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A P P U N T I

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MATERIA: Power Electronics - Temi D'Esame - Prof. Maddaleno

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**ATTENZIONE: QUESTI APPUNTI SONO FATTI DA STUDENTIE NON SONO STATI VISIONATI DAL DOCENTE.
IL NOME DEL PROFESSORE, SERVE SOLO PER IDENTIFICARE IL CORSO.**

Maddaleno
1-1

①

Power electronics: every time we are concerned about efficiency. → Electrical energy

DC → DC
DC → AC
AC → DC
AC → AC

Main conversions

In this course we only study these two

- DC → DC : converter
- DC → AC : ~~the~~ inverter
- AC → DC : rectifier
- AC → AC : (cyclic converters, nowadays not so much used, better performances with AC → DC → AC)

All electronic circuits need a DC supplier

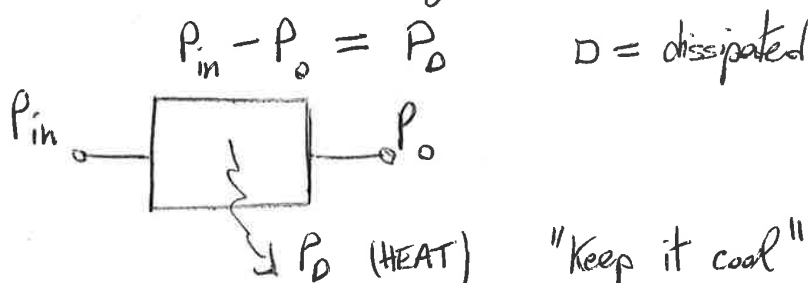
Power levels from fractions of W to MW and it's still power electronics.

To be precise, POWER EFFICIENCY

efficiency, $\eta = \frac{P_o}{P_{in}}$

Important for many reasons, most important one money.

Measurements are not so easy. Your instruments can lie to you.



2) POWER SAVING

Maddaleno
1-2 (2)

3) How much does the electric energy from the main cost? $0,2 \text{ €}/(\text{kWh})$

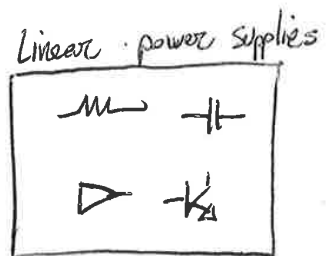
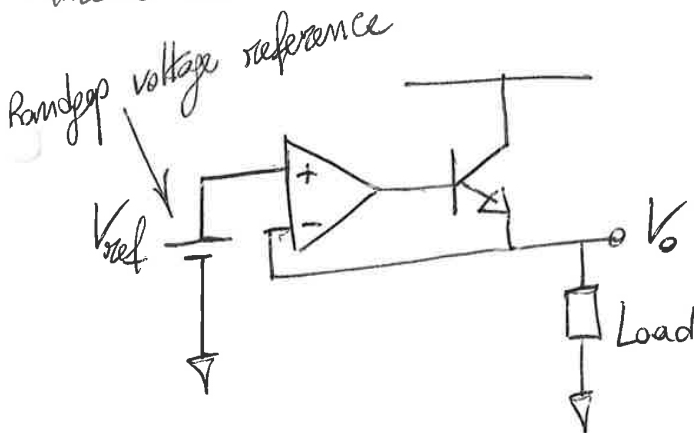
But in some applications the energy cost A LOT for example with batteries; $\sim 20 \text{ €}/(\text{kWh})$
Portable objects, like self phones.

PORTABLE DEVICES: LONGER ENDURANCE

SWITCH MODE CONVERSION to obtain an high efficiency. It's the only way.

LINEAR POWER SUPPLIES: transistor used as a linear device.

closed loop negative feedback circuit.



power dissipation: voltage across the transistor and current through it

With linear conversion we can only step down the voltage. The collector/drain has to be higher than the load.

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1-2

3

With switch conversion we can even obtain an opposite voltage, an isolated voltage, ecc. Even an higher voltage.

With switch mode we can have multiple outputs.

Switch converters are complicated

○ Over the crossover frequency the system do what it can.

The linear ones can be fast, the switching ones are slower.

Linear power supplies have very little E.M. noise, while a switching power supply is a good noise source.

Can we use synthesized inductors? No for several reasons, first one: in our inductors flow several amps. We should use POWER OPAMPS ... which have very bad efficiency!

1-3

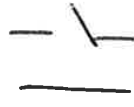
We can use synthesized inductors in filters.

HYPOTHESES

Maddaleno (4)



Switches ideal



no voltage across a closed switch.

1-3



RC or $\frac{L}{R}$ time constants, τ

$\tau \gg T_{SW}$ period of switching

there are capacitors and inductors and capacitors we will deal with LINEAR (and not exponential) waveforms.

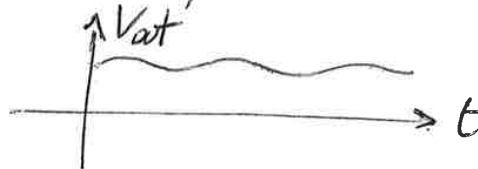
R could be the parasitic resistance of an inductor, for example

for a short period of time a sinusoidal waveform is linear

this hypothesis means that efficiency is one!



Output voltage is constant, that means no ripple!
we are cheating

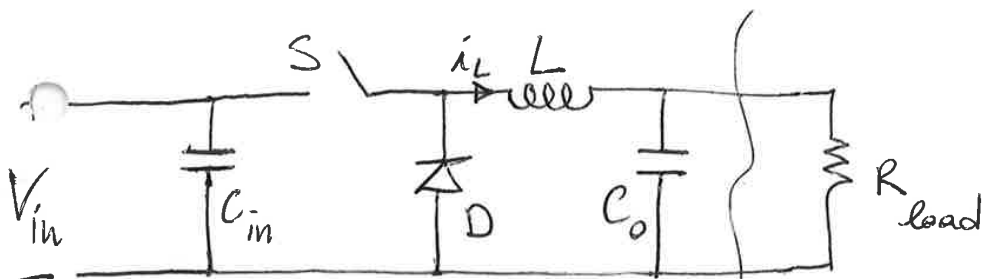


BUCK

Modulo 5

5

1_3



I don't know what the load is

The switch can be a BJT, a THYRISTOR, an IGBT...

THYRISTOR: switched on by a command, but it turns off only when the current through it goes to ϕ .

Is a diode a switch as well? Well, if you patent it so...

HERE IT IS A NON-CONTROLLED BY YOU SWITCH

MODES OF OPERATION

1_4

CCM, Continuous Conduction Mode

DCM, Discontinuous Conduction Mode

The difference is the behavior of the inductor current i_L

CCM $i_L \neq 0$, in some cases $i > 0 A$

DCM: $i_L = 0$ in part of ^{the} cycle

(The real fact is about the derivative of i_L)

CCM/DCM change completely the behavior of the circuit.

We can't recognize the behavior looking at the schematic.

$$\overline{i_c} = C \frac{d\overline{v_c}}{dt} = 0 \quad \text{too in}$$

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1-4 (6)

cyclostationary conditions,

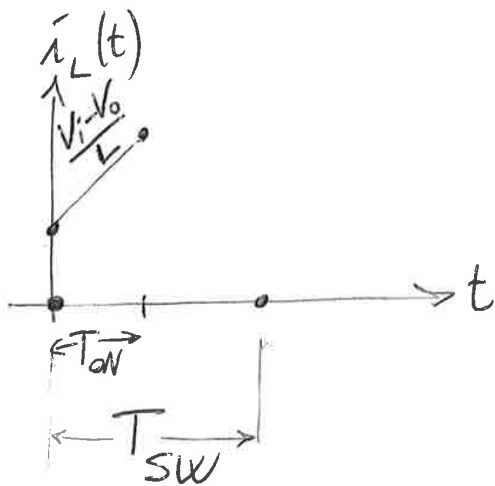
A capacitor for a DC is an open circuit.

Capacitor with a constant current and a constant current:
the capacitor fails!

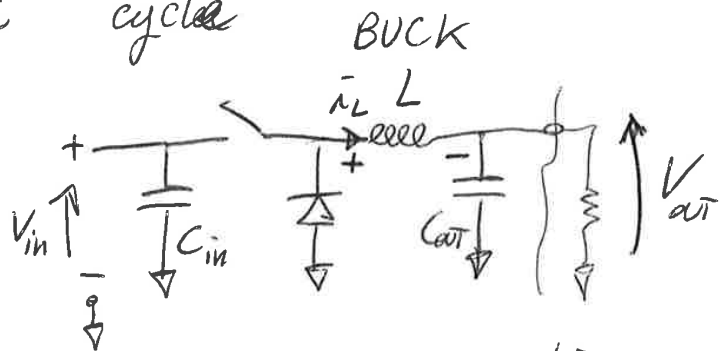
CYCLOSTATIONARY CONDITIONS

$$\begin{cases} \overline{v_L} = 0 \\ \overline{i_c} = 0 \end{cases}$$

FIND OUT $\overline{i_L}(t)$



CCM : at the beginning the current has an initial value which is the final value from the previous cycle



If the switch is ON:

$$v_L = L \frac{di_L}{dt} = V_{in} - V_{out} \quad v_L = L \frac{di_L}{dt}$$

The derivative is constant. The slope of the current is constant. The current will go up with a slope of $\frac{V_{in} - V_{out}}{L}$ while the switch is ON (closed)

But we made a lot of assumptions!

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(7)

1-4

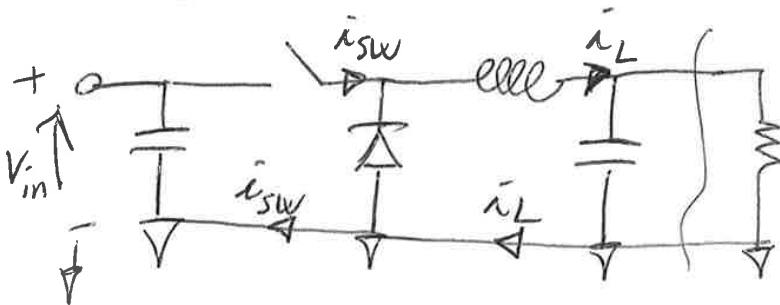
with a real switch

$$\left(\frac{V_{in} - V_{\text{switch closed}}}{L} \right) T_{ON} - \left(\frac{V_o + V_{\text{switch open}}}{L} \right) T_{OFF} = 0$$

The waveforms are "partial parts" of a sinusoid.

BUCK

~~2-1~~

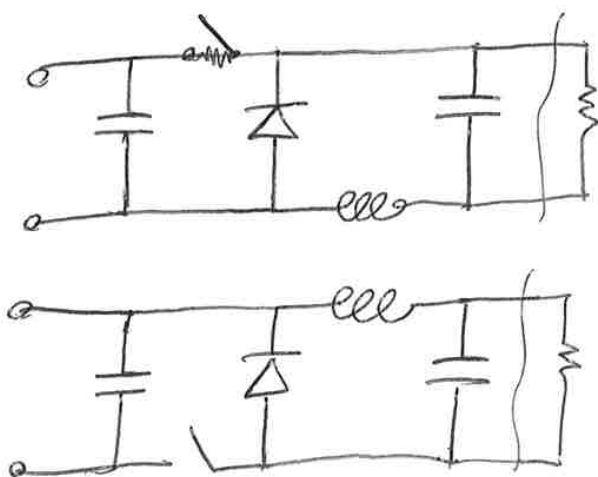


2-1

CCM: the inductor current is never constant

$$V_o = V_{in} D, \quad D = \frac{T_{ON}}{T_{ON} + T_{OFF}} = \frac{T_{ON}}{T_{SW}}$$

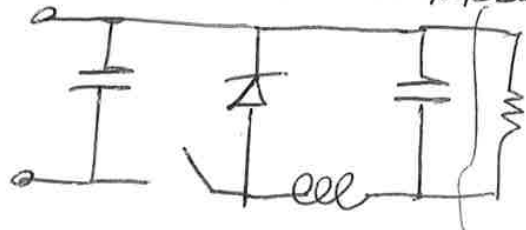
Topologies: there are other topologies.



Still a buck

BAD TOPOLOGIES

STILL AN OK TOPOLOGY



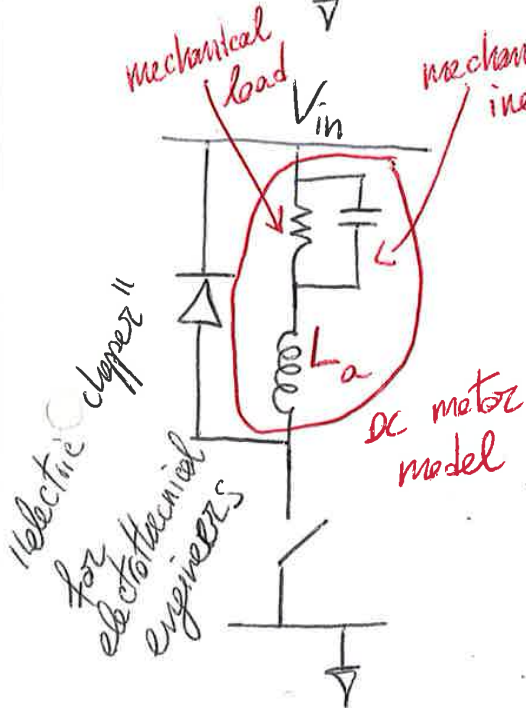
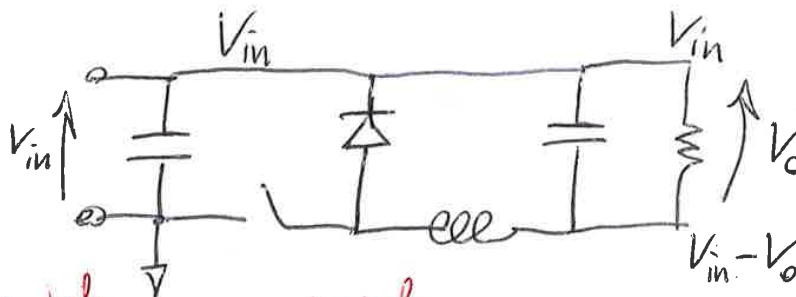
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2-1

8

The ground plane / chassis acts like a big capacitor in conjunction with the rest of the universe. We are moving fast a lot of voltage across it: radio transmitter.

So we have to pay attention.



This is still a buck

This is the typical circuit to drive an electric DC motor

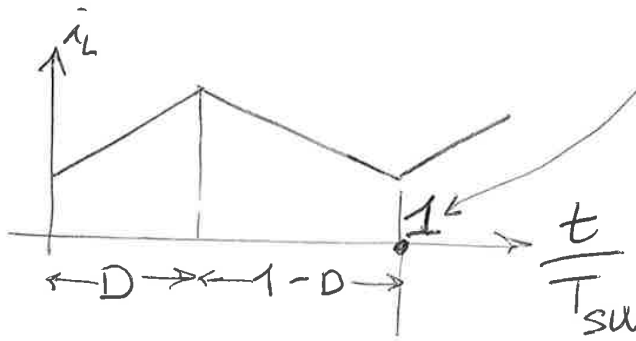
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9

2-1

$$\frac{T_{on}}{T_{sw}} = D$$

$$\frac{T_{off}}{T_{sw}} = 1 - D$$



strictly speaking D is dimensionless, in fact we change the time dimension

$$\frac{V_{in} - V_{sw} - V_o}{L} D - \frac{V_o + V_o}{L} (1 - D) = 0$$

↳ We cannot avoid the inductor!

L can not be zero (mathematical answer)

$$V_o = (V_{in} - V_{sw}) D - V_o (1 - D)$$

V_o is always smaller than V_in

How much duty cycle I want to get the voltage I want?

$$D_{real} = \frac{V_o - V_o}{V_{in} - V_{sw} + V_o}$$

Nowadays 1,2V for a processor, the numbers become important

Maddaleno

2-1 (10)

$$\frac{\Delta V_o}{\Delta I_o} = \text{LOAD REGULATION}$$

$$V_o = V_{in} \cdot D$$

$$\frac{\partial V_o}{\partial V_{in}} = D \quad \text{audio susceptibility}$$

$$\frac{\partial V_o}{\partial D} = V_{in} \quad \text{gain, if the input voltage changes, the gain changes.}$$

$$\frac{\partial V_o}{\partial I_o} = 0 \quad \text{if I don't consider any loss}$$

$$\frac{V_o}{V_{in}} = M \quad \text{for any converter}$$

only for buck, $M = D$

$$\text{for any converter } V_o = V_{in} \cdot M$$

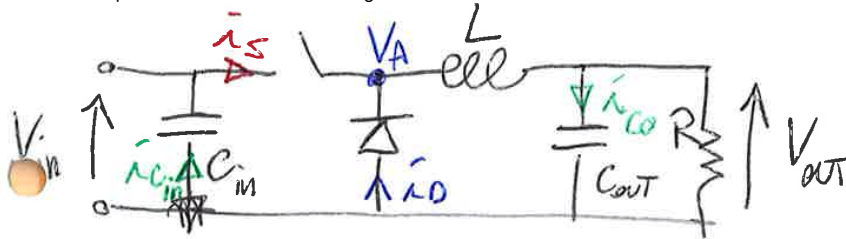
$$\frac{\partial V_o}{\partial V_{in}} = M \quad \text{audio susceptibility}$$

$\frac{\partial V_o}{\partial I_o} = 0$ wonderful, it looks like a voltage source

in CCM $\frac{\partial V_o}{\partial I_o} \approx 0$, no matter what converter is

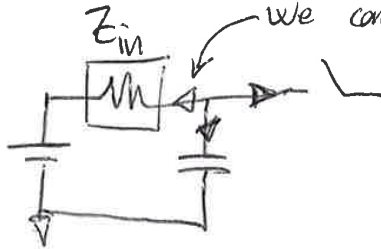
in DCM it becomes quite larger than 0.

Macchalemo
2-2 (11)

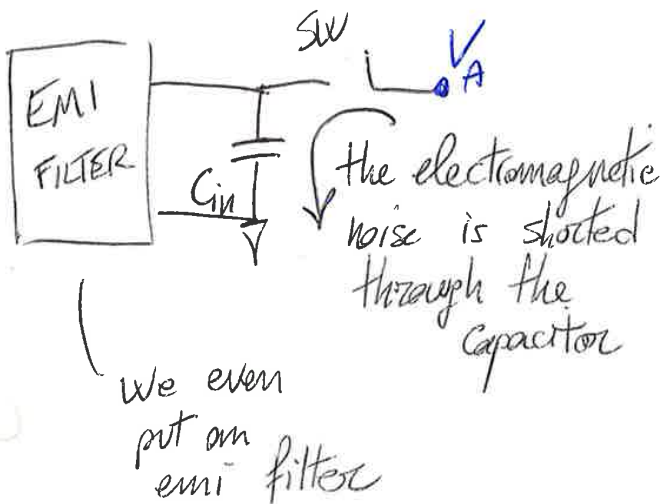


With a constant V_{in} and ideal V_{in} , if C_{in} is charged (already), no current flows through C_{in}

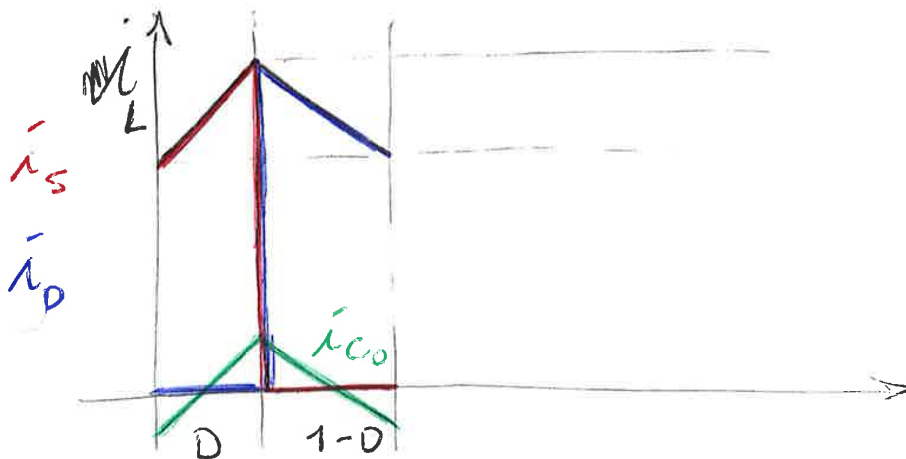
No ideal V_{in} exists! So something always flows in the capacitor
we cannot inject things in V_{in} !



C_o is there to maintain small L
(second order filter)



We already draw two waveforms: $V_A(t)$, $i_L(t)$



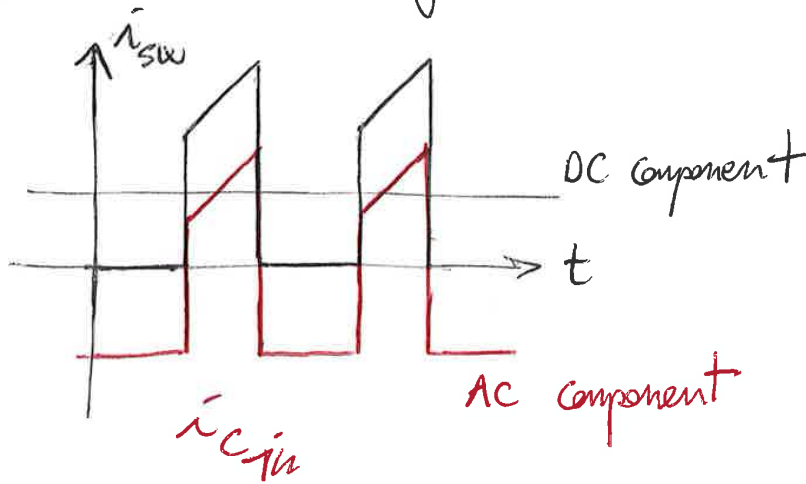
during T_{ON}
 $i_s \approx i_L$
during T_{ON} , $i_D = 0$
during T_{OFF} ,
 $i_D \approx i_L$

The capacitor "steals" all the ripple.

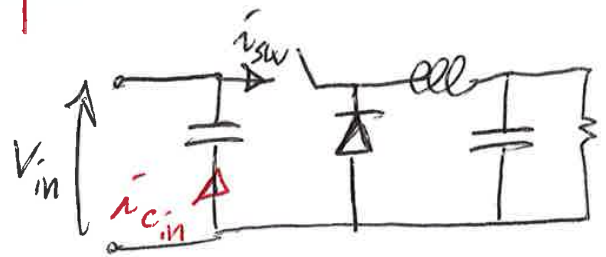
Maddaleno (12)

We apply the same reasoning for C_{in}

2-2

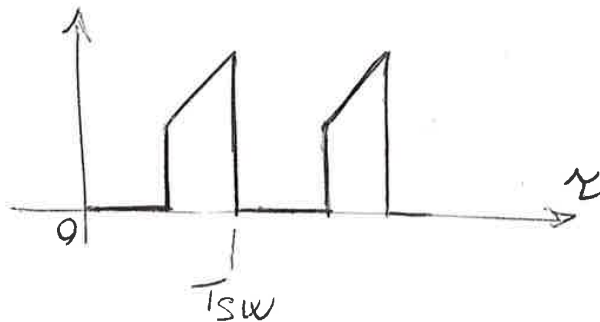


The output capacitor has a good life.



The input capacitor has a STRESSFUL LIFE: it has to sustain high currents!

FIND THE AVERAGE VALUE OF A PERIODIC WAVEFORM



$$\bar{r} = \frac{1}{T_{sw}} \int_0^{T_{sw}} \hat{r}(\tau) d\tau$$

Let's find the area, spread it along one period



Area of the parabola: $\frac{2}{3}$ of the rectangle.

$$\Delta I_L = \frac{V_{in} - V_o}{L f_{sw}} D = -\frac{-V_o (1-D)}{L f_{sw}}$$

Maddaleno

3_1

13

We will use

$$\Delta I_L = \frac{V_o (1-D)}{L f_{sw}}$$

- Attention: hypothesis!

No switch voltage (perfect one), no ripple,
straight lines

$$I_{max} - I_{min} = \frac{V_o}{L f_{sw}} (1-D)$$

$$\frac{I_{max} + I_{min}}{2} = \frac{V_o}{R}$$

$$2 I_{max} = 2 \frac{V_o}{R} + \frac{V_o}{L f_{sw}} (1-D)$$

$$I_{max} = V_o \left(\frac{1}{R} + \frac{1}{2L f_{sw}} (1-D) \right)$$

$$I_{min} = V_o \left(\frac{1}{R} - \frac{1}{2L f_{sw}} (1-D) \right)$$

peak current
for the
inductor!

$\frac{V_o}{R}$ is the
output current!

Maddaleno

(14)

10 W

1 MHz \rightarrow 300 kHz

it goes down a lot using

BJT or IGBT ~~or MOSFET~~

3-1

100 W

500 kHz \rightarrow 100 kHz

1 kW

100 kHz \rightarrow 20 kHz

IT IS
CONVENIENT
TO USE A
LARGER FREQUENCY
TO USE A
SMALLER INDUCTOR

$$L = \frac{(1-D)R}{2f_{sw}} \quad \text{for a buck converter}$$

CRITICAL INDUCTANCE

"Crinale" part of the mountain that divides water

R changes! Variable loads

CRITICA \rightarrow DISTINGUO

$$D = \frac{V_o}{V_{in}} \quad \leftarrow \text{the main can change, universal power supplies...}$$

$$\frac{V_o}{V_{in, \max}} < D < \frac{V_o}{V_{in, \min}}$$

TO STAY IN CCM!

$$I_{\min} > 0$$

Worst case:
$$\frac{V_o}{R} - \frac{V_o(1-D)}{2f_{sw}L} > 0$$

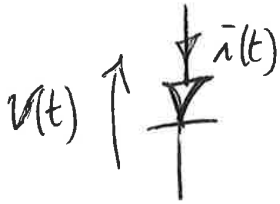
\downarrow R is maximum and D is minimum

$\overline{p(t)} = \overline{v(t)i(t)}$ WHICH IS NOT $\overline{v(t)}\overline{i(t)}$

Maddaleno (15)

$P_{AVE} = \frac{1}{T_{SW}} \int_0^{T_{SW}} v(t)i(t) dt$

3-2



$v(t)$ is almost constant
(order of magnitude $\sim 1V$)
for power diodes.

Schottky in signal domain, $\sim 0,1V$
in power electronics $\sim 0,5V$

Si-Carbide, \sim very fast but $\sim 2V$

BJT, IGBT, V_{CEsat} is almost constant

$\hat{i}_o(t)$ $P_{AVE} = \frac{1}{T_{SW}} V_o \int_0^{T_{SW}} \hat{i}_o(t) dt = V_o I_{AVERAGE}$

A circuit diagram showing a diode symbol. A downward-pointing arrow is labeled $\hat{i}_o(t)$. An upward-pointing arrow is labeled V_o .

$\hat{i}(t)$ $P_{AVE} = \frac{1}{T_{SW}} \int_0^{T_{SW}} v(t)i(t) dt = \frac{1}{T_{SW}} \int_0^{T_{SW}} R i^2(t) dt$

A circuit diagram showing a resistor symbol. A rightward-pointing arrow is labeled $\hat{i}(t)$. A downward-pointing arrow is labeled $v(t)$.

$P_{AVE} = R I_{RMS}^2$

$RMS(x) = \sqrt{\int x^2}$

There is no RMS power

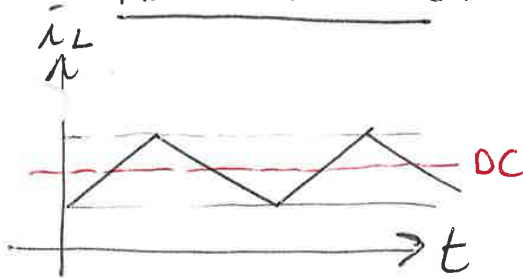
~~RMS~~ power is meaningless, W_{RMS} does not exist

What is important is the average power

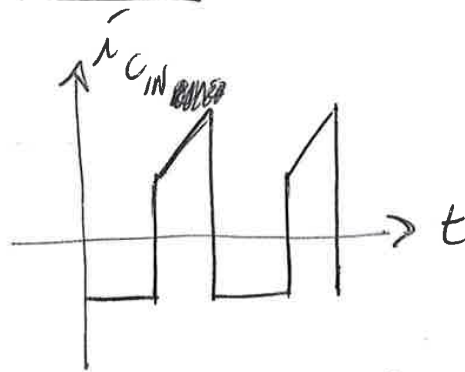
Maddaleno

16

INDUCTOR CURRENT



INPUT CAPACITOR CURRENT



3_2

$\bar{i}_{L_{RMS}}$: this tells me the stress on the wire and how much power

$\bar{i}_{C_{in_{RMS}}}$ is what stresses the capacitor, very important

I loose.

A SORT OF KCL FOR RMS

$$\bar{i}(t) = I_{DC} + \bar{i}_{AC}(t)$$

$\overline{\bar{i}_{AC}(t)} = 0$ the AC component has average 0

$$RMS(\bar{i}(t))^2 = \frac{1}{T_{SW}} \int_0^{T_{SW}} (I_{DC} + \bar{i}_{AC}(t))^2 dt =$$

$$= \frac{1}{T_{SW}} \int_0^{T_{SW}} I_{DC}^2 dt + \frac{1}{T_{SW}} \int_0^{T_{SW}} 2 I_{DC} \bar{i}_{AC}(t) dt + \frac{1}{T_{SW}} \int_0^{T_{SW}} \bar{i}_{AC}^2(t) dt$$

Zero because we have the average of \bar{i}_{AC}

$$RMS(\bar{i}(t))^2 = I_{DC}^2 + I_{AC_{RMS}}^2$$

that's a sort of KCL

$$I_{TOTAL_{AC+DC_{RMS}}}^2 = I_{DC}^2 + I_{AC_{RMS}}^2$$

for a capacitor, we have no DC component

$$I_{AC\ RMS}^2 = \frac{\Delta I_L^2}{12}$$

Maddaleno (17)

3-3

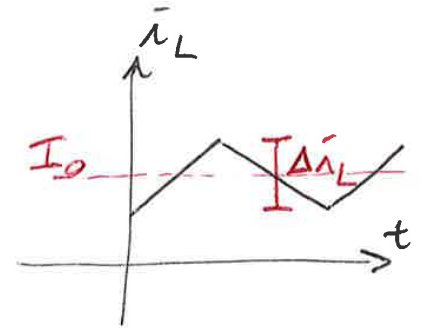
$$I_{TOTAL\ AC+DC\ RMS}^2 = I_{DC}^2 + I_{AC\ RMS}^2$$

We are "adding two powers" but there is not a resistance...

in the Hilbert space they are orthogonal

So we have

$$I_{L\ RMS}^2 = I_0^2 + \frac{\Delta \hat{i}_L^2}{12}$$



$$I_{L\ RMS} = \sqrt{I_0^2 + \frac{\Delta \hat{i}_L^2}{12}}$$

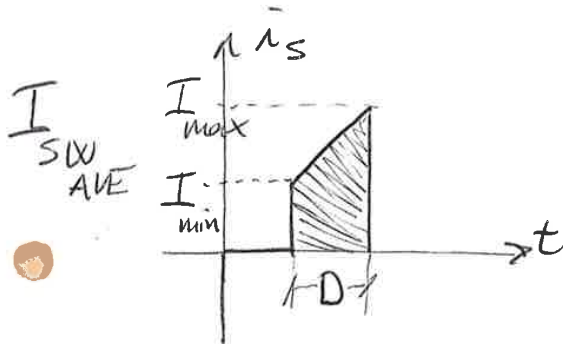
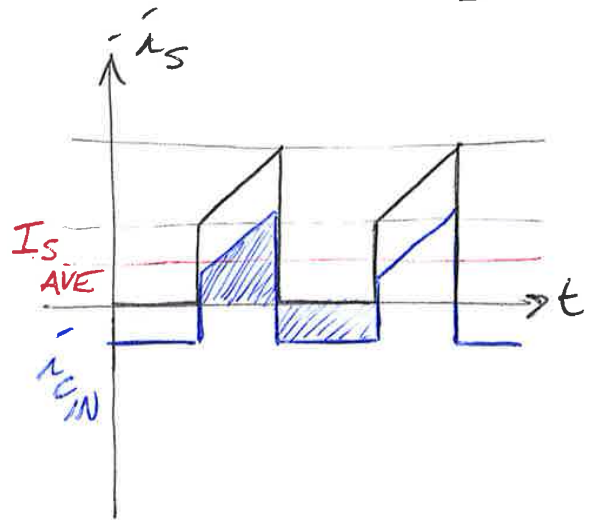
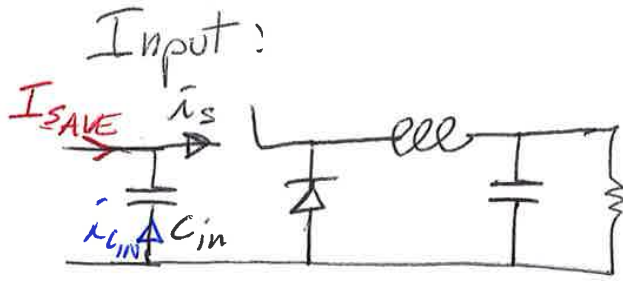
this is what makes the wire hot

Only one assumption made: all the AC component in the capacitor.

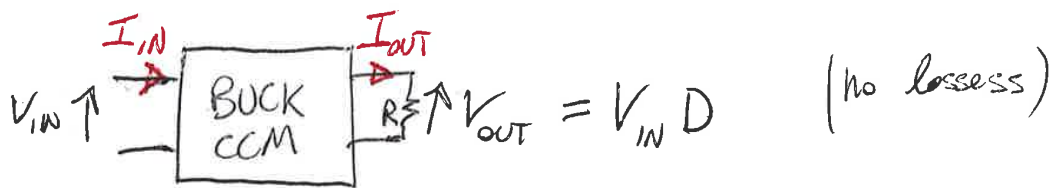
IN CASE OF CCM, $\frac{\Delta \hat{i}_L}{12}$ IS NEGLIGIBLE

Buck, ccm: $I_{L_{RMS}} \approx I_{L_{AVERAGE}}$

Maddaleno 18
3-3



$$I_{SW_{AVE}} = \frac{I_{min} + I_{max}}{2} D = I_o D = I_{IN}$$

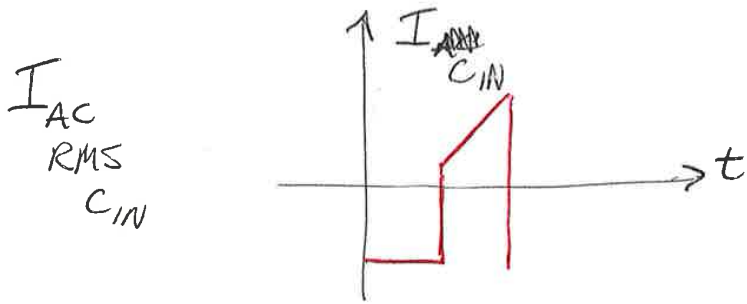


$$I_{IN} = I_o D \quad I_o = I_{IN} \frac{1}{D} \quad \text{this is a transformer equation}$$

$$V_o I_o = V_{IN} I_{IN}$$

$P_o = P_{IN}$ but this is not true because we have losses.

Any converter looks like a DC transformer

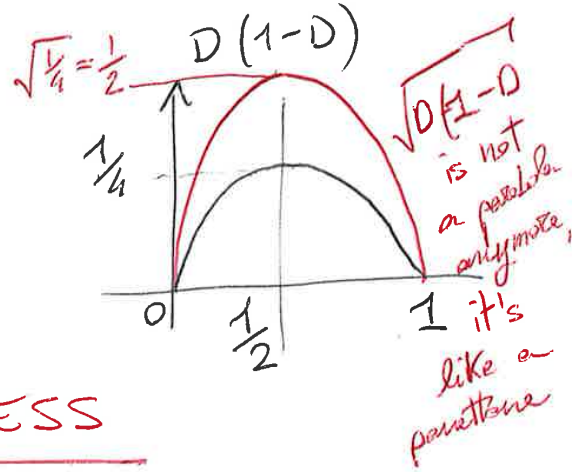


Machbano
3-3 (19)

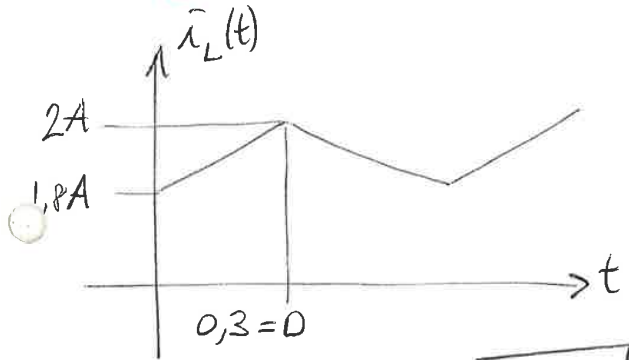
$$I_{AC\ RMS\ C_{IN}} = \sqrt{I_{TOT\ RMS}^2 - I_{DC}^2} = \sqrt{I_0^2 D - I_0^2 D^2} =$$

$$I_{TOT\ RMS} = I_{SW\ RMS} = I_0 \sqrt{D}$$

$$I_{AC\ RMS\ C_{IN}} = I_0 \sqrt{D - D^2}$$



VERY STRONG RMS STRESS



$$\Delta \hat{i}_L = 0,2A$$

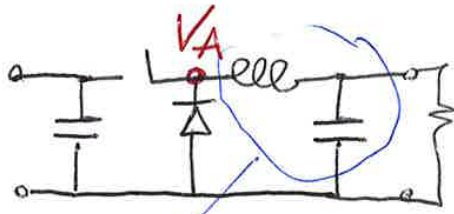
$$I_{C_{OUT}\ RMS} = \frac{\Delta \hat{i}_L}{\sqrt{12}} = 57,735\ mA$$

$$I_{C_{IN}\ RMS} \approx I_0 \sqrt{D - D^2} \approx \frac{1}{2} I_0 \approx 0,95A$$

TOTALLY IN DIFFERENT CONDITIONS

$$I_{C_{IN}\ RMS} = 1,9A \sqrt{0,3 \cdot 0,7} = 870,689\ mA$$

C_{IN} has to work at high frequencies and high currents



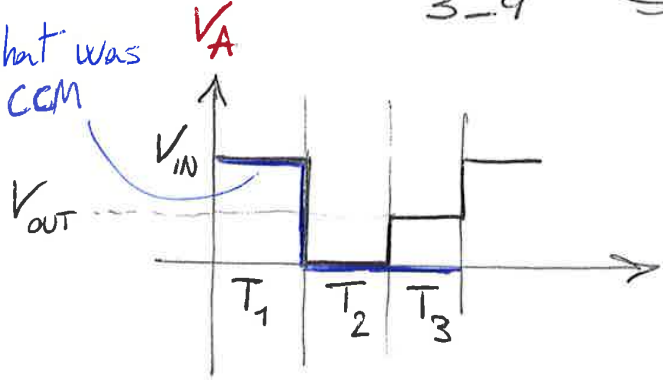
Machaleno

3-4

20

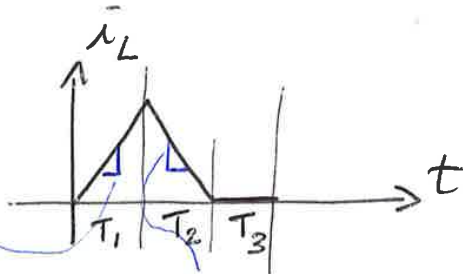
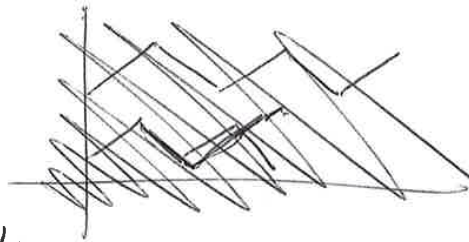
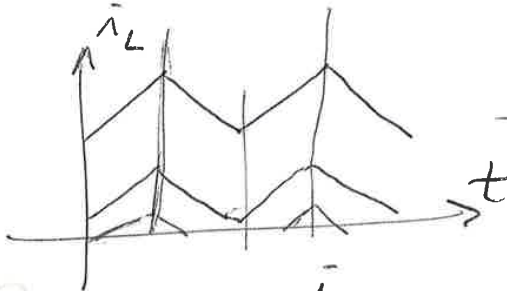
Second order low pass filter

what was CCM



The DCM waveform has an "extra" and so a larger average value, so the output voltage will be larger.

If the load is very light the ccm \hat{i}_L waveforms translates down until it reaches the boundary between CCM and DCM



$$\frac{V_{IN} - V_0}{L} T_1 + \left(\frac{-V_0}{L} T_2 \right) = 0$$

$$\frac{V_0}{V_{IN}} = \frac{T_1}{T_1 + T_2} \rightarrow \text{IS NOT } T_{SW}!$$

We need a second equation because we don't know T_2

DCM BUCK

Maddaleno

(21)

$$\frac{1}{R} = \frac{D^2}{2f_{sw}L} \cdot \alpha (\alpha - 1)$$

4-1

$$\frac{D^2 R}{2f_{sw}L} \cdot \alpha (\alpha - 1) - 1 = 0$$

$$\alpha = \frac{1}{M} = \frac{V_{IN}}{V_{OUT}}$$

$$\alpha^2 - \alpha - \frac{2f_{sw}L}{D^2 R} = 0$$

We are looking for $\alpha = \frac{V_{IN}}{V_{OUT}}$

Good I can choose f_{sw} and L

Good I can impose D

But... R ? BAD NEWS THIS IS NOT AN "IDEAL" VOLTAGE SOURCE

$$\alpha = \frac{1 \pm \sqrt{1 + \frac{8f_{sw}L}{D^2 R}}}{2} = \frac{V_{IN}}{V_{OUT}}$$

$$M_{\text{BUCK DCM}} = \frac{2}{1 + \sqrt{1 + \frac{8f_{sw}L}{D^2 R}}} = \frac{V_{OUT}}{V_{IN}} = \frac{1}{\alpha}$$

If D goes to 0, $V_{OUT} = 0$

V_{OUT} IS ALWAYS LESS THAN V_{IN} (the square root has 1+ something inside)

Maddaleno

4-1

22

"Possible" advantage of DCM

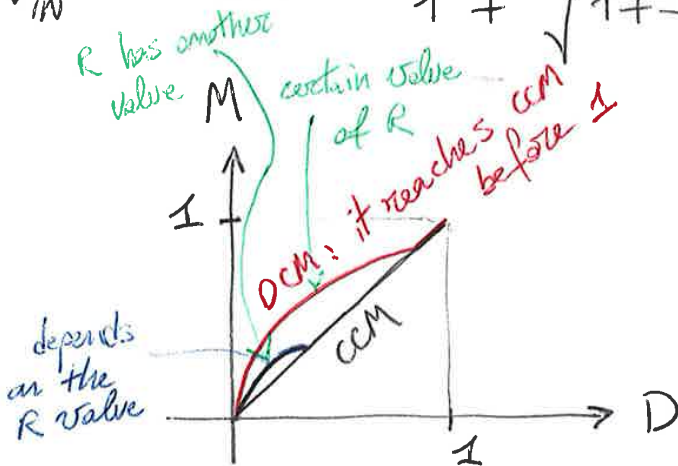
in CCM, $L_{CCM} > \frac{R_{MAX} (1 - D_{MIN})}{2 f_{SW}}$

in DCM, $L_{DCM} < \frac{R_{MIN} (1 - D_{MAX})}{2 f_{SW}}$

$L_{DCM} < L_{CCM}$ but a larger peak and rms current! It's not a real advantage.

There are cases when we are forced to work in DCM, for control reasons.

$$\frac{V_{OUT}}{V_{IN}} = M_{DCM} = \frac{1}{1 + \sqrt{1 + \frac{8 f_{SW} L}{D^2 R}}}$$



in CCM, $M = D$

Usually, $M_{CCM} \leq M_{DCM}$ but there is a value of D where they join. mancando il min allora fine della 4-1

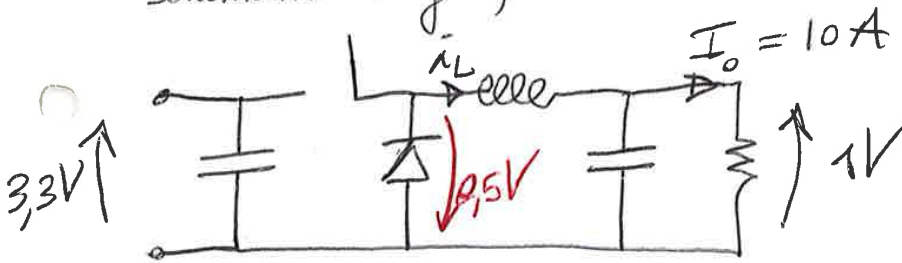
$L_{CRIT} = \frac{R(1-D)}{2 f_{SW}}$ value which separates CCM and DCM

Schematic changes, BUCK

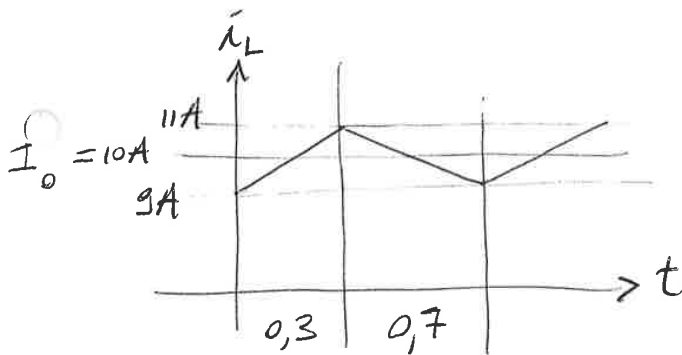
Maoblabano

23

4-2



$D = \frac{1V}{3,3V} = 0,3$... maybe not. the voltage across the diode starts to be important.



What's the voltage drop across the diode? 0,5 V with a Schottky. The diode dissipates $0,5V \cdot 10A = 5W$. It's just an approximation!

Across the transistor switch we will have something like 0,1 V, $\approx 1W$

The efficiency is low! Main loss on the diode.

And it's a good diode!

We need a different component. There are no diodes with a voltage drop of 0,1 V...

But 10A are not a lot

Maddaleno
4-2 (24)

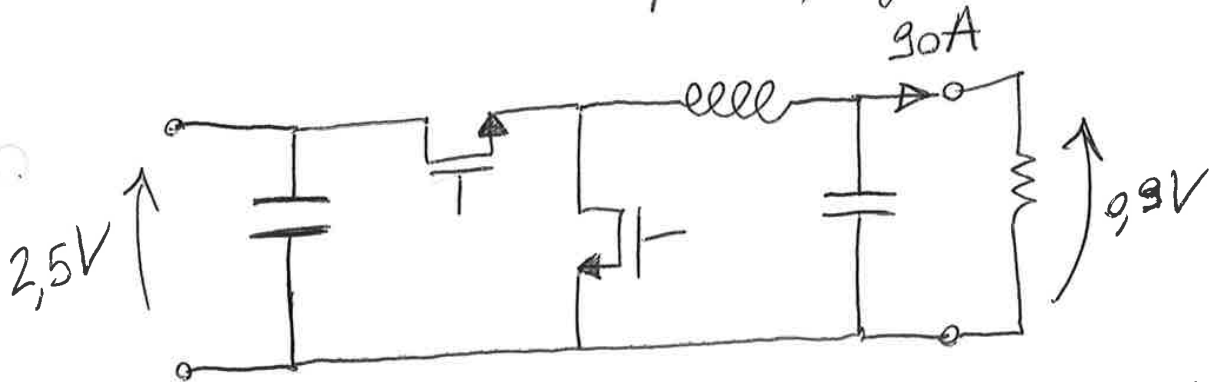
from 2,5V to 0,9V

$$D = \frac{0,9V}{2,5V} = 0,36$$

BUT $90A = I_{OUT}$



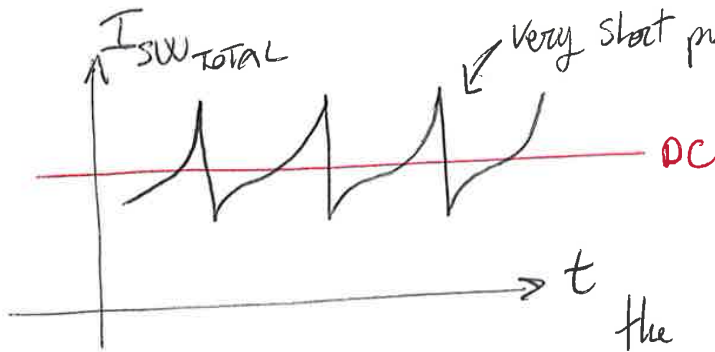
Not a good idea to put 2-3 mos transistor in parallel, they can oscillate and explode. It is possible, doing it.



OK we can find mos which can reach 90A but C_{IN} ? It has to resist 45A the inductor sustains 90A!

DIVIDE ET IMPERA

We make 3 converters, 30A each, in parallel
But there is another idea... it works well with fixed voltages



Maddaleno
4-2 (25)

Very small pulses,
the RMS current in the capacitor
 C_{IN} is very reduced

The output capacitors sees three triangular waveforms
shifted by $\frac{1}{3}$ in phase ($\frac{1}{3}$ of a cycle) and the
total ripple goes down a lot

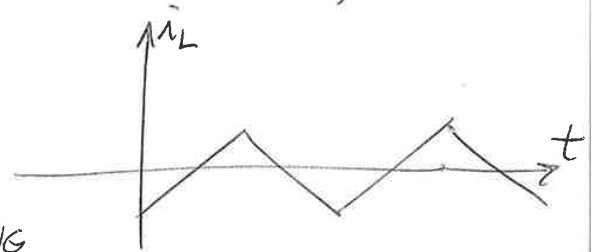
Different channels on the motherboards

MULTI PHASE : low voltage, very high current

SYNCHRONOUS BUCK with a 5-1

load that increases: it remains in CCM,
but \bar{i}_L becomes negative

if I_o is very low, in some
cases they switch off EVERYTHING



~~OFF~~ BURST MODE to don't waste power

Maddaleno
5-1 (26)

To stay in CCM,

$$f_{sw} = 200 \text{ kHz}$$

$$L > \frac{(1 - D_{MIN}) R_{MAX}}{2 f_{sw}}$$

$$D \approx \frac{V_o}{V_{in}} \text{ it is just an approximation}$$

because we are not considering losses.

$$D_{MIN} = \frac{V_o}{V_{in MAX}} = \frac{12V}{28V} \approx 0,43 \text{ including losses}$$

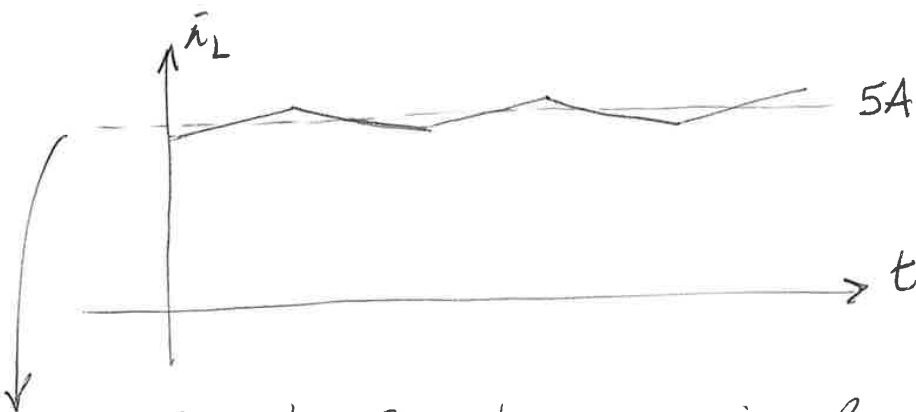
the duty cycle goes up.

$$R_{MAX} = \frac{V_o}{I_{o min}} = \frac{12V}{0,5A} = 24 \Omega$$

if the minimum current was 50 mA: the inductor goes up by a factor of 0.

With $I_{min} = 0A$, we jump to DCM

Reasonable interval?



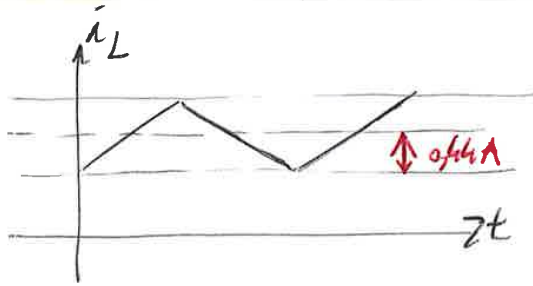
with a small ripple I need an expensive, large inductor because $I_{o min}$ can be VERY LOW

Good choice: 10-15% of ~~ripple~~ the output current as ripple. too large and the stress will be too high

Maddaleno

5-1

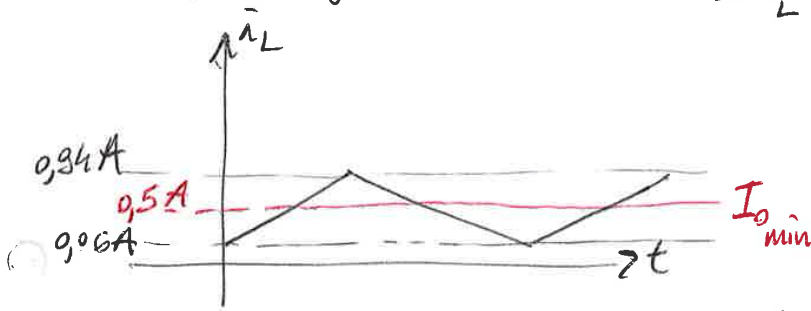
27



What happens when I_0 decreases to 0.5 A?

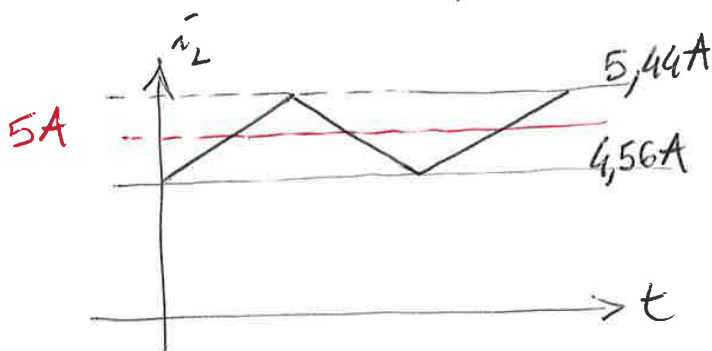
The ripple stays the same:

$$\Delta i_L = \frac{V_0 (1-D)}{L f_{sw}}$$



good, we stay in ccm
just a check

What's the maximum peak value?



max I_{out}
max ripple

The only component value that we guess from this point is the inductor.

From this point we think about stresses.

$$L = 39 \mu H$$

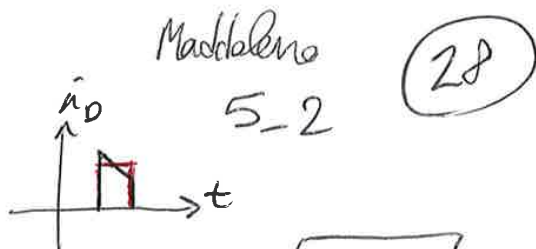
We think about $I_{peak} = I_{pk_L}$

because we don't want the inductor to saturate

$$I_{pk_L} \cong 5.5 A$$

We need $I_{L_{RMS}}$, important for resistive losses and power dissipation. $I_{L_{RMS}} = 5 A$

We don't need it, but let's calculate the rms using the flat-top approximation



$$I_{D_{RMS}} = I_0 \sqrt{1-D} = 5A \sqrt{1-0,43} = 3,77A$$

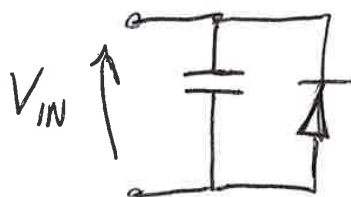
only for HIGH current diodes (1 MW converters)
the internal resistance becomes important

$$\bar{I}_D = 2,85A, \quad I_{PK_D} = 5,44A$$

What's the maximum voltage in reverse bias?

The ~~max~~ input voltage

$$V_{max} = 28V$$



but we take a 40V diode...

... in a car, truck, BIG overvoltages, 50-60V

$$\text{So: } \bar{I}_D = 2,85A, \quad I_{PK_D} = 5,44A$$

$$V_{Dr} = 40V$$

Now we can estimate the dissipated power

The voltage in conduction is almost constant

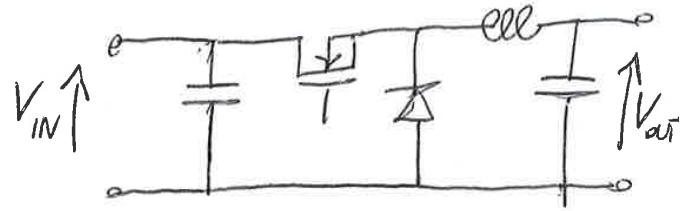
Across a Schottky, $\approx 0,5V$

$$P_D = 0,5V \cdot \bar{I}_D = 0,5V \cdot 2,85A \approx 1,5W$$

The average current through the switch is coming from the input, so I can find the input power

Macclabano (29)
5-2

If the V_{input} changes, $I_{AVE SW}$ changes too because the D changes.



Power dissipated on the Mos:

attention: we find the dissipated power on the diode with $I_{D AVE} = I_o (1 - D_{MIN})$

so using D_{MIN}

but for the Mos we think about I_{RMS} and D_{MAX}

$$I_{RMS MOS} = 3,82 A = I_o \sqrt{D_{MAX}} \approx 3,9 A$$

maximum voltage across the Mos: when it is open

$$V_{DS max} = V_{IN} - (-V_D) \approx 29 V$$

we need to ~~pick~~ pick a higher value.
the capacitor C_{IN} acts a bit as a protection against spikes. A bit.

Maddaleno (30)

We could choose a VERY LOW small $r_{DS(on)}$ transistor. But we have disadvantages

- 1) Big package, which is more expensive (we need more Si area)
 - 2) The bigger Si area means a bigger capacitance to charge and discharge.
- We need a strong driver.

$$r_{DS(on)} = \frac{V_{DS(on)}}{I_{D(MAX)}} = \frac{0,2V}{5,4A} = \boxed{37 \text{ m}\Omega}$$

HOT,
NOT
COLD AS
DECLARED

if not limited by package, it surely can sustain large currents.

A car with 60 hp = 44,74 kW

$r_{DS(on)}$ | @ 25 °C PAY ATTENTION, IT WILL BE AT 80 °C NOT 25 °C

We will need 37 mΩ as an HOT resistance!

~~The~~ The hot resistance can be 1,7 X larger, it's a function of temperature

INPUT CAPACITOR

Maddaleno (31)
5-3

Working voltage : $> V_{IN}$

The minimum that we find is

Charles 1870
Remond

R from a
French captain of the army

R5 : 10, 16, 25, 40, 63

five values in
a decade

We choose 40V

If the temperature goes up, the working voltage goes down

ALWAYS ~~REMEMBER~~ REMEMBER THE RMS CURRENT

$$I_{C_{IN} \text{ RMS}} = I_0 \sqrt{D(1-D)} \quad \text{approximation}$$

if it reaches 0,5 = D, use the maximum

when $D = 0,5$,

$$I_{C_{IN} \text{ RMS}} \approx \frac{I_0}{2} = 2,5 \text{ A real high stress}$$

BAD news: in power electronics capacitance is not important.

The larger is C, usually the smaller is the impedance.

The input capacitor keeps the peaks inside

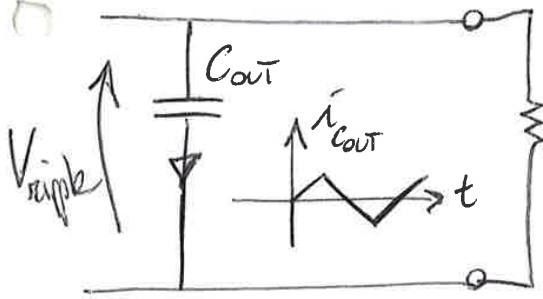
WE NEED the EMI FILTER

Ripple voltage

Maddaleno

5-3

32



What's the voltage across the capacitor?

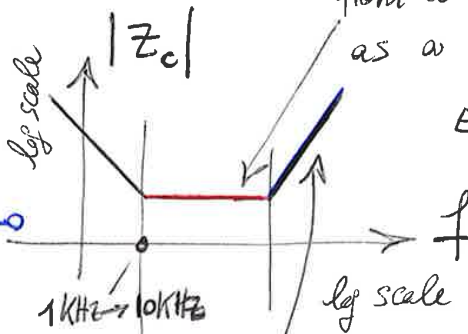
We could use $\Delta i_L \frac{1}{SC} = V$

but here we can avoid Laplace transforms.

$\frac{1}{SC}$: this is an ideal capacitor. It does not exist.

Two kind of parasitics:

Electrolytic:



from a certain frequency it acts as a resistance,

ESR = Equivalent Series Resistance

from another frequency it acts as an inductor

We can get 500 Hz! Bad!

10 kHz is optimistic

Tantalum capacitors: they have small working voltages but they act as capacitors up to 10 kHz \rightarrow 50 kHz

OSCON: Brand name, up to 20 kHz

The harmonics at 200 kHz see the ESR!

Maddaleno

5-4

33

$$f_{z_{ESR}} = \frac{1}{2\pi C \cdot ESR}$$

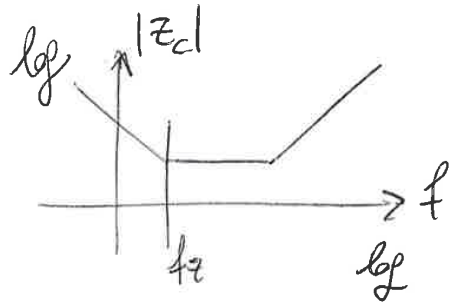
We need something like

$$C = \frac{1}{2\pi f_z ESR}$$

↑ 110 mΩ

We guess f_z , from 1 kHz to 10 kHz

We can estimate that

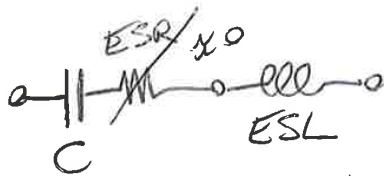


$$C = \frac{1}{2\pi \cdot 110 \text{ m}\Omega \cdot 3 \text{ kHz}} = 482 \mu\text{F}$$

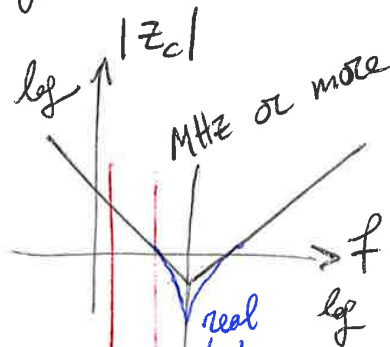
We need this value to design the control

CERAMIC AND FILM CAPACITOR

They have an ESR, but it's so small that it goes to 0.



but they have an ESL



We usually stay where it's a capacitor

(STEP UP) BOOST $\frac{V_o}{V_{in}} \geq 1$

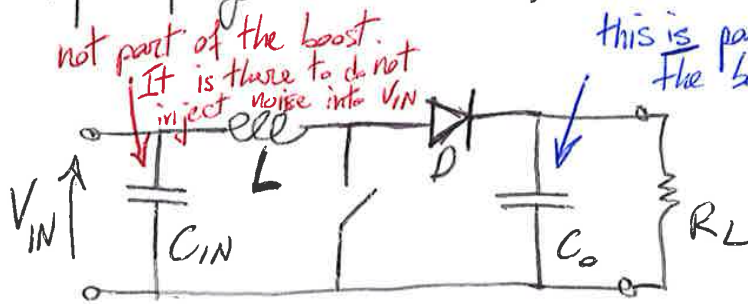
Maddaleno
~~XXXX~~
 B-1
 (34)

Controlling a boost converter is not trivial.

IN MANY CASES, ESPECIALLY FOR HIGH POWER, we use other topologies.

They have very specific field of application.

~~MP3~~ Mp3 players with 1.5V ~~and~~ battery

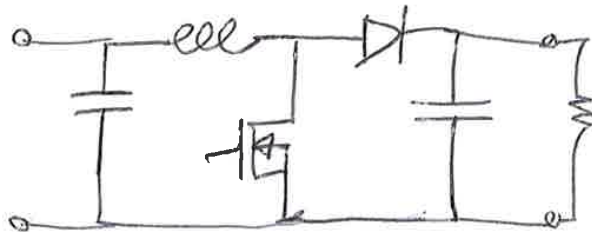


not part of the boost. It is there to do not inject noise into V_IN

this is part of the boost. Not like the buck, where it was there to behave like a filter

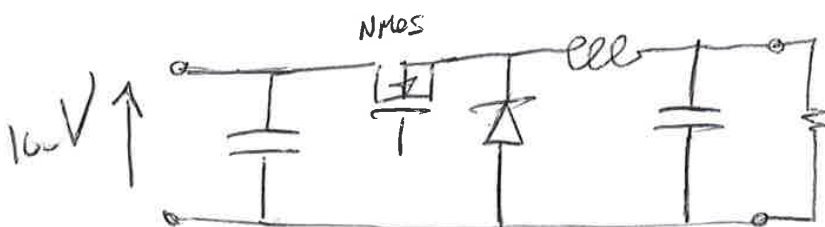
The current through L is very smooth.

In a buck, a pulsed overvoltage of V_{in} could kill the switch or the diode. Here L protects the switches of circuit.



Low side switch, while in the buck it was an high side switch, more complicated and expensive to drive.

BUCK:

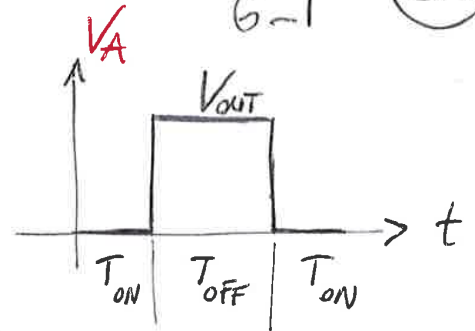
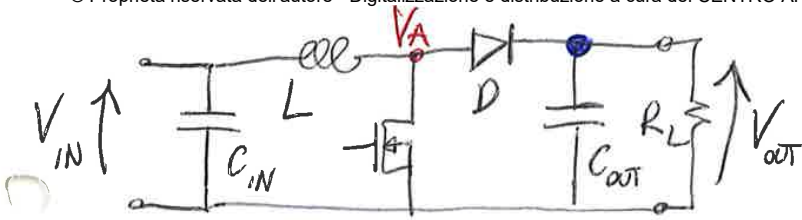


here we need to drive the mos ~~gate~~ ~~gate~~ putting the gate ~~at~~ at $\approx 110V$ from 0V, and 110V is more positive than the input voltage

Maddaleno

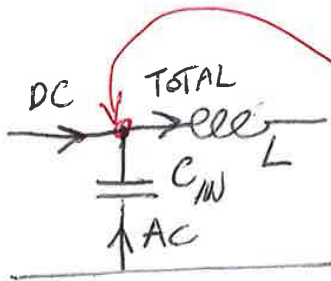
G-1

35



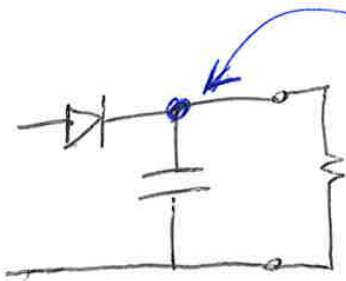
The RMS current through the inductor is more or less equal to the average current through the inductor itself, if we are in CCM.

$$I_L \underset{\text{RMS}}{\approx} I_{L \text{ AVE}} \approx I_{L \text{ DC}}$$

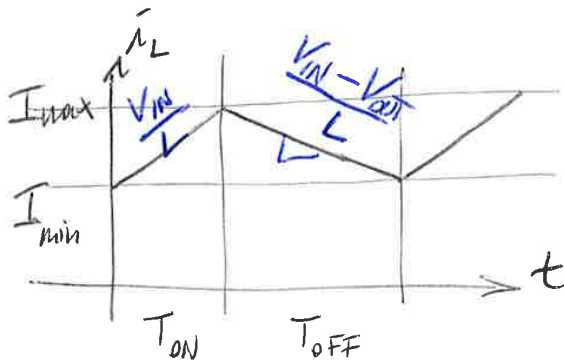


here there is just a ripple, it is not pulsating. We cannot use quadratic KCL because we have ~~ripples~~ a very large cancellation error.

That's because the currents are very similar



here instead there is a pulsating current, so we can use quadratic KCL



We can find $\frac{V_{OUT}}{V_{IN}} = M$ in CCM

CCM, ideal components:

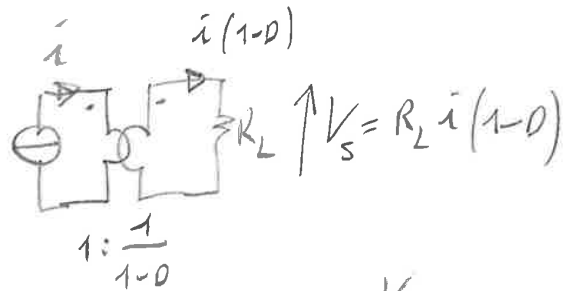
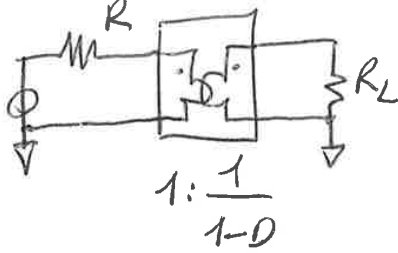
$$\frac{V_{IN}}{L} T_{ON} + \frac{V_{IN} - V_O}{L} T_{OFF} = 0$$

we can't eliminate L! without an inductor closing the MOS we short the input!

Limite all'M del boost

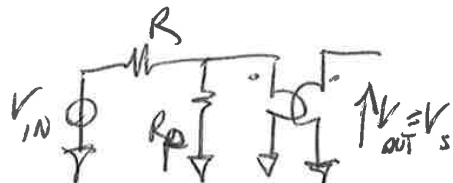
$$\left. \frac{V_0}{V_{IN}} \right|_{\text{boost}} = M = \frac{1}{1-D} \quad \text{INSERTO}$$

Ma anche solo considerando la R parassita dell'induttore...



$$V_p = V_S (1-D) = R_L i (1-D)^2$$

$$R_p = \frac{V_p}{i} = R_L (1-D)^2$$



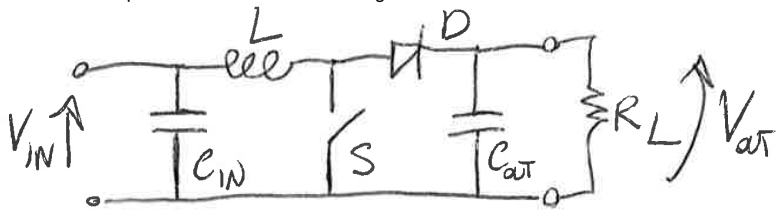
$$V_p = V_{IN} \frac{R_p}{R + R_p} = V_{IN} \frac{R_L (1-D)^2}{R + R_L (1-D)^2}$$

$$V_S = V_p \frac{1}{1-D} = V_{IN} R_L \frac{(1-D)}{R + R_L (1-D)^2} = V_{out}$$

Quindi ottergo

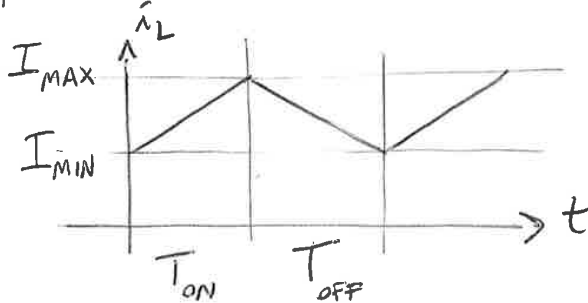
$$\frac{V_0}{V_{IN}} = M = \frac{R_L (1-D)}{R + R_L (1-D)^2} \quad \text{anzichè} \quad \frac{V_0}{V_I} = \frac{1}{1-D}$$

che per $R_L \rightarrow \infty$ tende a $\frac{1}{1-D}$ quindi se la corrente di uscita è molto bassa...



Flash in cameras: we can't go up from 3V to 300V with a boost.

Defibrillator: ~6 KV, the current is 20 A



To guarantee CCM, $I_{MIN} > 0$

Unfortunately, we have to design them in DCM to control them.
 with 100% efficiency

$$\frac{I_{MAX} + I_{MIN}}{2} = I_{AVE_L} = I_{IN} \stackrel{\text{with 100\% efficiency}}{=} \frac{I_o}{1-D} = \frac{V_o}{R(1-D)}$$

bound between average current and output current

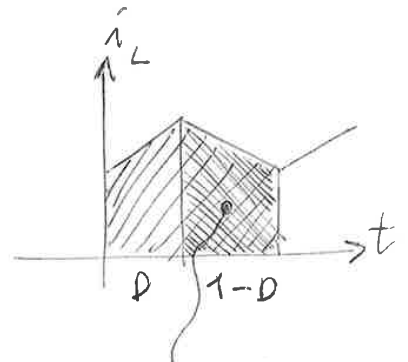
$$\textcircled{I} \quad I_{IN} = \overline{I_{SW}} + \overline{I_D} = \overline{I_{SW}} + \frac{V_o}{R}$$

$$\textcircled{II} \quad I_{MAX} - I_{MIN} = \Delta \hat{i}_L = \frac{V_{IN}}{L} \frac{D}{f_{SW}} =$$

$$= \Delta \hat{i}_L = \frac{D}{L f_{SW}} (1-D) V_{OUT}$$

Now we have two equations, we can add them

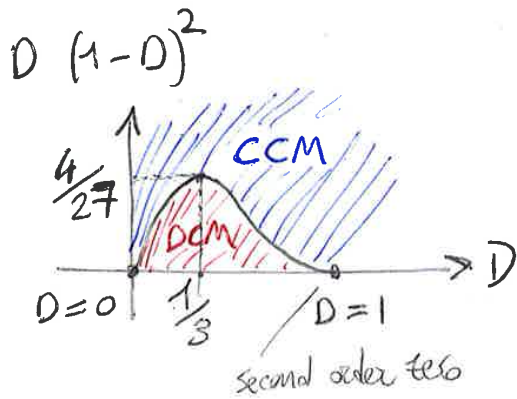
$$I_{MAX} = \frac{V_o}{R(1-D)} + \frac{D(1-D)V_o}{2 f_{SW} L}$$



the total area is proportional to $\frac{I_o}{1-D}$

To stay in CCM!

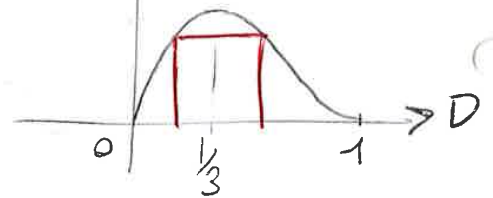
$$L > \frac{D(1-D)^2 R_{MAX}}{2f_{sw}}$$



$$\frac{\partial}{\partial D} [D(1-D)^2] = (1-D)^2 + 2D(1-D)(-1)$$

$$3D^2 - 4D + 1 = 0 \quad D_{1,2} = \frac{1 \pm \sqrt{1-3}}{3} = \frac{1 \pm \sqrt{-2}}{3}$$

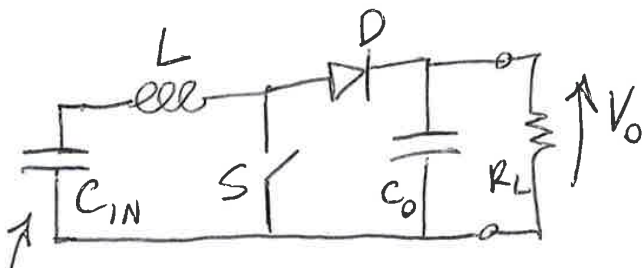
$$L = \frac{R D(1-D)^2}{2f_{sw}}$$



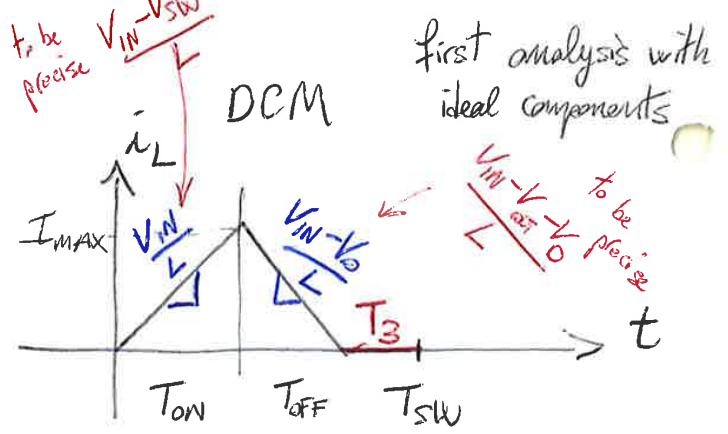
If the duty cycle moves :

~~CCM~~ ~~DCM~~

DCM boost



it keeps the EMI noise inside the circuit



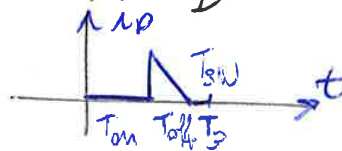
T_3, T_{IDLE} , during T_3 both SW and DIODE are open

~~$$\frac{V_{IN}}{L} T_1 + \frac{V_{IN} - V_O}{L} T_2 = 0$$~~

$$V_{IN} (T_1 + T_2) = V_O T_2 \quad M = \frac{V_O}{V_{IN}} = \frac{T_1 + T_2}{T_2} = \frac{T_1}{T_2} + 1$$

we need another equation because we don't know T_2 .

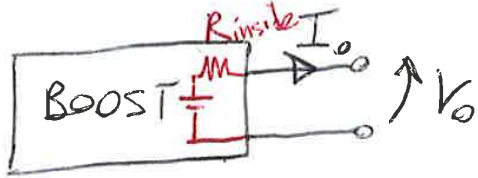
Same of the buck converter, bound with $I_O = \frac{V_O}{R_L}$ the DC component of I_D is equal to $\overline{I_D}$.



$$\frac{V_O}{R_L} = \text{average current through the diode} = \frac{1}{2} T_{OFF} \frac{V_{IN}}{L} \cdot \frac{1}{T_{SW}}$$

area triangle = $\frac{1}{2} \cdot \text{base} \cdot \text{height}$

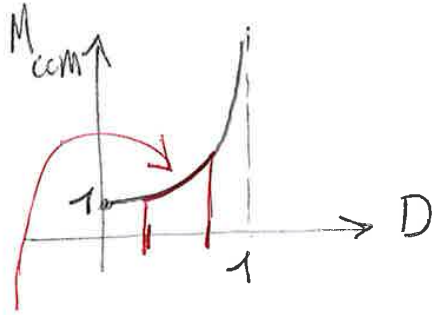
$$\frac{M}{R} = \frac{1}{2} \frac{D}{L} T_2 \quad \text{from } M = 1 + \frac{T_1}{T_2}, \quad T_2 = \frac{T_1}{M-1}$$



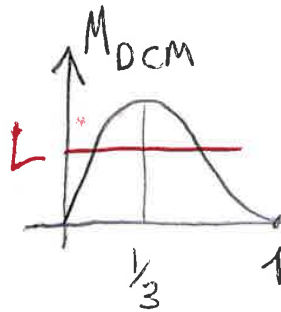
R_{inside} is a load but I'm using the source rule, so R_{inside} is negative

$$\frac{\partial V_o}{\partial D} = \text{GAIN}(V_{in}, R, D, \dots)$$

life is bad



$$M_{ccm} = \frac{1}{1-D}$$



choosing this L I can move around ccm and DCM

IN DCM,

$$M = \frac{1 + \sqrt{1 + \frac{2RD^2}{f_{sw}L}}}{2}$$

this is much larger than 1

so it remains, neglecting the one, constant slope

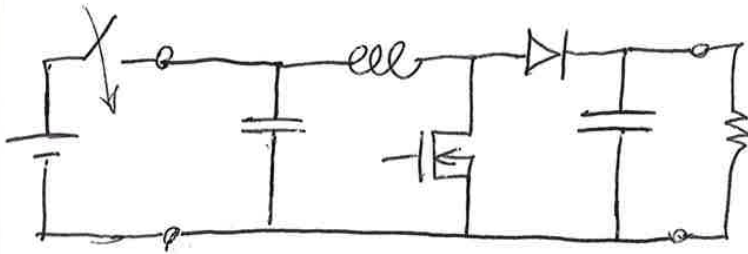
$$M \approx \frac{1}{2} + \frac{1}{2} D \sqrt{\frac{2R}{f_{sw}L}}$$

So

$$M = \frac{1 + \sqrt{1 + \frac{2RD^2}{f_{sw}L}}}{2}$$

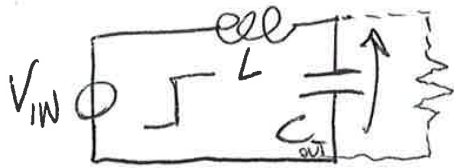
if $R \rightarrow \infty$, $M \rightarrow \infty$ if we disconnect the load the output voltage start to increase forever, KABOM.

Some boards have a protection

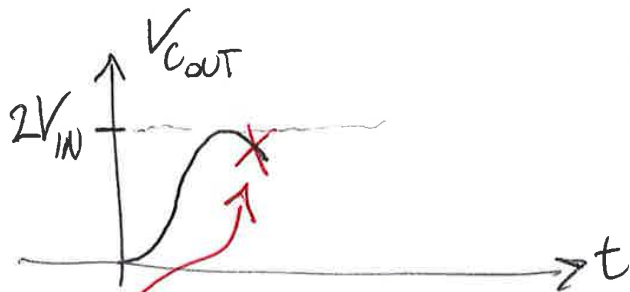


POWER ON

Inrush current in C_{IN} , but ok...

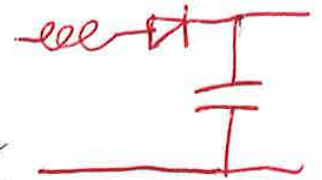


resonant circuit
what happens?



how big are the oscillation of the resonant circuit?

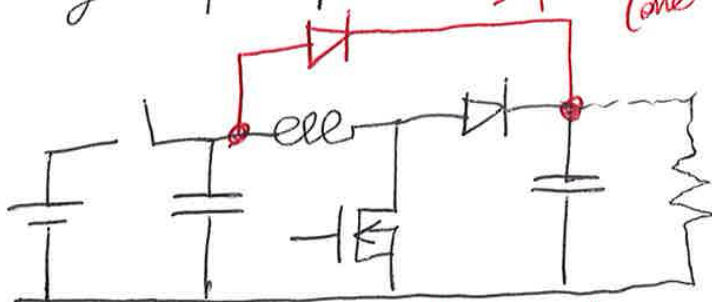
but in the real circuit we have a diode, the capacitor can't discharge back



If $V_{IN} = 330V$, and we want $V_{out} = 330V$,
THIS IS REALLY BAD, C_{OUT} WILL NOT
STAND 660V DUE TO THE RESONANCE

How can we damp resonances? With resistors, but they dissipate power

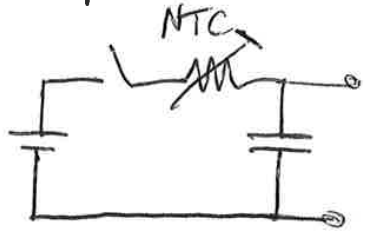
Simple solution (one of them)



the current goes through the diode, no current in the resonant circuit.

we charge the output capacitor up to V_{IN} , that's fine.
OK for low power circuits.

We can put an NTC Negative Temperature Resistor 7-2

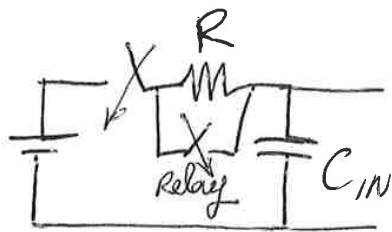


When it's hot the resistance greatly goes down (maybe from 20Ω to $0,1\Omega$)

Hot is something like 150°C

Used ~~years~~ years ago in ~~laptops~~ desktops ... but if we switch it off and ~~off~~ on the NTC could still be hot. So kaboom.

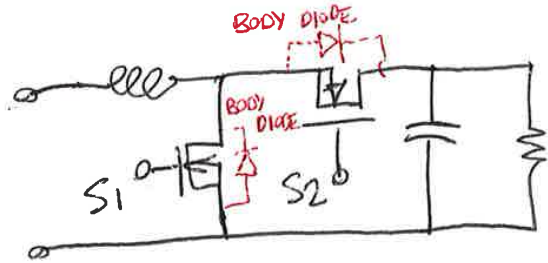
Another solution for large powers: _____



a timer circuit closes the relay some times after the ignition.

But the mechanical relay costs.

At home: 60 A limit, generally, but for a short time we can reach 100 A.

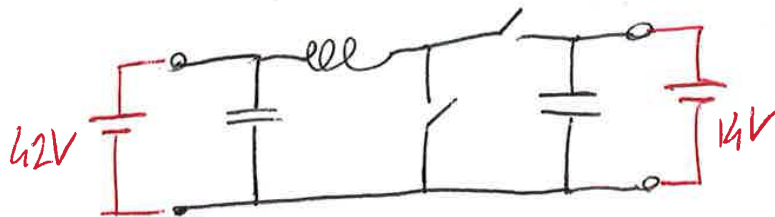


$$S1 = \overline{S2}$$

Not a great advantage as with low-voltage bucks, because

SYNCHRONOUS BOOST

We have generally an high output.



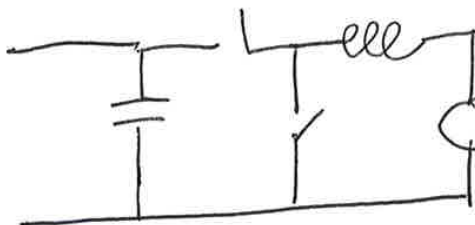
read from left to right:

SYNCHRONOUS BOOST

read from right to left: SYNCHRONOUS BUCK

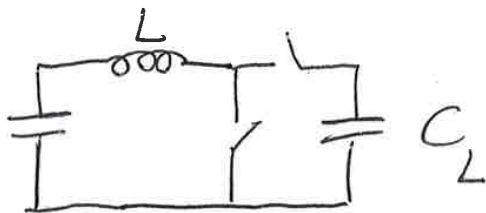
We can move energy between batteries

When we need to recover energy



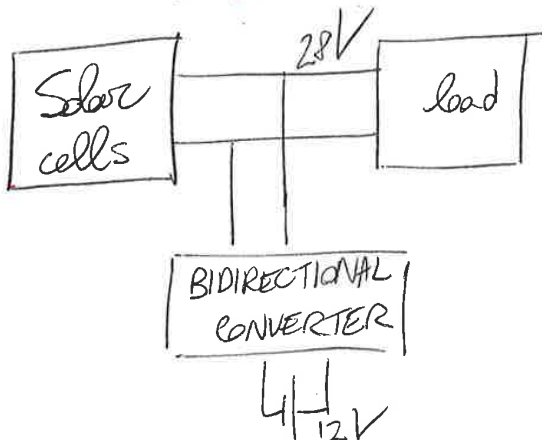
DC MOTOR

A DC motor could be used as a generator

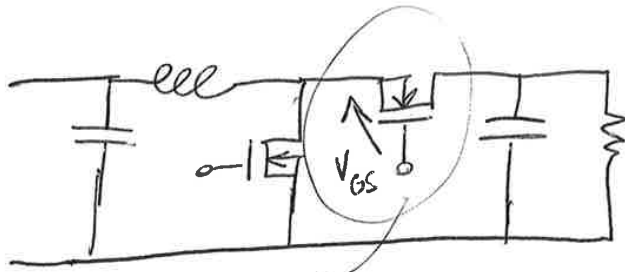


Satellites

to much to boost from 12V to 200V, we use other methods

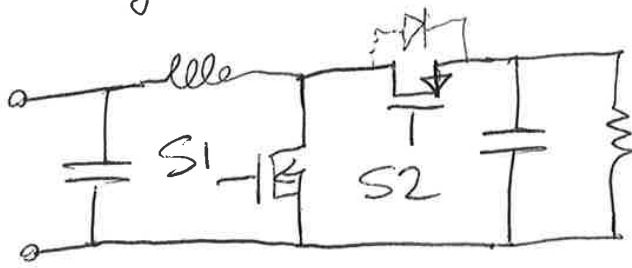


less mass using a bidirectional converter.



High side driver / Transformer

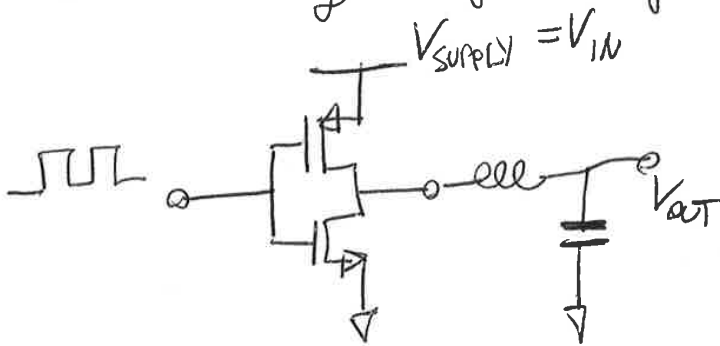
Using a PMOS instead:



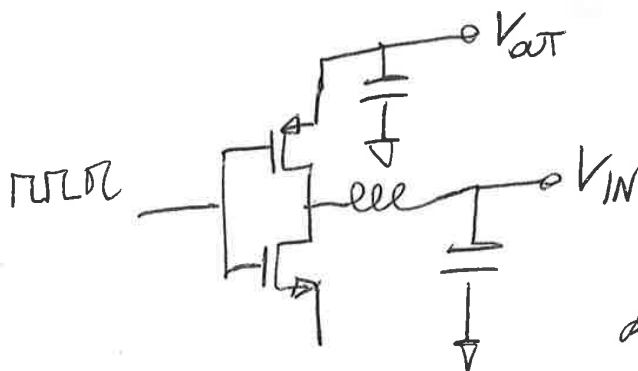
Same body diagram orientation high side, but to switch it on I need to put the gate down respect to the source

Sometimes, If lucky, we could drive the gates together.

BUT connecting the gates together is not a good idea:



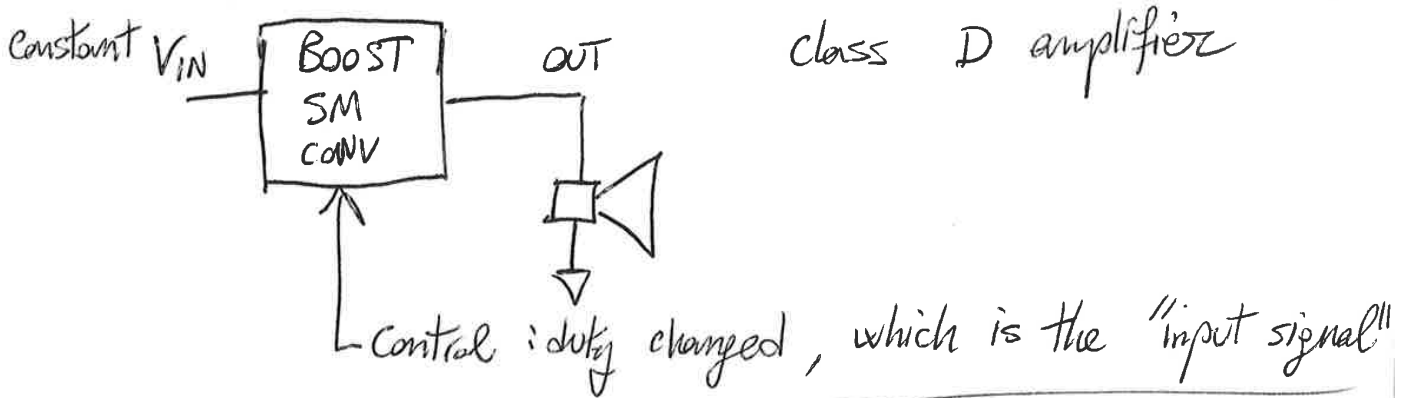
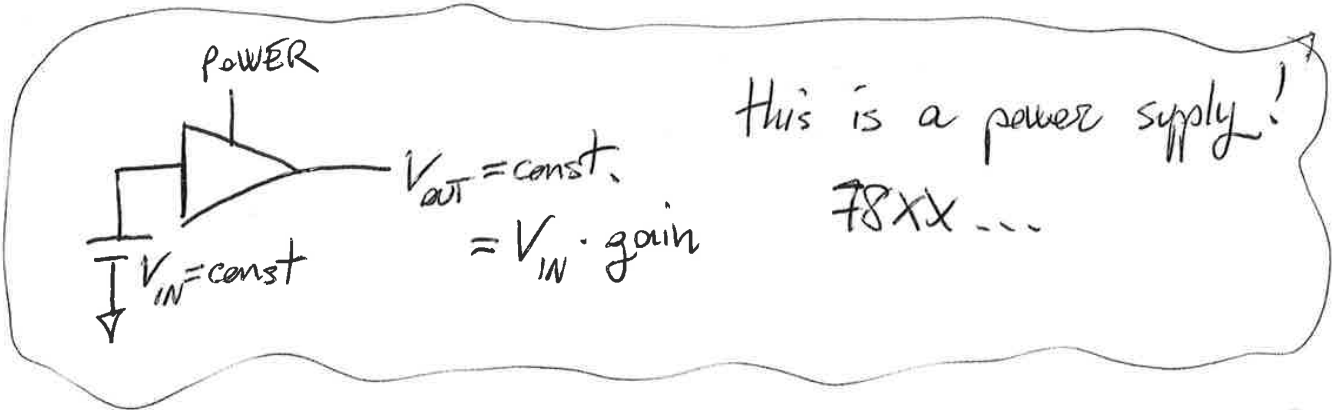
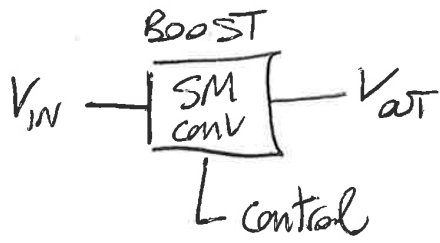
BUCK

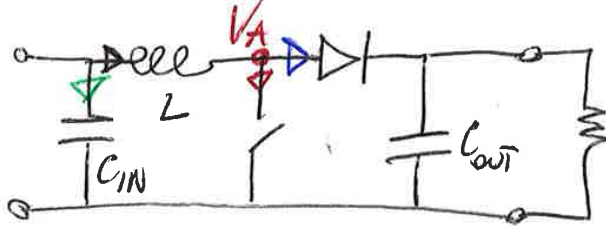


BOOST

During the switch phase for a period of time they both (CROSS CONDUCTION) SHOOT THROUGH which is loss of power

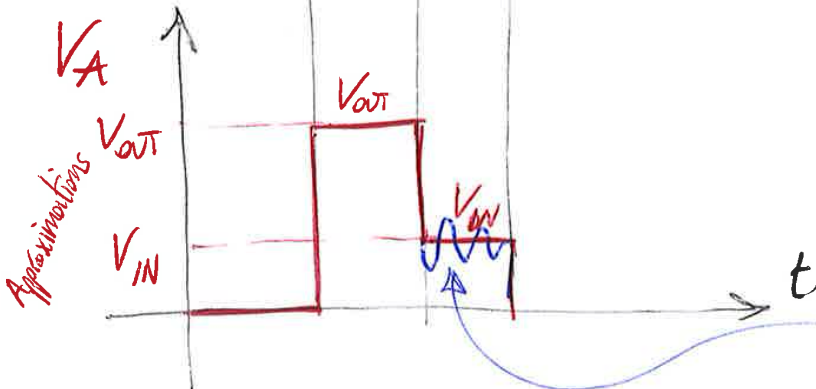
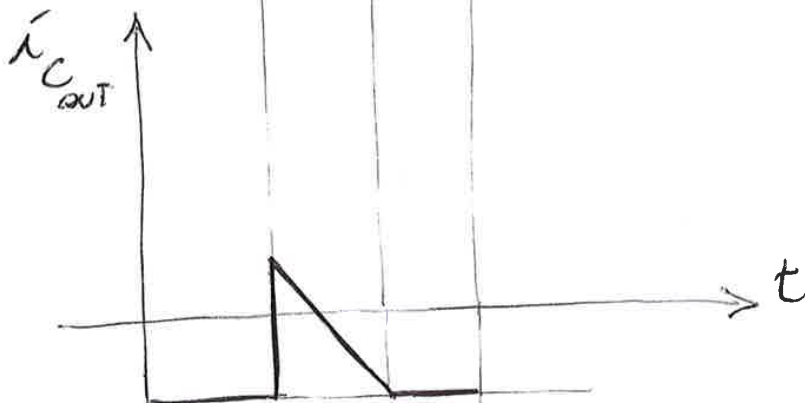
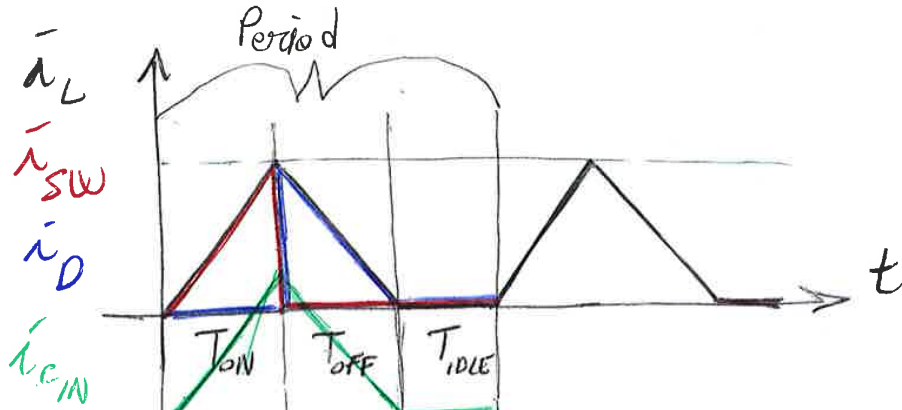
So we still need some delay





DCM

What could change:
 f_{sw} , L , load, waveforms



During T_{IDLE} both SW and diode closed, so we have $V_A = V_{IN}$

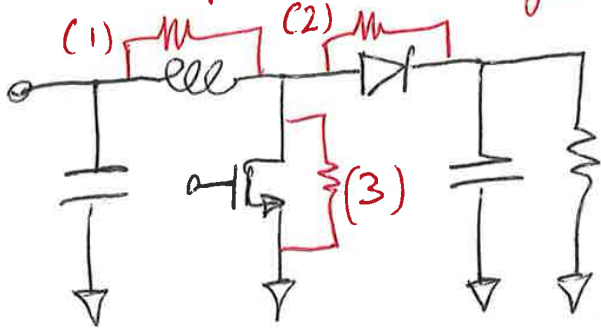
↑ Supposed to be like this, BOOST DCM

but we have RINGING

bad part: it generates electromagnetic noise, problems!
 we want to DAMP IT

Then we will proceed.

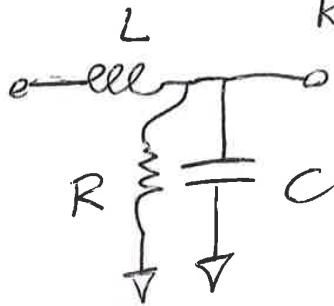
We will put it, indifferently, in these positions:



(only one of them)

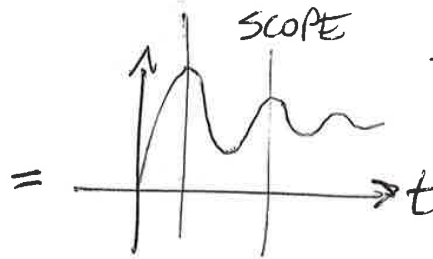
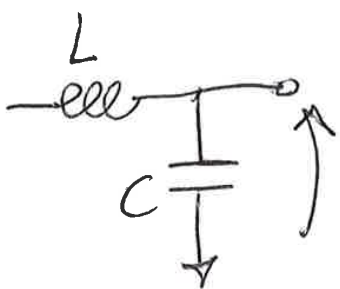


Resonant circuits



$$f_{RES} = \frac{1}{2\pi\sqrt{LC}}$$

Characteristic impedance $Z_0 = \sqrt{\frac{L}{C}}$

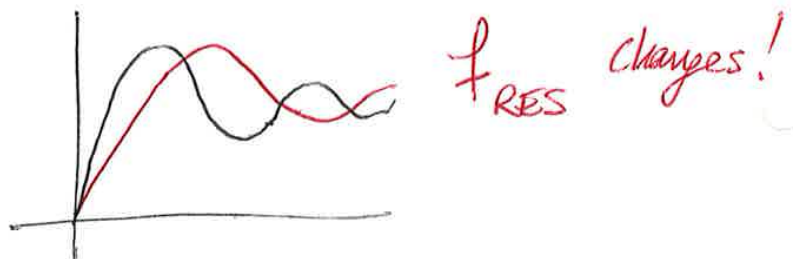
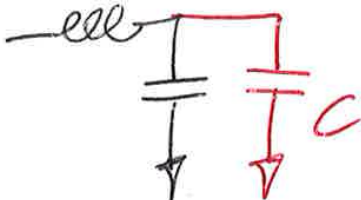


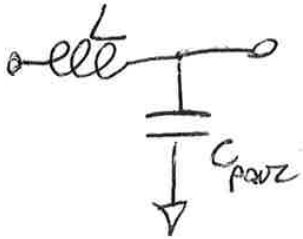
$$f_{MEASURED} = \frac{1}{2\pi\sqrt{LC}}$$

OK from the scope we obtain $f_{MEASURED}$, but we miss L AND C. We need a second equation, obtained like this:

We physically put a known hardware capacitor

A small one! when the sw/probes closes it has to discharge it!





Now we know f_{MEAS} and C_{par} and so

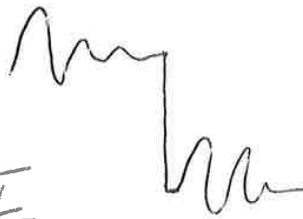
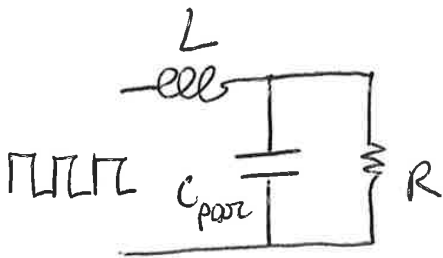
$$f_{MEAS} = \frac{1}{2\pi \sqrt{LC_{par}}}$$

We can derive L.

$$L = \left[\frac{1}{(2\pi f_{MEAS})^2 C_{par}} \right]$$

DO π !
to check any mistake

$$Z_0 = \sqrt{\frac{L}{C_{par}}}$$



$$Q = \frac{Z_0}{R} \quad \text{or} \quad Q = \frac{R}{Z_0}$$

What is the series one and what the parallel one?

What happens if $R \rightarrow \infty$? Circuit not damped and $Q \rightarrow \infty$

So the parallel term is $Q = \frac{R}{Z_0}$

