sample). Thorlabs gives 32.8 mm...



Aperture 0.325 " in front and back close to the lenses..



## 7) Error Analysis

(misplacement of sample and master aperture: variation of the brightness of the spot)

```

ERANA( $f_b, x_{22}, H_O, H_{AP}, pc, daa, MLA_1, \Delta X_O, \Delta X_{AP}$ ) :=
  "Use the outer Chief Ray passing through the aperture"
  "Calculate the brightness of the spot"
  "=====
   $X_O \leftarrow -f_b + \Delta X_O$ 
   $XL \leftarrow MLA_1 \langle 0 \rangle$ 
   $N \leftarrow \text{rows}(MLA_1)$ 
   $XI \leftarrow \text{XHIM}(X_O, H_O, MLA_1) \langle 0 \rangle$ 
   $HI \leftarrow \text{XHIM}(X_O, H_O, MLA_1) \langle 1 \rangle$ 
  "=====
   $\alpha_{A2} \leftarrow 1 - \left( \frac{pc}{2} \cdot \frac{\text{DiaLens}}{H_O} + 1 \right) \cdot \frac{X_O}{X_O + daa}$ 
   $HA_0 \leftarrow H_O \cdot \alpha_{A2}$ 
  for  $I \in 1.. \text{rows}(MLA_1) - 1$ 
     $HA_I \leftarrow HA_{I-1} + \frac{HI_{I-1} - HA_{I-1}}{XI_{I-1} - XL_{I-1}} \cdot (XL_I - XL_{I-1})$ 
   $XLHA \leftarrow \text{augment}(XL, HA)$ 
  "Outer Chief Ray crossing last lens"
   $CRCL \leftarrow \text{submatrix}(XLHA, N - 1, N - 1, 0, 1)$ 
   $APERT \leftarrow (x_{22} + f_b + \Delta X_{AP} \quad H_{AP})$ 
   $IMAGE \leftarrow (XI_{N-1} \quad HI_{N-1})$ 
   $SL \leftarrow \frac{IMAGE_{0,1} - CRCL_{0,1}}{IMAGE_{0,0} - CRCL_{0,0}}$ 
   $HPR \leftarrow \text{sign}(CRCL_{0,1}) \cdot CRCL_{0,1} + SL \cdot (CRCL_{0,0} - APERT_{0,0})$ 
   $\left( \frac{HPR}{HI_{N-1}} \right)^2$ 

```

$$\Delta X_O := -2 \cdot \text{mm}$$

$$\text{ERANA}(f_b, x_{22}, H_O, H_{AP}, pc, daa, MLA_1, \Delta X_O, \Delta X_{AP}) = 0.88608$$

$$\Delta X_O := 2 \cdot \text{mm}$$

$$\text{ERANA}(f_b, x_{22}, H_O, H_{AP}, pc, daa, MLA_1, \Delta X_O, \Delta X_{AP}) = 1.12551$$

**There is NO maximum of brightness of the spot at focus...**  
**A "working" system has to be built according to the specifications.**

## 8) User Methodology (a CZC suggestion)

### Bar code and blur with circular aperture simulation

```

BLUR(IMA,ND) := "Blur IMA with disk diameter ND"
                MASK ← IMA·0
                R ← rows(IMA) - 1
                C ← cols(IMA) - 1
                for I ∈ 0..ND - 1
                  for J ∈ 0..ND - 1
                    MASKI,J ←  $\Phi \left[ \frac{ND}{2} \cdot \left( \frac{ND}{2} + 1 \right) - \left[ \left( I - \frac{ND}{2} \right)^2 + \left( J - \frac{ND}{2} \right)^2 \right] \right]$ 
                FIMA ← (cfft(IMA)·cfft(MASK))
                AVMA ← icfft(FIMA)
                AVIMA ←  $\frac{AVMA}{\text{mean}(AVMA)} \cdot \text{mean}(IMA)$ 
                MAV ← (Re(AVIMA)· $\Phi(\text{Re}(AVIMA))$ )

```

```

BARSPA(M,N,WL,BL) := "Simple Bar - Space Image"
                    BBM-1,N-1 ← 0
                    BB ← BB + BL
                    WBM-1,N-1 ← 0
                    WB ← WB + WL
                    IMA ← augment(BB, WB, BB, WB, BB, WB, BB, WB, BB)

```

```

NOISE(IMA,NL) := for i ∈ 0..rows(IMA) - 1
                  for j ∈ 0..cols(IMA) - 1
                    NIMAi,j ←  $\text{rnd}(NL) - \frac{NL}{2}$ 
                IMA + NIMA

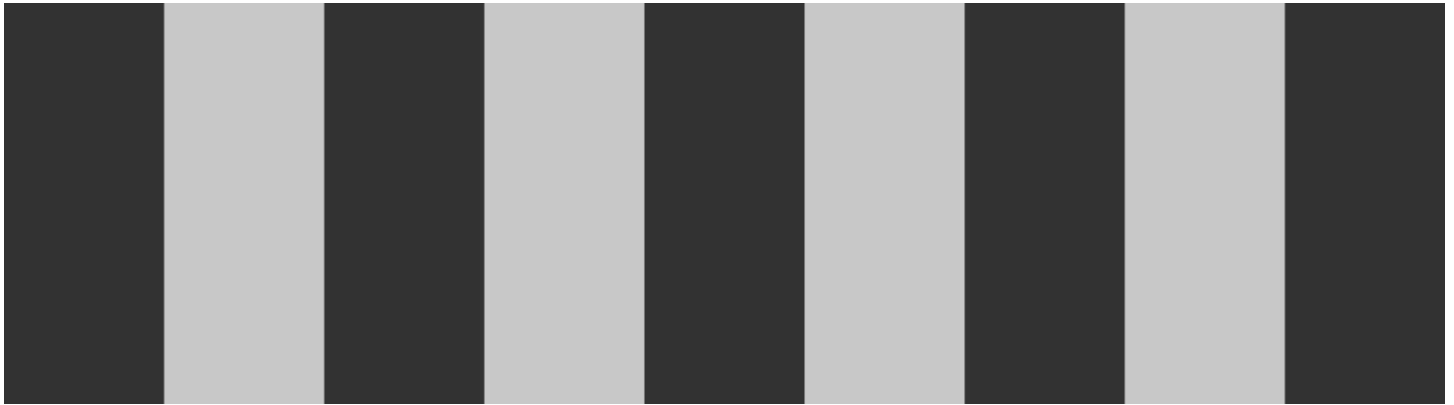
```

```

MAGNIF(MAT,K) := M ← rows(MAT)
                  N ← cols(MAT)
                  for i ∈ 0..K·M - 1
                    for j ∈ 0..K·N - 1
                      MAGMAi,j ←  $\text{MAT}_{\text{floor}\left(\frac{i}{K}\right), \text{floor}\left(\frac{j}{K}\right)}$ 
                MAGMA

```

ZIMA := BARSPA(200,80,200,50)



ZIMA

MAZIMA := MAGNIF(ZIMA,5)

MABIM := BLUR(MAZIMA, 5·D<sub>A</sub>)

BIM := MAGNIF(MABIM,  $\frac{1}{5}$ )



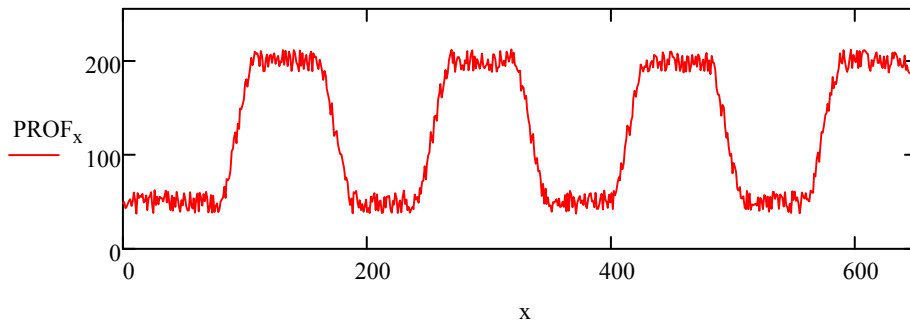
BIM

x := 0..cols(BIM) - 1

D = diameter of aperture      D<sub>A</sub> ≡ 28

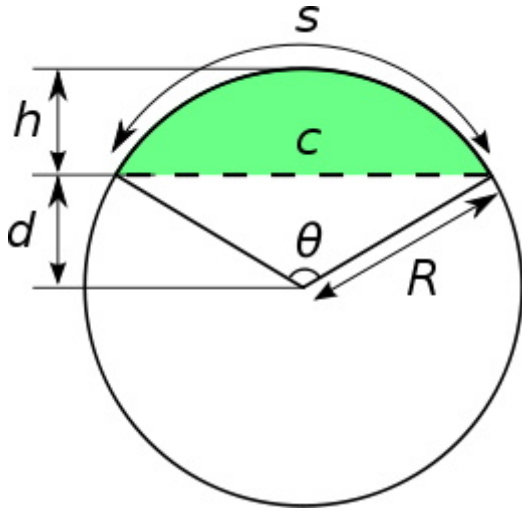
NBIM := NOISE(BIM,25)

PROF<sub>x</sub> := NBIM<sub>100,x</sub>



**Bar Code edge due to circular blur:**

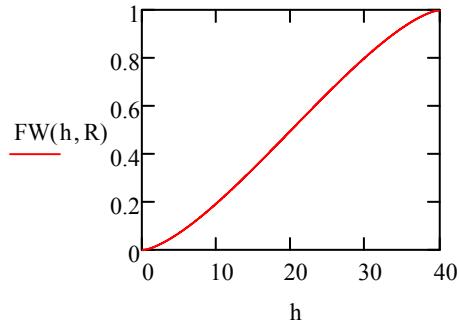
The area of the circular segment is equal to the area of the circular sector minus the area of the triangular portion. We are looking for a function of R and h



$$\theta(h, R) := 2 \cdot \arccos\left(1 - \frac{h}{R}\right)$$

$$FW(h, R) := \frac{1}{2 \cdot \pi} \cdot (\theta(h, R) - \sin(\theta(h, R)))$$

$$R := 20 \quad h := 0, 0.001 \dots 2 \cdot R$$



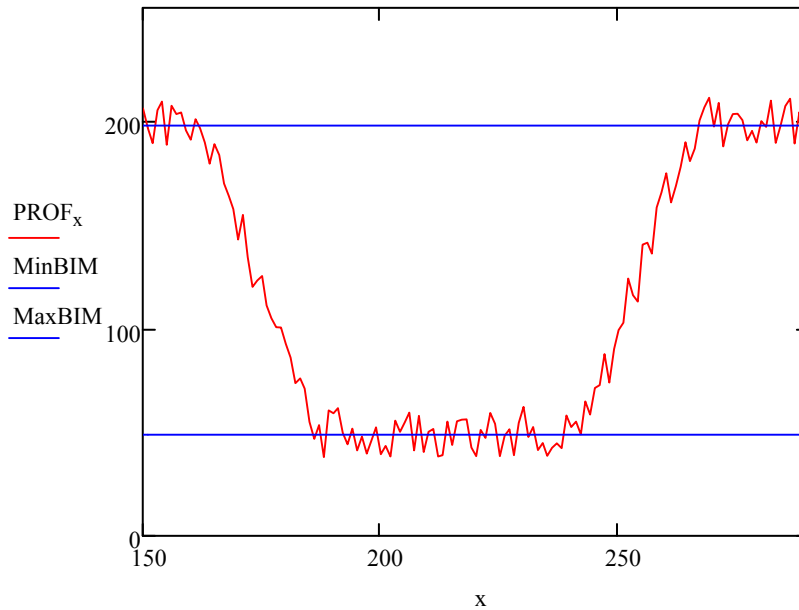
**Calculation of the effective aperture and bar width**

**1) Averaging noise (on top and bottom):**

$$\text{MinBIM} := \frac{1}{31} \cdot \sum_{y=200}^{230} \text{PROF}_y \quad \text{MaxBIM} := \frac{1}{31} \cdot \sum_{y=275}^{305} \text{PROF}_y$$

**(Has to be generalized and optimized for automation)**

$$y := 200 \dots 300 \quad y_0 := 220$$



MinBIM = 48.991

MaxBIM = 198.295

**2) Very simple piece wise function must be fitted:**

$$\text{PHIM}(y, y_0, D) := \text{MinBIM} + \left( \Phi(y - y_0) \cdot \Phi(y_0 + D - y) \cdot \text{FW}\left(y - y_0, \frac{D}{2}\right) + \Phi(y - y_0 - D) \right) \cdot (\text{MaxBIM} - \text{MinBIM})$$

3) Very simple procedure:

```

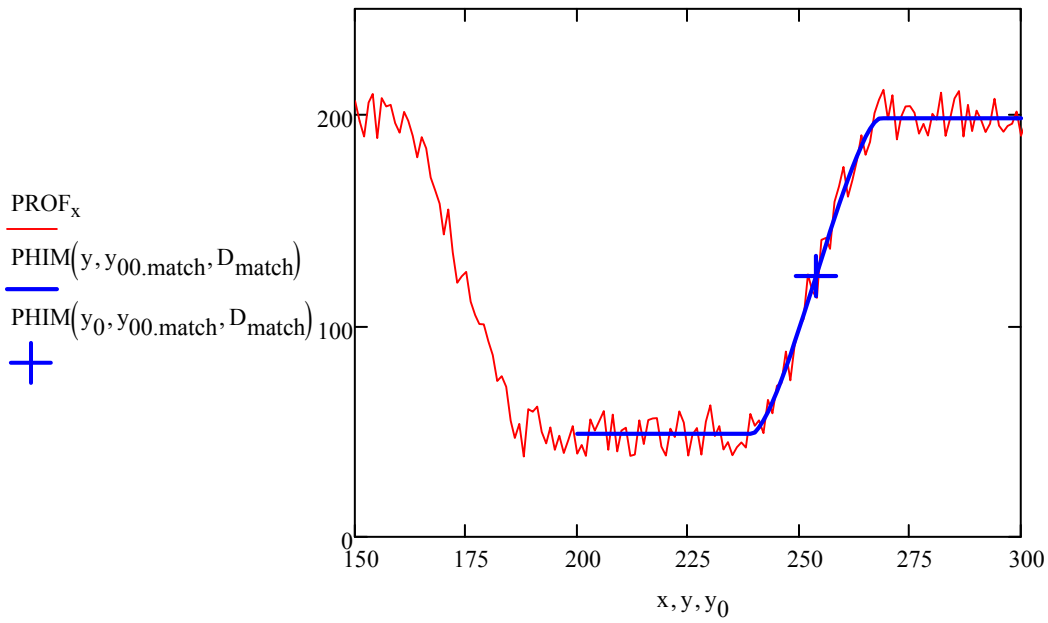
RESOLVE( PROF, x_min, x_max, D_min, D_max ) := ""
y0 ← (x_min + x_max) / 2
for i ∈ 0..500
  D_i ← D_min + (D_max - D_min) * i / 500
  y00_i ← root ( PROF_x - ∑_{x=x_min}^{x_max} PHIM(x, y0, D_i), y0 )
  VAR_i ← ∑_{x=x_min}^{x_max} ( PROF_x - PHIM(x, y00_i, D_i) )^2
n_match ← match( min(VAR), VAR )_0
D_n_match
y0 ← root ( PHIM(y0, y00_n_match, D_n_match) - (MinBIM + MaxBIM) / 2, y0 )
"y.0 is coordinate where to measure the bar width "
( D_n_match
  y00_n_match
  y0 )

```

$$\begin{pmatrix} D_{\text{match}} \\ y00_{\text{match}} \\ y_0 \end{pmatrix} := \text{RESOLVE}(\text{PROF}, 200, 300, 20, 40)$$



$D_{\text{match}} = 28.56 \quad D_A = 28$



That's just an example of fitting one side or a bar. Similar calculation can be done for the other side to measure the bar width. Note that the value of the measured effective aperture, as well as the measured width of the bar are very sensitive to the noise. Multiple profiles with enough data points on the side of the bar have to be used in conjunction with a statistical analysis.

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