



Corso Luigi Einaudi, 55 - Torino

Appunti universitari

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Prof. Misul

Il presente lavoro nasce dall'impegno dell'autore ed è distribuito in accordo con il Centro Appunti.

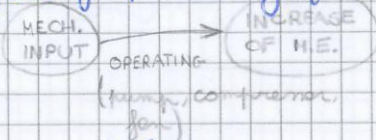
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**ATTENZIONE: QUESTI APPUNTI SONO FATTI DA STUDENTIE NON SONO STATI VISIONATI DAL DOCENTE.
IL NOME DEL PROFESSORE, SERVE SOLO PER IDENTIFICARE IL CORSO.**

FLUID MACHINE

↳ system or a machine with a fluid working in it

- **MOTOR**: displays work on a shaft (turbine)
- **OPERATING**: it absorbs work from the outside to transfer to the fluid (a fan is an example of operating fluid machine and a compressor)



What are the energy sources?

- FOSSIL FUELS: energy is in chemical bonds;
- SOLAR ENERGY: available and clean ↑;
not enough ↓;
- WATER: potential energy of water;
- WINDS: see solar energy;
- TIDES: not easy to be controlled;

The main goal is to increase the overall efficiency of the machine.

Fluid machines can be divided into:

- **THERMAL**:

we consider the thermal issues connected with the fluid ($p \neq \text{const.}$)

- **HYDRAULIC**:

deals with an incompressible fluid ($p = \text{const.}$) and thermal phenomena can be neglected

- **VOLUMETRIC**:

machine where all the interactions within it are connected to a change of volume (internal combustion engine)

- **TURBO**:

fluid flows continuously into the machine without significant change in volume (the flow has not to be steady but just continuous).

$$e_{\text{mech}} = \frac{p}{\rho} + \frac{v^2}{2} + gz$$

The choice of the system to study is always up to us but there is always a more or less convenient choice of the system.

Properties

- **INTERNAL STATE**: T and p define in a unique way our system (= HOMOGENEOUS SYSTEM);

- **EXTERNAL STATE**: position in space of my system and velocity.
BARICENTER

The HOMOGENEITY of the system is fundamental to allow us to write:

$$V = m \cdot v;$$

otherwise we should write:

$$V = \int_{m_c} v dm, \quad \text{remark that } v = \frac{1}{\rho}$$

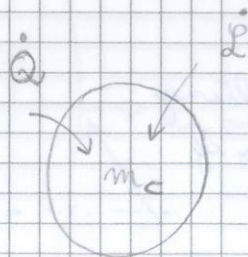
Also:

L, Q : extensive values

L, Q : intensive values

1st PRINCIPLE OF THERMODYNAMICS for CLOSED SYSTEMS

If we have a system that goes under an evolution from an initial state (i) at time t to the final (f) at time $t+dt$ we can say:



$$\delta Q + \delta L = dE = E_f - E_i$$

$$Q + L = \Delta E = E_f - E_i$$

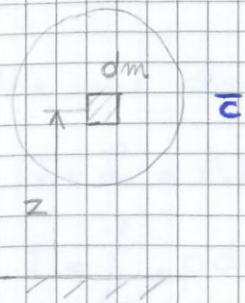
with

$$\delta Q = \dot{Q} dt, \quad \delta L = \dot{L} dt$$

RMK the difference!

When the process executed by the closed system in a cycle:

$$\oint \delta Q + \oint \delta L = 0$$



$$E_g = \int_{m_c} g z dm = g z m_c$$

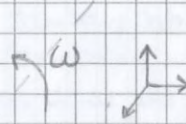
$$E_k = \int_{m_c} \frac{c^2}{2} dm$$

The energy storage from centrifugal force is:

$$E_\omega = \int_{m_c} -\frac{u^2}{2} dm = \int_{m_c} -\frac{\omega^2 r^2}{2} dm$$

tangential velocity

parte dell'energia viene spesa per tenere compatto il sistema



The 1st law of thermodynamics becomes:

$$Q + L = \Delta E =$$

$$= \Delta U + \Delta E_g + \Delta E_k + \Delta E_\omega$$

$$Q + L = \Delta U + \Delta E_g + \Delta E_k + \Delta E_\omega$$

INTEGRAL FORM

$$\delta Q + \delta L = dU + dE_g + dE_k + dE_\omega$$

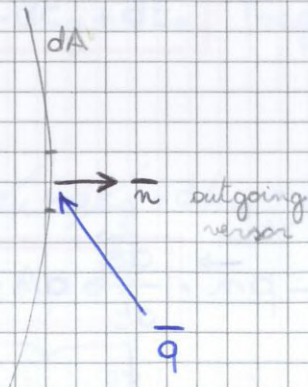
DIFFERENTIAL FORM

WORK AND HEAT

Work and heat are exchanged at the boundary.

$$\delta Q = \dot{Q} dt$$

\bar{q} : heat per unit time per unit of surface



$$\dot{Q} = \int_A -\bar{q} \cdot \bar{n} dA$$

$$\delta L = \dot{L} dt$$



We were about 1st law of thermodynamics:

$$Q + \mathcal{L} = \Delta E = \Delta U^* + \Delta E_k + \Delta E_g + \Delta E_w$$

$$\mathcal{L} = \int_{V} -p dV \Rightarrow \delta \mathcal{L} = -p dV$$

what is - sign for?

$$\mathcal{L} > 0$$



- if $dV < 0$ (compression) $\Rightarrow \mathcal{L} > 0$
- if $dV > 0$ (expansion) $\Rightarrow \mathcal{L} < 0$

Actually the complete expression for work is:

$$2) \quad d\mathcal{L} = -p dV + dE_k + dE_g + d\mathcal{L}_w$$

↓
pé la pression
externe de
système chius

↓
due to viscous
losses
($d\mathcal{L}_w > 0$)

δQ and $\delta \mathcal{L}$ will be
converted into dQ and
 $d\mathcal{L}$

$$1) \quad dQ + d\mathcal{L} = dU + dE_g + dE_k \quad (\text{neglecting } dE_w)$$

↳:

$$dQ - p dV + dE_k + dE_g + d\mathcal{L}_w = dU + dE_g + dE_k$$

$$dQ + d\mathcal{L}_w = dU + p dV$$

interactions with the
surrounding properties of
the system

we define:

$$h = U + pV$$

$$dh = dU + p dV + V dp$$

↳:

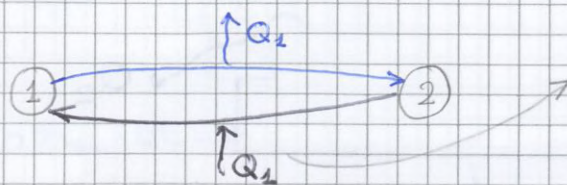
$$dQ + d\mathcal{L}_w = dh - V dp$$

The 2nd principle can be also expressed in terms of Clausius inequality:

for a CYCLE (initial point = final point) we have:

$$\oint \frac{dQ}{T} \leq 0$$

• equality applies if the cycle is reversible:



if a opposite value of heat and/or work is introduced the system goes back to the initial state

• S is a property \Rightarrow if we have to calculate the variation of entropy between two states we can calculate it through any process between the two same states (even a reversible process)

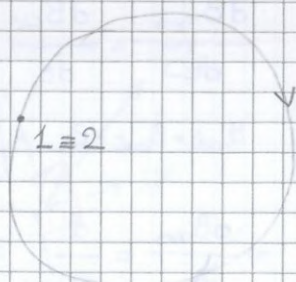
• for a cycle $\Delta S_{\text{cycle}} = 0$

$$\Rightarrow \oint \frac{dQ}{T} + \oint \frac{dL_w}{T} = 0$$

$$\oint \frac{dQ}{T} = - \oint \frac{dL_w}{T}$$

Clausius's inequality works

Let us consider a CYCLE:



$$\begin{aligned} dQ + dL &= dU + dE_g + dE_k + dE_w \\ Q + L &= \cancel{\Delta U} + \cancel{\Delta E_g} + \cancel{\Delta E_k} + \cancel{\Delta E_w} \\ &= 0 \text{ (cycle)} \end{aligned}$$

$$\Rightarrow \oint dQ + \oint dL = 0$$

$$m_e(t + \Delta t) = m_{cv}(t + \Delta t) - \frac{dm_{in}}{(1-1')} + \frac{dm_{out}}{(2-2')}$$

$$m_{cv}(t) = m_{cv}(t + \Delta t) - dm_{in} + dm_{out}$$

$$m_{cv}(t + \Delta t) - m_{cv}(t) + dm_{out} - dm_{in} = 0$$

$$dm_{out} = \dot{m}_{out} \cdot dt$$

$$dm_{in} = \dot{m}_{in} \cdot dt$$

so:

$$dm_{cv} + \dot{m}_{out} \cdot dt - \dot{m}_{in} \cdot dt = 0$$

$$\frac{dm_{cv}}{dt} + \dot{m}_{out} - \dot{m}_{in} = 0$$

$$\frac{\partial m_{cv}}{\partial t} + \dot{m}_f = 0, \quad \dot{m}_f = \sum_i \dot{m}_{out,i} - \sum_j \dot{m}_{in,j}$$

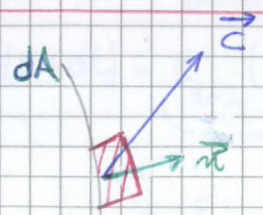
↓

the use of a partial derivative is due to possible changes of mass within the control volume (it is not exactly the same mass: same amount but different mass)

so: if $\dot{m}_{in} = \dot{m}_{out} \Rightarrow \frac{\partial m_{cv}}{\partial t} = 0 \Rightarrow$ same amount of mass but different mass

so:

$$\frac{\partial}{\partial t} \int_{cv} \rho dV + \dot{m}_f = 0$$



$t \rightarrow t + dt$

$$d^2 m = \rho d^2 V, \quad d^2 V = dA \cdot \vec{n} \cdot d\vec{s}$$

$$\Rightarrow d^2 m = \rho dA \vec{n} \cdot d\vec{s}$$

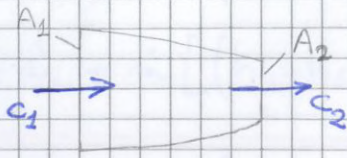
$$\frac{d^2 m}{dt} = \rho dA \vec{n} \cdot \vec{c}$$

$$d \frac{dm}{dt} = \rho dA \vec{n} \cdot \vec{c}$$

$$\rho_2 c_2 \cos \theta_2 A_2 = \rho_1 c_1 \cos(\pi - \theta_1) A_1$$

• If the fluid is INCOMPRESSIBLE:

$$c_{m_2} A_2 = c_{m_1} A_1 \quad (\text{CONTINUITY EQUATION})$$



1st PRINCIPLE for OPEN SYSTEM

$$\frac{\partial}{\partial t} m_{cv} + \dot{m}_g = 0$$

$$\frac{\partial}{\partial t} \int_{cv} \rho dV + \int_A \rho (\vec{c} \cdot \vec{n}) dA = 0$$

Let us consider a mass portion:

$$m_c = m_{cv}(t+dt) + \dots$$

the 1st law of thermodynamics holds:

$$dQ + dL = dE$$

$$dQ + dL = dE = E_c(t+dt) - E_c(t),$$

$$E_c(t) = E_{cv}(t)$$

$$E_c(t+dt) = \underbrace{E_{1-2}}(t+dt) + \underbrace{E_{2-2'}}(t+dt)$$

$$E_c(t+dt) = \underbrace{E_{1-2}}(t+dt) + \underbrace{E_{2-2'}}(t+dt) - E_{1-1'}(t+dt)$$

$$= E_{cv}(t+dt) + dE_{out} - dE_{in}$$

$$dE = E_c(t+dt) - E_c(t) =$$

$$= E_{cv}(t+dt) + dE_{out} - dE_{in} - E_{cv}(t)$$

So:

$$dQ + dL = dE_{cv} + \dot{E}_{out} dt - \dot{E}_{in} dt$$

$$\dot{Q} + \dot{L} = \frac{\partial E_{cv}}{\partial t} + \dot{E}_g \quad \text{flux term}$$

- For 1D flow (= properties, at a given cross section, do not depend on the points of the cross section):

$$\dot{Q} + \dot{L}_i = \underbrace{\rho_2 C_2 \cos \nu_2 A_2 (h_2 + E_{k_2} + \dots)}_{\dot{m}_2} - \underbrace{\rho_1 C_1 \cos(\pi - \nu_1) A_1 (h_1 + E_{k_1} + \dots)}_{\dot{m}_1}$$

but at steady state: $\dot{m}_2 = \dot{m}_1 = \dot{m}$

$$\dot{Q} + \dot{L}_i = \dot{m} [(h_2 - h_1) + (E_{k_2} - E_{k_1}) + \dots]$$

$$\dot{Q} + \dot{L}_i = \dot{m} (\Delta h + \Delta E_k + \Delta E_g + \Delta E_w)$$

operating
motor

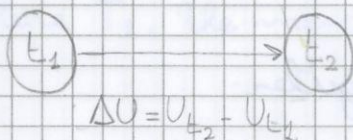
$$Q + L_i = \Delta h + \Delta E_k + \Delta E_g + \Delta E_w$$

If we make a comparison with the expression for closed system:

$$Q + L = \Delta U + \Delta E_k + \Delta E_g + \Delta E_w$$

we may notice:

- L refers to superficial work (moving boundary) while L_i is internal work (shaft work);
- ΔU for closed system is a difference between initial and final times



- Δh for open system is a difference between sections 1 and 2 (= difference in space and not in time).

The 1st principle of T states that:

$$dQ + dL_w = dh - v dp.$$

Let us consider the mass between sections 1 and 1' which evolves up to region 2 and 2'; since it is a closed system:

$$Q_{t_1 \rightarrow t_2} + L_w = h(t_2) - h(t_1) - \int_{t_1}^{t_2} v dp$$

since enthalpy is a property and we are considering a steady state flow the temperature of the mass does not change at the

and if $L_i = 0$ (no shaft) we get:

$$\frac{\Delta p}{\rho} + \Delta E_k + g \Delta z = 0$$

BERNOULLI'S EQUATION

2nd PRINCIPLE for OPEN SYSTEMS

$$dS = \frac{dQ}{T} + \frac{dL_w}{T}$$

$$dS = S_2 - S_1 = \int_{t_1}^{t_2} \frac{dQ}{T} + \int_{t_1}^{t_2} \frac{dL_w}{T} = \int_1^2 \frac{dQ}{T} + \int_1^2 \frac{dL_w}{T}$$

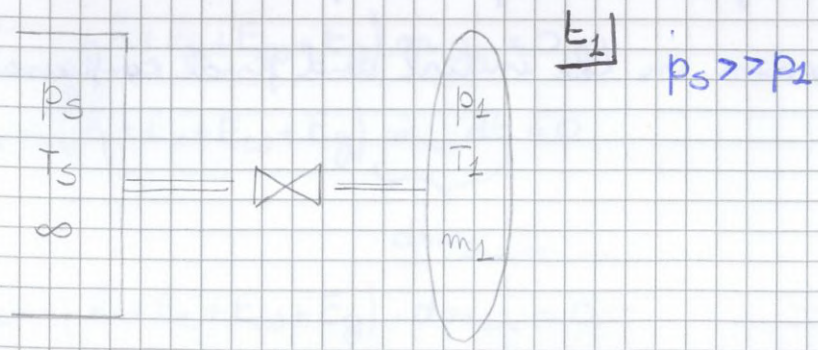
↓
for steady state flow

When we consider a COMPRESSIBLE FLUID (such as gas) we always neglect ΔE_g because to appreciate change of 1 kcal/kg we need a elevation change of 427 m.

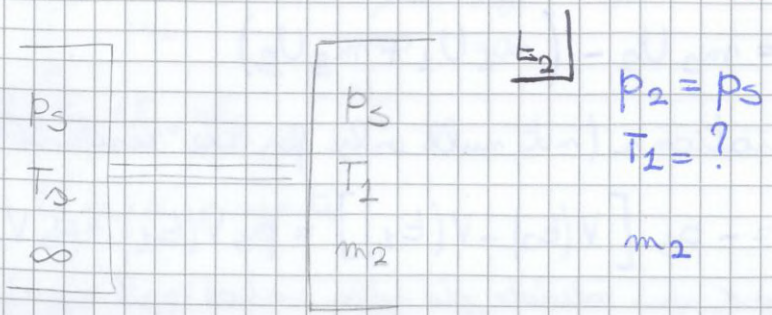
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EXERCISE

Let us consider an infinite capacity tank (= property does not change) at temperature T_s and pressure p_s and a cylinder at pressure p_1 and temperature T_1 . The valve is opened to allow fluid flow through the pipe



FLUID FLOW stops when the pressures get equal, as shown:



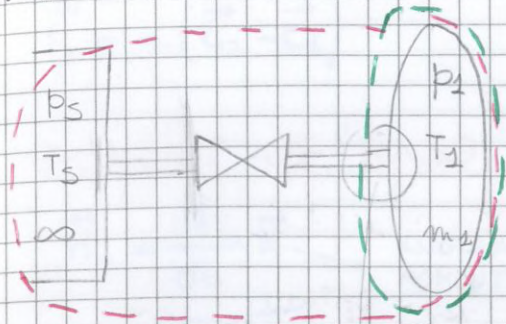
Pr:

$$p_5 m_5 v_5 = m_2 U_2 - (m_1 U_1 + m_5 U_5)$$

$$m_5 (U_5 + p_5 v_5) = m_2 U_2 - m_1 U_1$$

$$m_5 h_5 = m_2 U_2 - m_1 U_1$$

OPEN-SYSTEM APPROACH

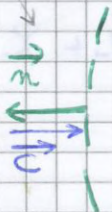


The open system chosen is not steady; so:

$$Q + \dot{L}_i = \frac{\partial}{\partial t} \int_{cv} \rho E dV + \int (h + E_k + E_w + E_g) \rho (\vec{c} \cdot \vec{n}) dA$$

= 0

- $Q = 0$ because the process is adiabatic;
- $\dot{L}_i = 0$ (null) because there is no shaft.



let's suppose we have a 1D flow

$$\frac{\partial E_{cv}}{\partial t} - (h + E_k + E_w + E_g) \dot{m}_{in} = 0$$

$$dE_{cv} - (h + E_k + E_w + E_g) \underbrace{\dot{m}_{in} dt}_{dm_{in}} = 0$$

$$dE_{cv} - (h + E_k + E_w + E_g) \cdot dm_{in} = 0$$

$$\int_{t_i}^{t_f} dE_{cv} - \int_{t_i}^{t_f} (h + E_k + E_w + E_g) dm_{in} = 0$$

= 0 = 0

$$h + E_k + E_w + E_g$$

since E is a property:

$$E_{cv}(t_f) - E_{cv}(t_i) -$$

• at steady state: $\frac{\partial}{\partial t} \int_{CV} \rho \vec{c} dV = 0$
 $dm = 0 \Rightarrow \dot{m}_{in} = \dot{m}_{out}$

so we get:

$$\vec{F} - \int_A p \vec{n} dA + \int_{CV} \rho \vec{g} dV = \dot{m}(\vec{c}_2 - \vec{c}_1)$$

$$\vec{R} = \dot{m}(\vec{c}_2 - \vec{c}_1)$$

MOMENT OF MASS MOMENTUM

$$\vec{H}_O = \frac{d}{dt} \vec{K} \rightarrow \text{ANGULAR MOMENTUM}$$

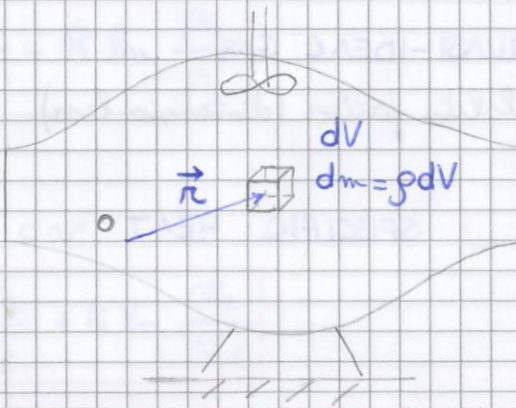
SUBSTANTIAL DERIVATIVE

$$\vec{H} = I \vec{\omega} = I \frac{d\vec{\omega}}{dt} = \frac{d}{dt} (I \vec{\omega}) = \frac{d}{dt} (\vec{H})$$

$$\vec{H} = \vec{r} \wedge \vec{R} = \vec{r} \wedge m \frac{d\vec{v}}{dt} = m \frac{d}{dt} (\vec{r} \wedge \vec{v})$$

Using RTT we can say:

$$\frac{d\vec{K}}{dt} = \frac{\partial \vec{K}}{\partial t} + \dot{K}_f$$



$$\vec{H}_O = \frac{\partial}{\partial t} \int_{CV} (\vec{r} \wedge \vec{c}) \rho dV + \int_A (\vec{r} \wedge \vec{c}) \rho (\vec{c} \cdot \vec{n}) dA$$

$$\vec{r} \times \vec{R}$$

at STEADY STATE:

$$\vec{H}_O = \int_A (\vec{r} \wedge \vec{c}) \rho (\vec{c} \cdot \vec{n}) dA$$

for 1D FLOW:

$$\vec{H}_O = \dot{m} (\vec{r}_{out} \wedge \vec{c}_{out} - \vec{r}_{in} \wedge \vec{c}_{in})$$

$$dh - du = p dv + v dp$$

$$c_p dT - c_v dT = d(v p)$$

$$c_p dT - c_v dT = d(RT)$$

$$c_p dT - c_v dT = R dT$$

$$c_v = \frac{R}{k-1}$$

$$c_p = \frac{k}{k-1} R$$

$$c_p - c_v = R \quad \text{Meyer's relation (for ideal gases only)}$$

Then:

$$dS = \frac{dQ + dL_w}{T}$$

$$T dS = dQ + dL_w = dh - v dp = dU + p dv$$

1st and 2nd
Gibbs equations

$$1) T dS = c_p dT - \frac{RT}{p} dp$$

$$dS = c_p \frac{dT}{T} - \frac{R}{p} dp$$

$$\Delta S_{1-2} = \int_{T_1}^{T_2} c_p \frac{dT}{T} - \int_{p_1}^{p_2} \frac{R}{p} dp$$

$$\Delta S_{1-2} = c_p \ln \frac{T_2}{T_1} - R \ln \frac{p_2}{p_1}$$

$$2) T dS = dU + p dv$$

$$dS = c_v \frac{dT}{T} + \frac{RT}{vT} dv$$

$$\Delta S_{1-2} = c_v \ln \frac{T_2}{T_1} + R \ln \frac{v_2}{v_1}$$

PROCESSES

1) $p = \text{const}$ ISOBARIC
 $p v = RT \Rightarrow \frac{T}{v} = \text{const}$

2) $v = \text{const}$ ISOCHORIC
 $p v = RT \Rightarrow \frac{T}{p} = \text{const}$

3) $T = \text{const}$ ISOTHERMAL
 $p v = \text{const}$

4) ADIABATIC REVERSIBLE $Q=0 \Rightarrow$ ISENTROPIC ($S = \text{const}$)

$$c dT = c_p dT - \frac{RT}{p} dp$$

$$(c_p - c) \frac{dT}{T} - (c_p - c_v) \frac{dp}{p} = 0 \quad (1)$$

And recalling:

$$T ds = dU + p dv$$

$$\Rightarrow (c_v - c) \frac{dT}{T} + (c_p - c_v) \frac{dv}{v} = 0 \quad (2)$$

For isentropic processes:

$$c_v \frac{dT}{T} + (c_p - c_v) \frac{dv}{v} = 0$$

$$(I) \frac{dT}{T} + (k-1) \frac{dv}{v} = 0$$

For polytropic processes:

$$(c_v - c) \frac{dT}{T} + (c_p - c_v) \frac{dv}{v} = 0$$

$$(P) \frac{dT}{T} + \left(\frac{c_p - c_v}{c_v - c} \right) \frac{dv}{v} = 0$$

$$m-1 = \frac{c_p - c_v}{c_v - c} \Rightarrow m = \frac{c_p - c}{c_v - c}$$

POLYTROPIC INDEX

$$\Rightarrow (P) \frac{dT}{T} + (m-1) \frac{dv}{v} = 0$$

So we can write the following equations for POLYTROPIC PROCESSES:

$$\begin{aligned} p v^m &= \text{const.} \\ T v^{m-1} &= \text{const.} \\ \frac{T}{p^{\frac{m-1}{m}}} &= \text{const.} \end{aligned}$$

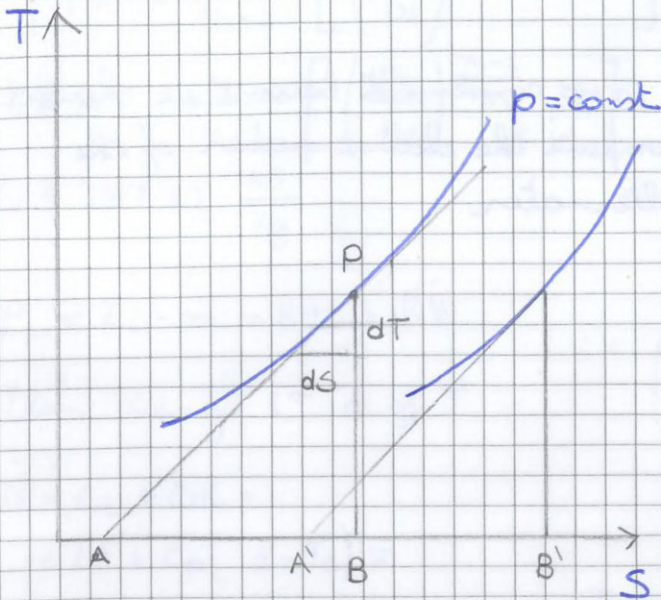
se hai il coefficiente m di un processo puoi applicare direttamente queste relazioni perché esse valgono anche per $dQ \neq 0$ e $dL_w \neq 0$

$$T_1 p_1^{\frac{1-m}{m}} = T_2 p_2^{\frac{1-m}{m}}$$

$$\left(\frac{p_2}{p_1} \right)^{\frac{1-m}{m}} = \frac{T_1}{T_2} \Rightarrow \frac{1-m}{m} = \log_{p_2/p_1} \frac{T_1}{T_2} \Rightarrow \frac{1}{m} = 1 + \log_{p_2/p_1} \frac{T_1}{T_2}$$

$$m = \frac{1}{1 + \log_{p_2/p_1} \frac{T_1}{T_2}}$$

Moreover:



- nel diagramma T,S le isobare e le isocore sono curve congiunte, cioè le possono essere rapportate con un movimento rigido
- poiché

$$\Delta S = c_p \ln \Delta T$$

le isobare sono curve a pendenza crescente e le isocore lo sono ancora di più

$$T dS = c_p dT$$

$$\frac{dS}{dT} = \frac{c_p}{T} \quad (1)$$

$$\frac{dT}{T} = \frac{dS}{c_p} \Rightarrow \Delta S = c_p \ln \frac{T_2}{T_1}$$

from geometry:

$$\frac{dS}{AB} = \frac{dT}{PB} \Rightarrow \frac{dS}{AB} = \frac{dT}{T} \quad (2)$$

from (1) and (2) we get:

$$c_p = \overline{AB} = \overline{A'B'}$$

APPLIED LECTURE 1

2) Date:

$$\dot{m} = 3 \frac{\text{kg}}{\text{s}}$$

$$p_1 = 10 \text{ bar}$$

$$T_1 = 500^\circ\text{C}$$

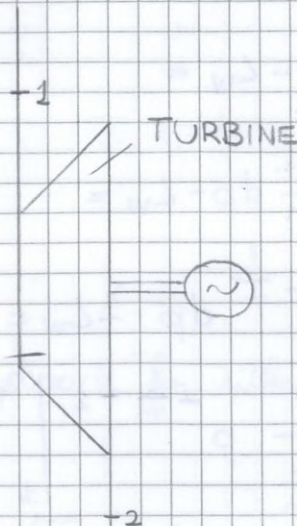
$$p_2 = 1 \text{ bar}$$

$$p_{\text{rot}}^{1.5} = \text{const.}$$

$$\Delta E_k \approx 0$$

$$L_w = 62 \frac{\text{kJ}}{\text{kg}}$$

c_p, R are known



Unknowns:

$P_i?$

$Q?$

$$= -p_1 v_1 \cdot \frac{m}{m-1} \left[\left(\frac{p_2}{p_1} \right)^{\frac{m-1}{m}} - 1 \right] - L_w =$$

$$= -RT_1 \cdot \frac{m}{m-1} \left[\left(\frac{p_2}{p_1} \right)^{\frac{m-1}{m}} - 1 \right] - L_w$$

$$L_i = 297.12 \frac{\text{kJ}}{\text{kg}}$$

$$\int_{v_1}^{v_2} v dp = RT_1 \cdot \frac{m}{m-1} \left[\left(\frac{p_2}{p_1} \right)^{\frac{m-1}{m}} - 1 \right]$$

$$P_i = L_i \cdot \dot{m} = 891.3 \text{ kW}$$

Then using 1st L. of T.

$$Q = L_i + \Delta h =$$

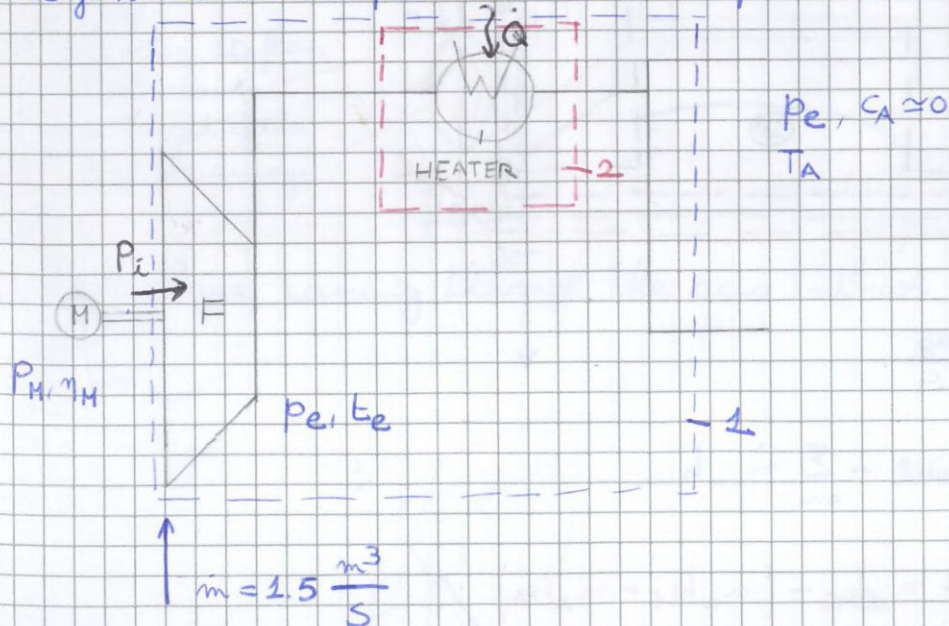
$$= L_i + c_p(T_2 - T_1) =$$

$$= L_i + c_p \left(\frac{p_2 v_2}{R} - T_1 \right), \quad \frac{T}{p^{\frac{m-1}{m}}} = \text{const.}$$

$$= L_i + c_p \left[T_1 \left(\frac{p_2}{p_1} \right)^{\frac{m-1}{m}} - T_1 \right] = -158.5 \frac{\text{kJ}}{\text{kg}}$$

we are refrigerating
our turbine from the
outside

3) A fan can be represented as a compressor:



We choose the Eulerian approach for either 1 or 2 of the CV chosen:

$$Q + L_i = \Delta h + \Delta E_k + \dots$$

$$\dot{Q} + P_i = \dot{m}(h_{out} - h_{in})$$

$$P_i = P_M \cdot \eta_M = 3.59 \text{ kW}$$

1) is wrong choice because

$$\dot{m}_1 = \dot{m}_2 = \dot{m}_3 = \dot{m}_4$$

$$\dot{m}_a = \dot{m}_b$$

2) we don't know $\dot{m}_a = \dot{m}_b = ?$

4) right choice

Using CV # 4:

$$P_i = \dot{m} (c_p T_2 + c_p T_4 - c_p T_1 - c_p T_3), \quad c_p \text{ normally assumed as}$$

$$1006,5 \frac{\text{J}}{\text{kg} \cdot \text{K}}$$

$$P_M = \frac{P_i}{\eta_m} = 37 \text{ KW}$$

13/03

TURBO-MACHINES

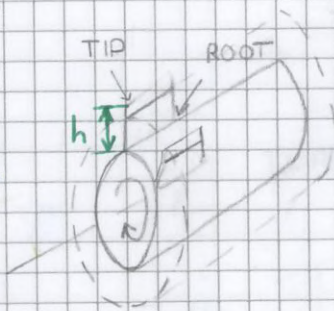
A turbo-machine is made of blades arranged around an axis.

1st) cylindrical surface with bigger diameter

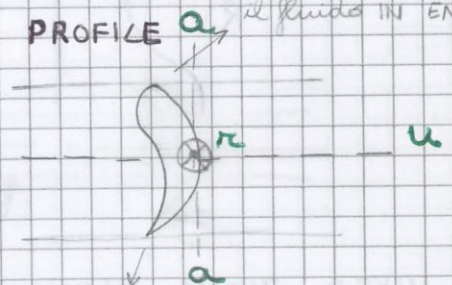
$$\frac{h}{d} \ll 1$$



we'll consider 1D flow with velocity constant along the height of the blade set at the average height



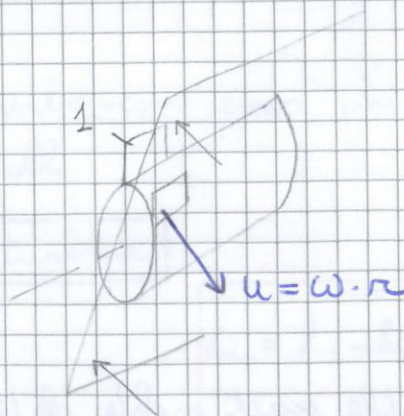
PROFILE



a goccia per raccogliere il fluido IN ENTRATA

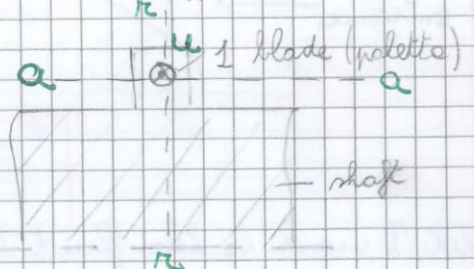
a punta per dirigere il fluido IN USCITA

2nd) plane passing through the axis but not touching the blades

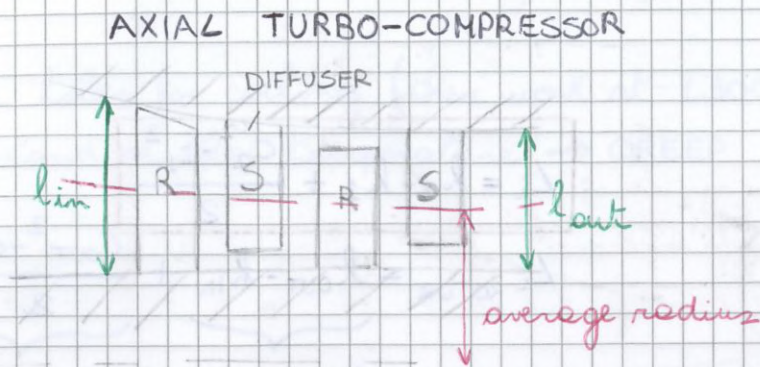


MERIDIONAL

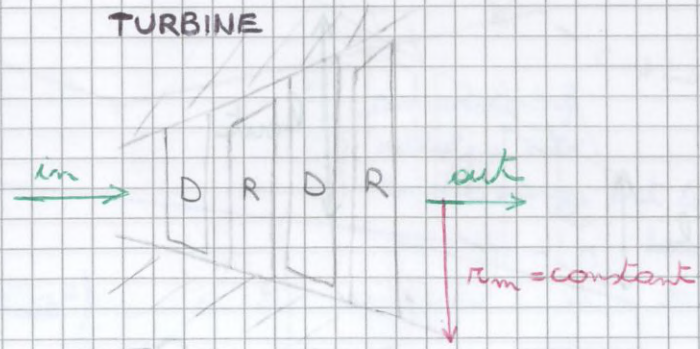
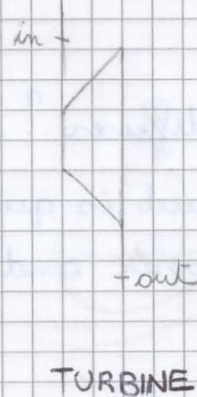
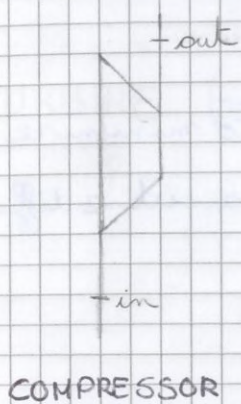
VIEW



A type of MERIDIONAL VIEW is the following:

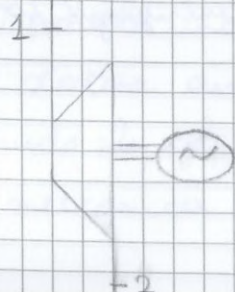


That is the reason why:



Quite often in a turbo-compressor you do not have the diffuser which is replaced by a scroll.

Let us consider a turbine



$$L_i = h_1 - h_2 + \frac{c_1^2 - c_2^2}{2}$$

$$L_{i \text{ STATOR}} = 0$$

$$L_{i \text{ ROTOR}} = h_{in} - h_{out} + \frac{c_{in}^2 - c_{out}^2}{2}$$

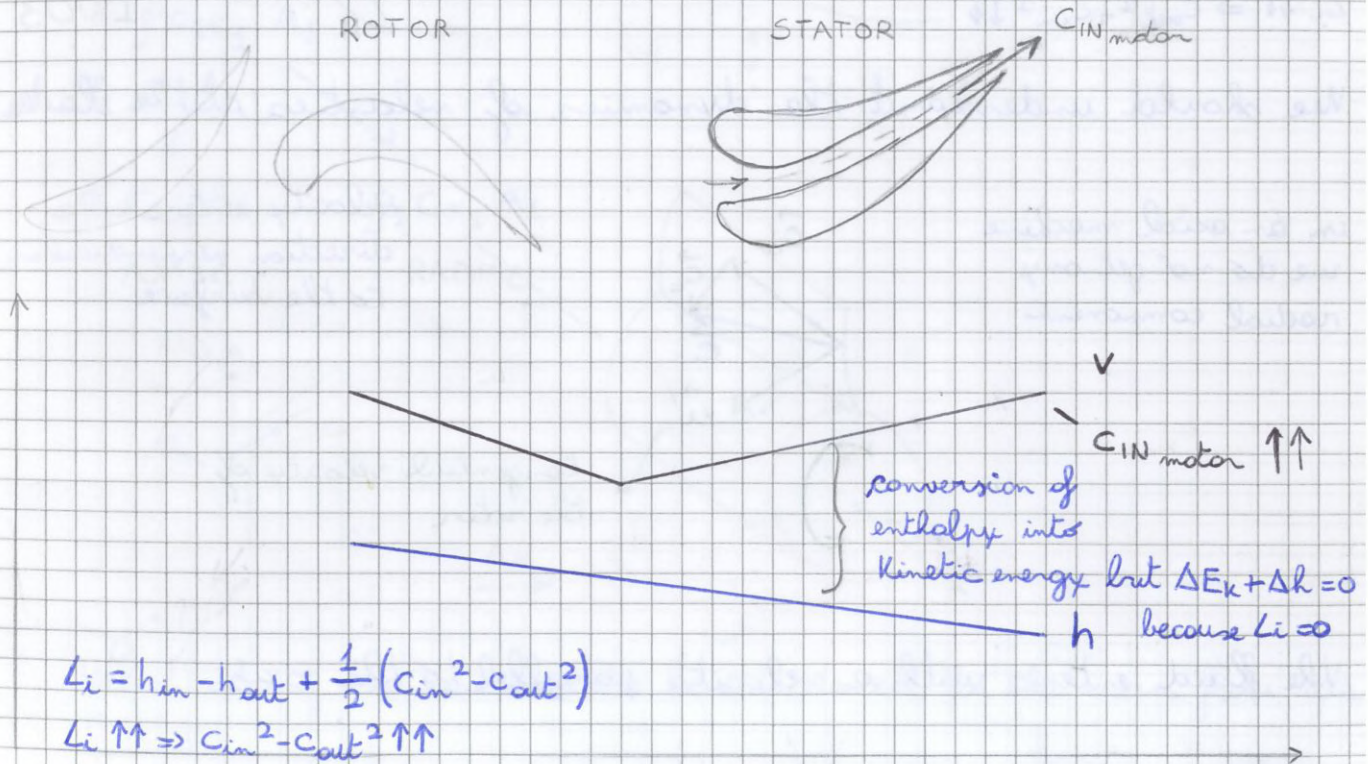
to maximise L_i : $c_{in} \uparrow \uparrow$, $c_{out} = 0$

In this last case we use a TWISTED PROFILE; it is also possible to have both twisted blades and not-twisted blades for compressor and turbine.

Turbines have holes for cooling (they work at 1300°C) because they continuously stand at that temperature \rightarrow CREEP



TURBINE (motor machine)



La prima palettatura fissa dello statore (distributore) serve ad aumentare l'energia cinetica del fluido; poi il rotore fa diminuire velocità e entalpia del fluido trasformando la variazione di energia meccanica in lavoro per l'albero; se vi fosse un nuovo rotore esso utilizzerebbe una velocità in entrata troppo bassa e quindi le palette dello statore aumentano la velocità in entrata del rotore.

Il fluido che colpisce le pale del rotore lo fa muovere e genera energia meccanica sotto forma di rotazione dell'albero.

The mass flow rate equation is:

$$\frac{\partial m_{cv}}{\partial t} + \dot{m}_g = 0$$

↓ ↓
transient flux
term term

talking with TURBOMACHINES we'll deal with STEADY STATE flow; so:

$$\dot{m}_g = 0 \Rightarrow \dot{m} = \text{const.}$$

$$\dot{m} = \int_A \rho (\vec{c} \cdot \vec{n}) dA$$

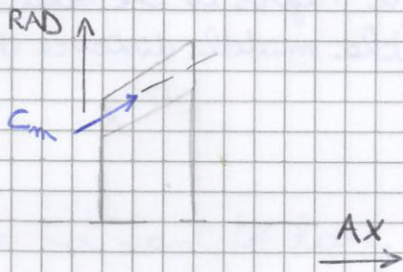
we assume the flow to be 1D flow; so:

$$\dot{m} = \rho_1 \vec{c}_1 \cdot \vec{n} A_1 =$$
$$= \rho c_{m1} A_1$$

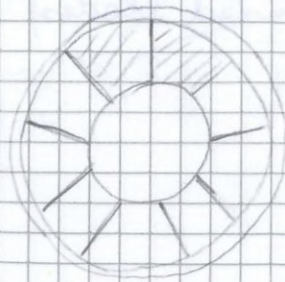
↓ ↓

$$\rho_1 c_{a1} A_1 \quad \rho_1 c_{x1} A_1$$

AXIAL RADIAL



What about the area A to be considered for the mass flow rate

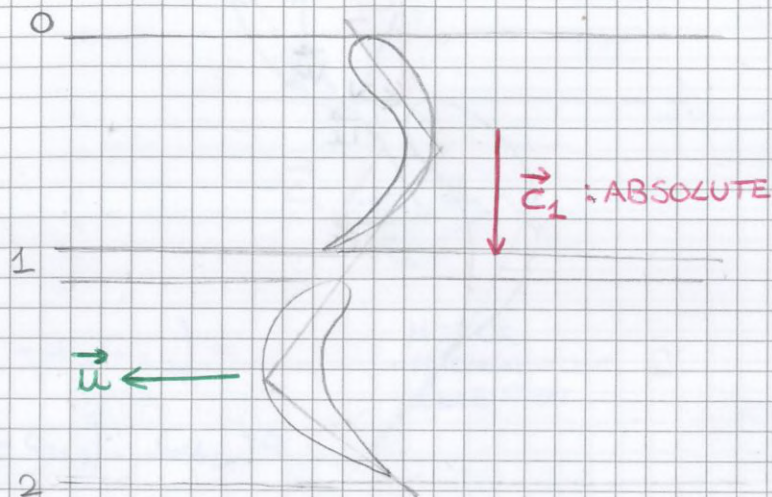


since $l \ll d$ we can compute it as:

$$\frac{\rho_1}{\rho_2} = \frac{C_{a2}}{C_{a1}}$$

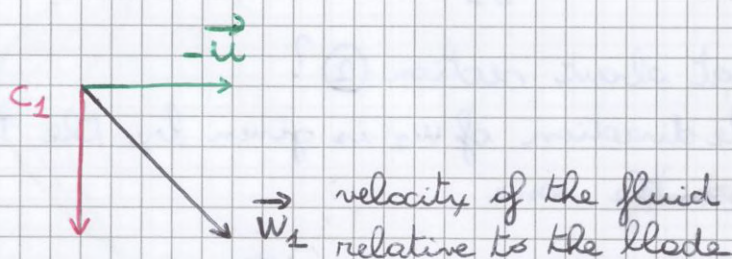
• if $\rho = \text{const} \Rightarrow C_a = \text{const.}$

VELOCITY TRIANGLE

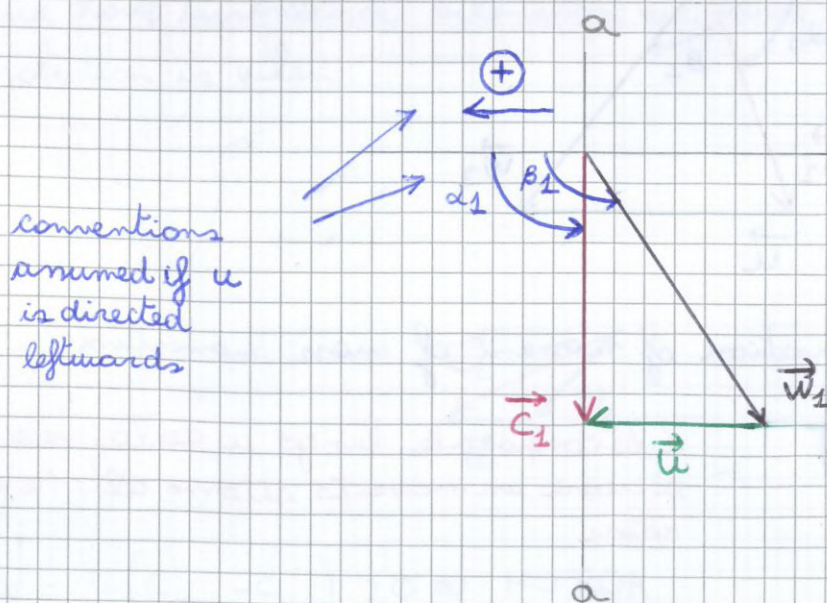


$$\vec{c}_1 = \vec{u} + \vec{w}$$

$$\vec{w}_1 = \vec{c}_1 - \vec{u}$$



we do not want to have $-\vec{u}$, so:



conventions assumed if u is directed leftwards

α_1 is not necessarily equal to $\frac{\pi}{2}$

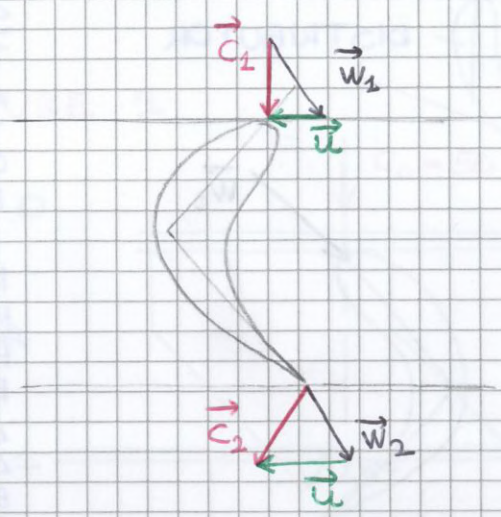
CIAO



$$L_i = u(c_{u2} - c_{u1})$$

$$L_i = u_2 c_{u2} - u_1 c_{u1}$$

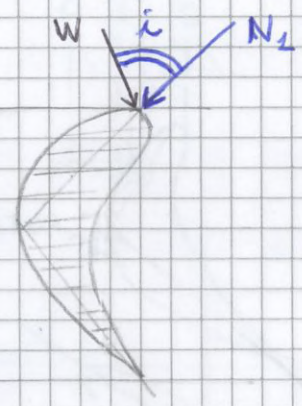
EULER



$$L_i = (u_1 c_{u1} - u_2 c_{u2}) =$$
$$= u (c_{u1} - c_{u2}), c_{u2} > 0$$

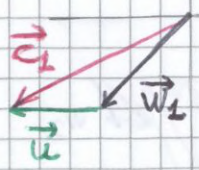
MOTOR
MACHINE
CONVENTION

$$= -u c_{u2} < 0 \Rightarrow \text{OPERATING}$$



we have turbulence whenever we have incidence \Rightarrow the optimum solution is when:

$$i = 0$$

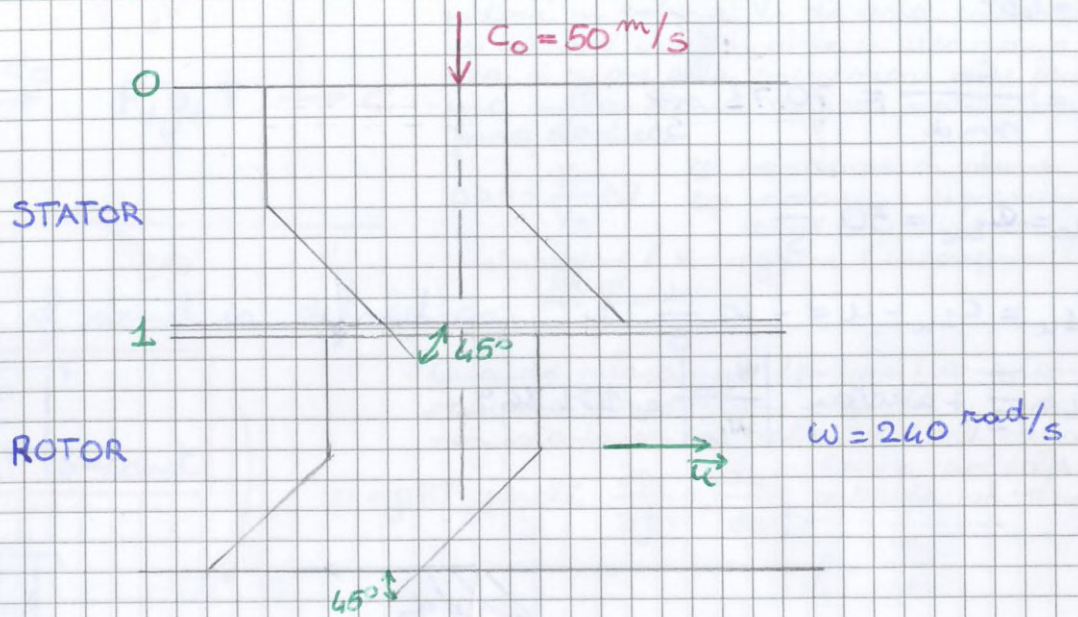


$$L_i = u(c_{u1} - c_{u2}) > 0 \Rightarrow \text{MOTOR}$$

That is the reason why we have a smooth leading edge is that:

APPLIED LECTURE 2

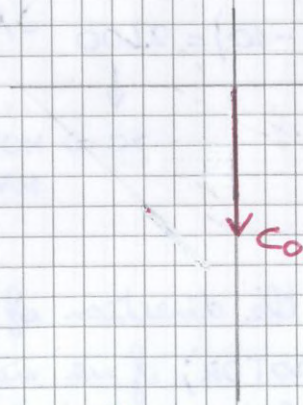
1)



d, l const
WATER

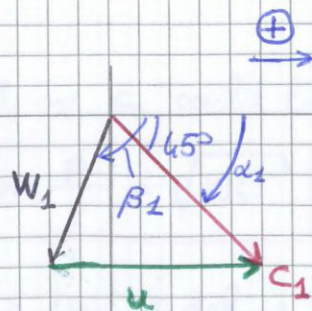


⊙



$$\vec{u} = \omega \cdot r = \omega \cdot \frac{d}{2} = 60 \frac{\text{m}}{\text{s}}$$

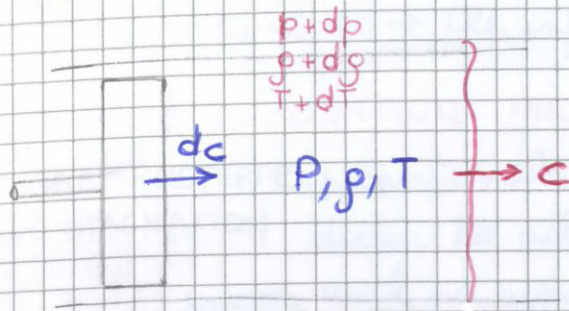
①



we are not working under design, so we cannot assume w_2 axially

We deal with a fixed channel flow.

Let us consider fluid properties in a channel:



- Se comprimiamo lentamente mediante un pistone un volume V_0 di aria contenute in un cilindro indeformabile, ci accorgiamo che essa si oppone alla compressione come farebbe una molla. L'aria reagisce mediante una forza elastica.

$$\Delta p = -\frac{K}{V_0} \Delta V$$

ΔV variazione di volume
 Δp variazione di pressione all'interno del cilindro

\Rightarrow maggiore è K maggiore l'incomprimibilità del fluido

the velocity of sound is defined as:

$$c_s = \sqrt{\left. \frac{\partial p}{\partial \rho} \right|_{s=\text{const}}}$$

$$c_s = \sqrt{\left. \frac{dp}{d\rho} \right|_{s=\text{const}}}$$

- Quando rilasciamo il pistone l'aria tende ad occupare il suo volume originale in maniera non istantanea, ma rallentata dall'inerzia dell'aria, cioè dalla massa contenuta nel volume V_0

$$p = \rho RT, \text{ perché } \frac{\partial p}{\partial \rho} = \frac{dp}{d\rho}$$

$$\rho = \frac{m}{V_0}$$

$$\Rightarrow c = \sqrt{\frac{K}{\rho}}$$

for an isentropic process applied to an ideal gas:

$$\frac{P}{\rho^k} = \text{const}$$

$$dP = d(\text{const} \cdot \rho^k)$$

$$dP = \text{const} \cdot d(\rho^k)$$

$$dP = \text{const} \cdot k \cdot \rho^{k-1} d\rho$$

$$dP = \frac{P}{\rho^k} \cdot k \cdot \rho^{k-1} d\rho$$

$$\frac{dP}{d\rho} = k \cdot \frac{P}{\rho}$$

- for an ideal gas $k = \frac{C_p}{C_v}$ and so c_s could be calculated as

$$\text{square root of } k \cdot \frac{P}{\rho} \Rightarrow c_s = \sqrt{k \cdot \frac{P}{\rho}} = \sqrt{kRT}$$

- for vapour what is k ? let's try to define it

$$Ma < 1 \Rightarrow C < C_s$$

$C_s - C > 0 \Rightarrow$ the information arrives

$$Ma > 1 \Rightarrow C > C_s$$

$C_s - C < 0 \Rightarrow$ the information does not arrive

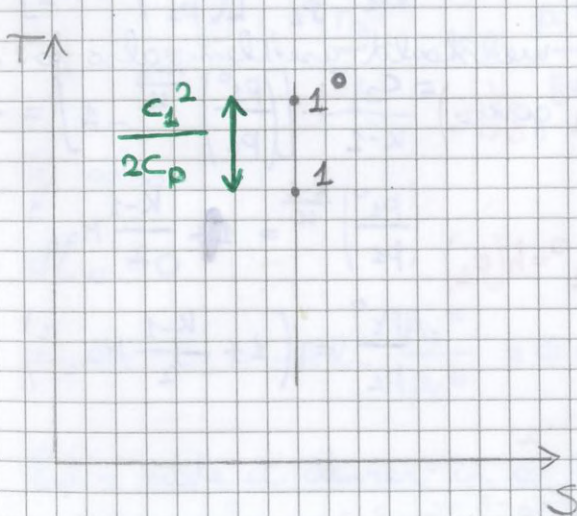
TOTAL & STAGNATION PROPERTIES

TOTAL PROPERTIES: properties the fluid would get if decelerating (or STAGNATION) down to nil velocity through an adiabatic reversible process with no work exchanged with environment.

$$p_1, C_1, T_1 \xrightarrow[\quad L_i = 0]{\quad dQ = 0, dL_w = 0} C_1^\circ = 0, p_1^\circ, T_1^\circ, \rho_1^\circ$$

Applying 1st l. of E. to O.S.:

$$\cancel{dQ} + \cancel{dL_i} = dh + dE_k + \cancel{dE_g} + \cancel{dE_w} \approx 0$$



$$h_1^\circ - h_1 + \frac{C_1^2 - C_1^2}{2} = 0$$

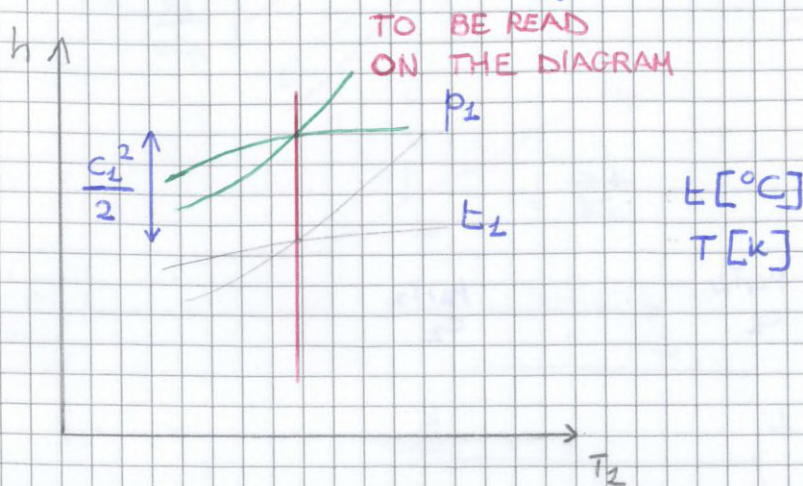
$$h_1^\circ = h_1 + \frac{C_1^2}{2}$$

$$c_p(T_1^\circ - T_1) = \frac{C_1^2}{2}$$

$$T_1^\circ = T_1 + \frac{C_1^2}{2c_p}$$

$$T_1^\circ = f(T_1)$$

What about Mollier's diagram for vapour:



$$dS = c_p \frac{dT}{T} - R \frac{dp}{p}$$

$$S_2 - S_1 = c_p \ln \frac{T_2}{T_1} - R \ln \frac{p_2}{p_1}$$

$$S_2 - S_1 = S_2^{\circ} - S_1^{\circ} = c_p \ln \frac{T_2^{\circ}}{T_1^{\circ}} - R \ln \frac{p_2^{\circ}}{p_1^{\circ}}$$

Let us suppose the process to be **adiabatic**: $dQ = 0$ and let's apply 1st l. of. t. for process 1 \rightarrow 2:

$$dQ + dL_i = dh + dE_k$$

$$h_1 + \frac{c_1^2}{2} = h_2 + \frac{c_2^2}{2}$$

$$h_1^{\circ} = h_2^{\circ}$$

$$h^{\circ} = \text{const.}$$

$$\Rightarrow T^{\circ} = \text{const.}$$

- adiabatic
- no internal work
- $h^{\circ} = \text{const}$
- $\Rightarrow T^{\circ} = \text{const}$
- $S_2 - S_1 = -R \ln \frac{p_2^{\circ}}{p_1^{\circ}}$

∴:

$$S_2 - S_1 = c_p \ln \frac{T_2^{\circ}}{T_1^{\circ}} - R \ln \frac{p_2^{\circ}}{p_1^{\circ}} = -R \ln \frac{p_2^{\circ}}{p_1^{\circ}}$$

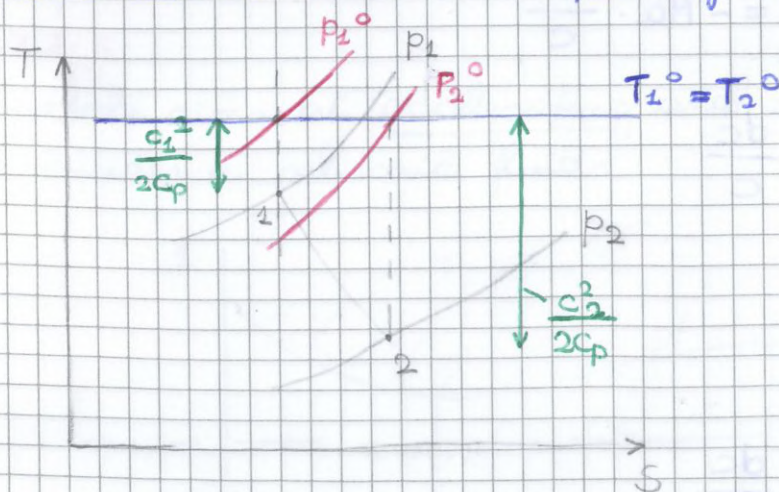
If also:

$$dL_w = 0$$

$$\Rightarrow S_2 - S_1 = -R \ln \frac{p_2^{\circ}}{p_1^{\circ}} = 0 \Rightarrow p^{\circ} = \text{const}$$

- adiabatic reversible
- no internal work
- $h^{\circ} = \text{const.}$
- $\Rightarrow T^{\circ} = \text{const}$
- $p^{\circ} = \text{const.}$

Let's make it clearer in a T,S diagram



$$\frac{dp}{\rho p} = -\frac{c^2}{c_s^2} \cdot \frac{dc}{c} \Rightarrow \frac{dc}{c} = -\frac{1}{KMa^2} \cdot \frac{dp}{p}$$

$$\frac{dA}{A} = \frac{1-Ma^2}{KMa^2} \cdot \frac{dp}{p}$$

un UGELLO o DIFFUSORE possono:

- accelerare e espandere
- decelerare e comprimere
- non ci sono più casi (accelerare e comprimere o espandere e decelerare) perché

$$\frac{dc}{c} = -\frac{dp}{p} \cdot \frac{1}{KMa^2} > 0$$

1) $\frac{dp}{p} > 0$
 $Ma < 1$

$$\Rightarrow \frac{dc}{c} < 0 \Rightarrow \frac{dp}{p} > 0$$

DIFFUSER =
 compressing +
 decelerating

2) $\frac{dp}{p} < 0$
 $Ma > 1$

$$\Rightarrow \frac{dc}{c} > 0 \Rightarrow \frac{dp}{p} < 0$$

NOZZLE:
 accelerating +
 expanding

3) $\frac{dp}{p} < 0$
 $Ma < 1$

$$\Rightarrow \frac{dc}{c} > 0 \Rightarrow \frac{dp}{p} < 0$$

NOZZLE:
 accelerating +
 expanding

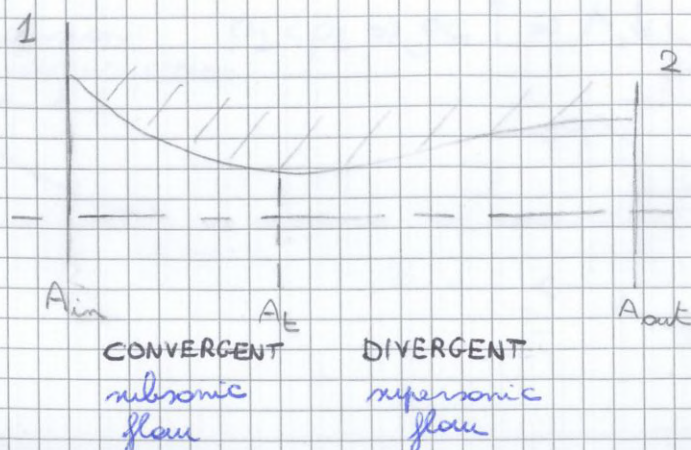
4) $\frac{dp}{p} > 0$
 $Ma > 1$

$$\Rightarrow \frac{dc}{c} < 0 \Rightarrow \frac{dp}{p} > 0$$

DIFFUSER:
 compressing +
 decelerating

NOZZLE

A nozzle aims at accelerating and expanding the gas.
 We consider a subsonic fluid:



$$1) \quad c \left(\frac{p}{p_2^0} \right) = \sqrt{\frac{2k}{k-1} \frac{p_2^0}{\rho_2^0} \left[1 - \left(\frac{p}{p_2^0} \right)^{\frac{k-1}{k}} \right]}$$

$$\frac{p_2^0}{\rho_2^0{}^k} = \frac{p}{\rho^k} \Rightarrow \rho \left(\frac{p}{p_2^0} \right) = \left(\frac{p}{p_2^0} \right)^{1/k} \rho_2^0 \quad 2)$$

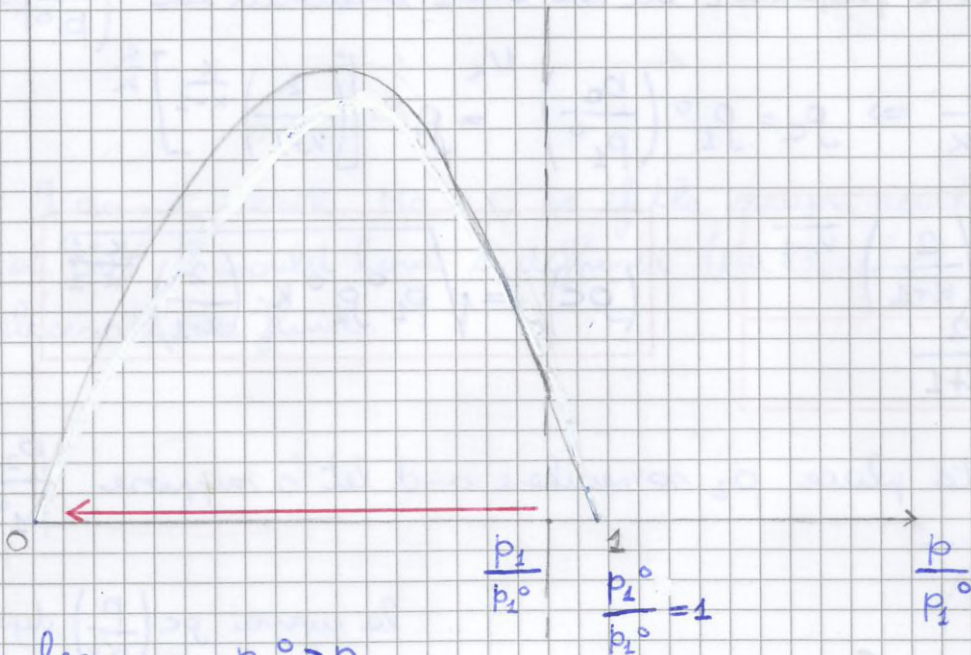
$$3) \quad \rho c \left(\frac{p}{p_2^0} \right) = \sqrt{\frac{2k}{k-1} p_2^0 \rho_2^0 \left[\left(\frac{p}{p_2^0} \right)^{\frac{2}{k}} - \left(\frac{p}{p_2^0} \right)^{\frac{k+1}{k}} \right]}$$

chi mi garantisce che $\frac{p_2^0}{\rho_2^0{}^k} = \text{const}$? perché per def. la proprietà totale per definizione non dipende su un'isentrope

20/03

Let us represent relation 3) in a diagram:

$$\frac{1}{A} \propto \rho c \uparrow$$



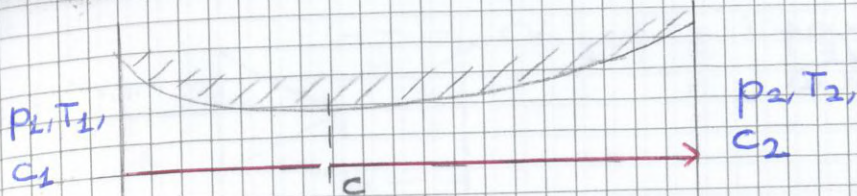
$$\frac{p}{p_2^0} < 1 \text{ because } p_2^0 > p_2$$

if I want to expand the fluid I would need to have ρc increase and therefore A has to decrease

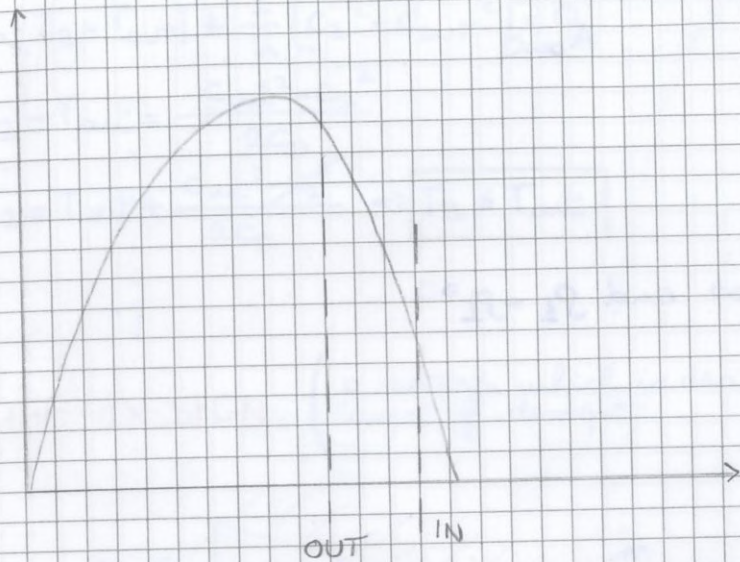
in the expansion: $p_2 < p_1 \Rightarrow \rho c \uparrow \Rightarrow A \downarrow$

CONVERGING REGION

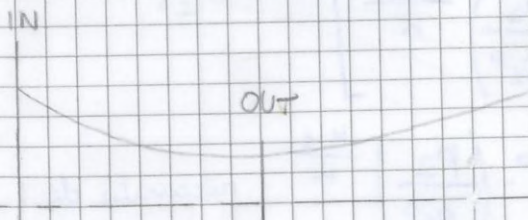
$p_1, T_1,$
 c_1



If I want to expand from IN to OUT



at OUT I do not reach $Ma = 1$; so if the section reaches its throat at OUT I would have a diffuser ($Ma < 1$) which compresses and decelerates the fluid.

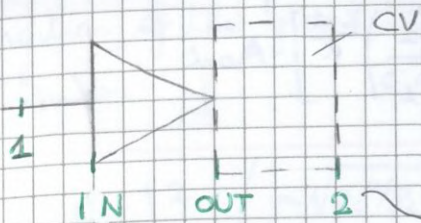


DESIGN OF NOZZLES

\dot{m}
 $p_1, T_1, c_1, \rho_1 \rightarrow p_2^0, T_2^0, \rho_2^0$
 $p_2 < p_1$ because it is expanded

1) $\left(\frac{p_2}{p_1^0}\right) > \left(\frac{p}{p_1^0}\right)_{CR}$: PURE CONVERGENT

2) $\left(\frac{p_2}{p_1^0}\right) < \left(\frac{p}{p_1^0}\right)_{CR}$: CONVERGENT + DIVERGENT (DE LAVAL)



point 1 can be considered to be coincident with point IN

$$\dot{Q} + \dot{W}_c = \Delta h + \Delta E_k$$

$$= 0 = 0$$

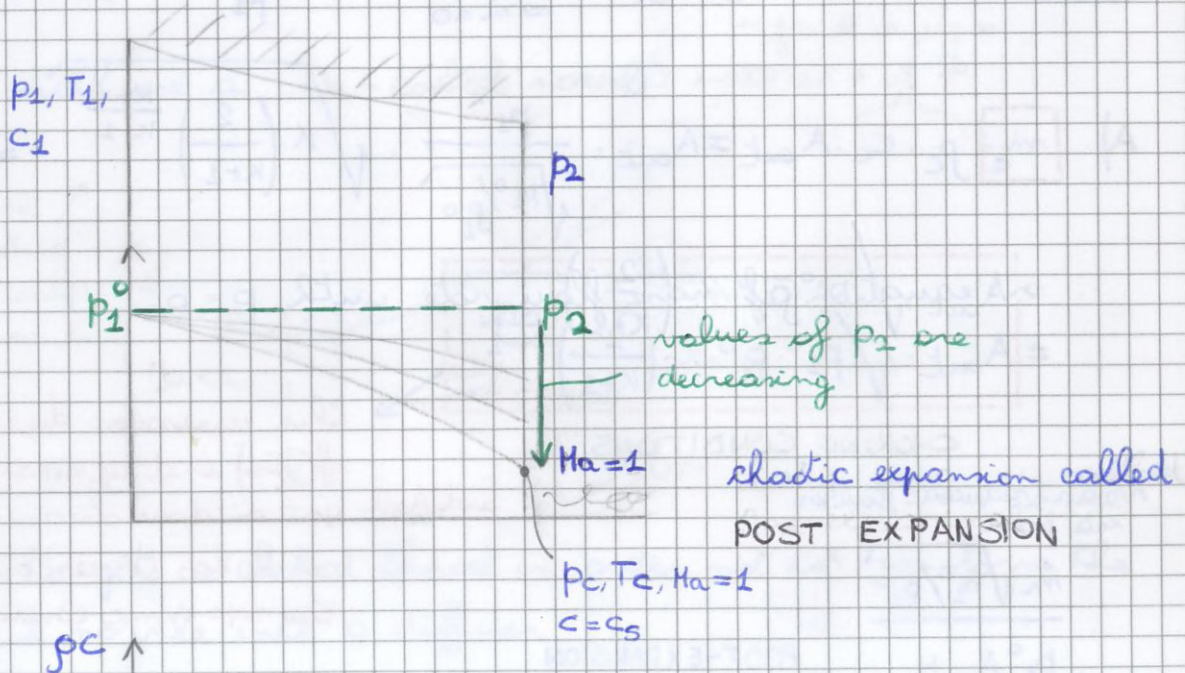
2 \equiv OUT $^{\circ}$ perché da OUT a 2 processo adiabatico, internamente reversibile e senza lavoro interno?

$$c_p(T_2 - T_{out}) + \frac{1}{2}(c_2^2 - c_{out}^2) = 0$$

$$T_2 - T_{out} = \frac{c_{out}^2 - c_2^2}{2c_p}$$

$$T_2 = T_{out} + \frac{c_{out}^2 - c_2^2}{2c_p} \Rightarrow \boxed{T_2 \neq T_{out}}$$

OFF-DESIGN (a nozzle which is designed isentropically is used off-design)



p_c

$$\frac{p_2}{p_1^0} = \frac{p_2}{p_2^0}$$

$$\Rightarrow D_1 = D_2$$

$$\frac{p}{p_1^0}$$

The portion of the graph characterized by the ellipse can be written as:

$$\left(\frac{\frac{p_2}{p_1^0} - \frac{p_c}{p_2^0}}{1 - \frac{p_c}{p_2^0}} \right)^2 + \frac{\left(\frac{m \sqrt{p_1^0 / \rho_1^0}}{p_2^0 \cdot A_{out}} \right)^2}{\sqrt{k \cdot \left(\frac{2}{k+1} \right)^{\frac{k+1}{k-1}}}} = 1$$

max flow rate for subsonic flow conditions can also be evaluated according to the following equation:
 approssimazione buona ma non esatta

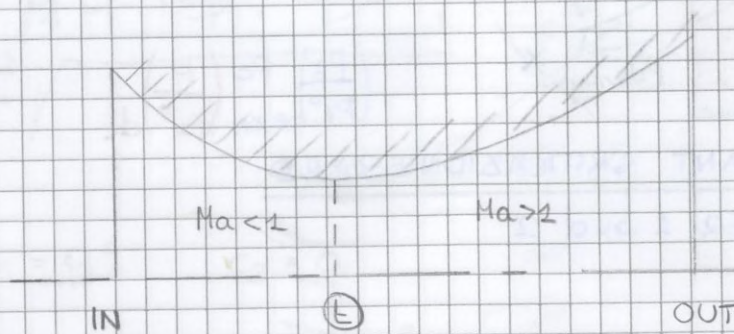
25/03

DE-LAVAL NOZZLE

Suppose we want to have:

$$\left(\frac{p_2}{p_1^0} \right) < \left(\frac{p}{p_1^0} \right)_{CR} \Rightarrow \text{we cannot longer use a SIMPLY CONVERGENT nozzle}$$

but I will use a De-Laval nozzle:



I want to get a choked throat in order not to transform the divergent nozzle into a diffuser:

at (E): $Ma = 1 \Rightarrow c = c_s$

(OUT): A_{out} is calculated by equation:

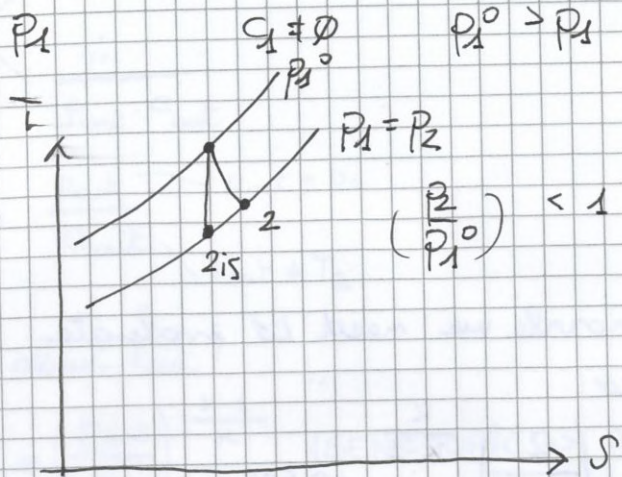
$$A_{out} = \frac{m \sqrt{p_1^0 / \rho_1^0}}{p_2^0} \cdot \frac{1}{\sqrt{\frac{2k}{k-1} \left[\left(\frac{p_{out}}{p_1^0} \right)^{\frac{2}{k}} - \left(\frac{p_{out}}{p_1^0} \right)^{\frac{k+1}{k}} \right]}}$$

$p_{out} = p_2$
under DESIGN

(IN): $A_1 = \frac{m}{\rho_1^0 c_1}$

$$c_2 = 0$$

$$p_2 = p_1$$



$$\frac{dp}{p} = -c dc$$

$$\int_{p_1^0}^{p_2} \frac{dp}{p} = \int_1^2 -c dc = \frac{c_2^2}{2} - \frac{c_1^2}{2}$$

$$c_2 = \sqrt{\frac{k}{k-1} \frac{p_2}{p_1^0} \left[\left(\frac{p_2}{p_1^0} \right)^{\frac{k-1}{k}} - 1 \right]}$$

$$p_2 = p_2^0 \quad c_2 = 0 \quad \infty$$

$$p_{out} = p_2$$

$p_{out} = p_2$ anche per $\left(\frac{p_2}{p_1^0} \right)_{0.85} \leq \frac{p_2}{p_1^0} \leq \left(\frac{p_2}{p_1^0} \right)_d$

while

$p_{out} \neq p_2$ for $\left(\frac{p_2}{p_1^0} \right) \leq \left(\frac{p_2}{p_1^0} \right)_{design}$

What about A_{out} ?

$$A_{out} = \frac{\dot{m}}{p_{out} \cdot c_{out}} \quad \text{eq. 1}$$

$$p_{out} = \frac{p_{out}}{RT_{out}} \quad \begin{array}{l} p_{out} = p_2 \\ T_{out} \neq T_2 \end{array}$$

What about T_{out} ?

$$\frac{T_{out}}{T_2} = \left(\frac{p_{out}}{p_1} \right)^{\frac{k-1}{k}} \quad \text{ISENTROPIC} \Rightarrow T_{out} = T_2 \cdot \left(\frac{p_{out}}{p_1} \right)^{\frac{k-1}{k}} = 637.2 \text{ K}$$

and c_{out} ?

$$\cancel{Q} + \cancel{K_i} = \Delta E_k + \Delta h$$

$$c_p(T_{out} - T_2) + \frac{1}{2}(c_{out}^2 - c_2^2)$$

$$c_{out} = \sqrt{c_2^2 + 2c_p(T_2 - T_{out})} = 369.0 \frac{\text{m}}{\text{s}}$$

so:

$$A_{out} = \frac{\dot{m}}{\frac{p_{out}}{RT_{out}} \cdot c_{out}} = 102.01 \text{ cm}^2$$

Now check:

- $A_{out} < A_{in}$
- check $Ma_{out} < 1$

$$Ma_{out} = \frac{c_{out}}{c_{s_{out}}} = \frac{369.0}{\sqrt{kRT_{out}}} = 0.880 < 1$$

OFF-DESIGN (we use the nozzle designed with other conditions)
We need to evaluate the expansion ratio:

$$\left(\frac{p_2}{p_2^0} \right) \left(\frac{p}{p_2^0} \right)_{CR} = \left(\frac{2}{k+1} \right)^{\frac{k}{k-1}} = 0.528$$

$$p_2^0 = p_2 \left(1 + \frac{k-1}{2} \cdot \frac{c_2^2}{kRT_2} \right)^{\frac{k}{k-1}} = p_2 = 0.5 \text{ MPa}$$

NOTE

Quando progetta un ugello tale da avere un determinato rapporto di pressioni $\left(\frac{p_2}{p_1^0}\right)$ decide in base alla relazione:

$$\frac{p_2}{p_1^0} \leq \left(\frac{p}{p_1^0}\right)_{CR}$$

se progettare un ugello di de Laval o un ugello puramente convergente.

Nelle progettazioni OFF-DESIGN nel caso di un ugello puramente convergente non ci son problemi fino al rapporto:

$$\left(\frac{p_2}{p_1^0}\right) \geq \left(\frac{p}{p_1^0}\right)_{CR}$$

$$\text{e se } \left(\frac{p_2}{p_1^0}\right) = \left(\frac{p}{p_1^0}\right)_{CR}$$

ottengo:

$$\begin{cases} c = c_c \\ \rho = \rho_c \\ \dot{m} = A_{out} \cdot \frac{p_2^0}{\sqrt{p_2^0/\rho_2^0}} \sqrt{k \cdot \left(\frac{2}{k+1}\right)^{\frac{k+1}{k-1}}} \end{cases}$$

queste espressioni non dipendono dal punto 2 (p_2, ρ_2 : DOWNSTREAM CONDITIONS)

Quindi se diminuisco ulteriormente

$$\frac{p_2}{p_1^0} < \left(\frac{p}{p_1^0}\right)_{CR}, \dot{m} \text{ rimane costante.}$$

Così succede invece a c ? Se utilizzo l'ugello con la condizione

$$\frac{p_2}{p_1^0} = \left(\frac{p}{p_1^0}\right)_{CR} \text{ la } c_{out} = c_s, \text{ cioè la velocità in uscita è sempre}$$

la velocità del suono; se lavoro a $\frac{p_2}{p_1^0} < \left(\frac{p}{p_1^0}\right)_{CR}$ ho la fase

di POST-EXPANSION in cui:

c rimane costante perché $c_c = \sqrt{\frac{2k}{k+1} \cdot \frac{p_1^0}{\rho_1^0}}$ non dipende dalle condizioni e vale e rimane pari a c_s

\dot{m} rimane costante

Quindi la post-expansion avviene fuori dall'ugello? ed è una espansione non isentropica da p_{out} a p_2 ? ✓

Ricorda che la curva di \dot{m} non è simmetrica.

Is it the ratio belonging to the choked non isentropic?

The two equations:

$$\dot{m} = A_{out} \sqrt{\frac{2k}{k-1} p_1^0 g_1^0 \left[\left(\frac{p_2}{p_1^0} \right)^{\frac{2}{k}} - \left(\frac{p_2}{p_1^0} \right)^{\frac{k+1}{k}} \right]} \quad (1)$$

$$\dot{m} = A_E \sqrt{p_1^0 g_1^0 k \cdot \left(\frac{2}{k+1} \right)^{\frac{k+1}{k-1}}} \quad (2)$$

hold for both points (1) and (2).

So:

$$A_E \sqrt{p_1^0 g_1^0 k \cdot \left(\frac{2}{k+1} \right)^{\frac{k+1}{k-1}}} = A_{out} \sqrt{\frac{2k}{k-1} p_1^0 g_1^0 \left[(x)^{\frac{2}{k}} - (x)^{\frac{k+1}{k}} \right]}$$

solving the equation we'd get $x = \left(\frac{p_2}{p_1^0} \right)_d$ but we miss values of A_E .

Another solution is:

① $p_2/p_1^0 = 0.11 \Rightarrow \dot{m}_{choked} = 0.13 \text{ kg/s}$

② $p_2/p_1^0 = 0.64 \Rightarrow \dot{m} = 0.232 \text{ kg/s}$

if we compare them we can understand that the point under study is in the CHOKED NON-ISOENTROPIC; otherwise if

$\dot{m}(p_2/p_1^0) < \dot{m}(0.11)$ we'd have been in the NON-CHOKED

ISOENTROPIC.

What about C_{out} ?

we cannot use $C = \sqrt{\frac{2k}{k-1} p_1^0 / g_1^0 \left[1 - \left(\frac{p_2}{p_1^0} \right)^{\frac{k-1}{k}} \right]}$

but

1) $\dot{m} = \text{const} = \rho_{out} \cdot A_{out} \cdot C_{out} = \frac{\rho_{out}}{RT_{out}} A_{out} \cdot C_{out}$ (we miss T_{out})

2) $dQ + dL_i = dh + dE_k$

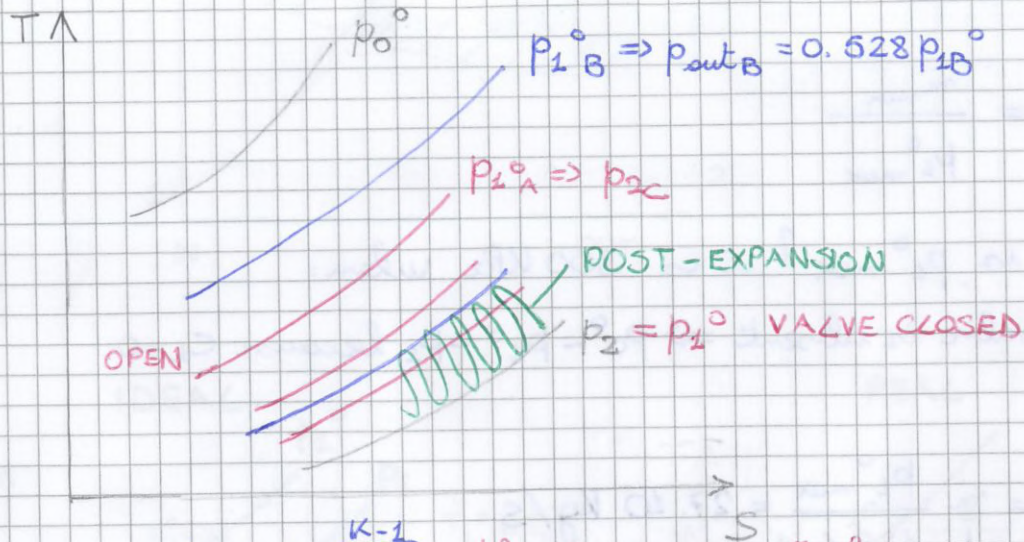
$dL_i = v dp + dE_k + dL_w$ (we do not use because dL_w is not known)

we use equation 2-1:

The max. possible velocity is:

$$c_{s_{out}} = \sqrt{kRT_{out}} \text{ got at the throat.}$$

Can I change the upstream conditions to affect the speed of sound at the outlet?



$$T_{out} = T_1^{\circ} \cdot \left(\frac{p_{out}}{p_1^{\circ}} \right)^{\frac{k-1}{k}}$$

\parallel
 T_0° const.

The idea is: can I have a greater velocity c_2 by varying p_1° ? I know $Ma=1$ at the throat \Rightarrow if I want to have a greater c_{out} I need to have a greater $c_{s_{out}}$ but $c_{s_{out}}$ depends on T_{out} which depends on $\frac{p_{out}}{p_1^{\circ}}$

$\therefore T_{out}$ does depend only on T_1° and not on the ratio

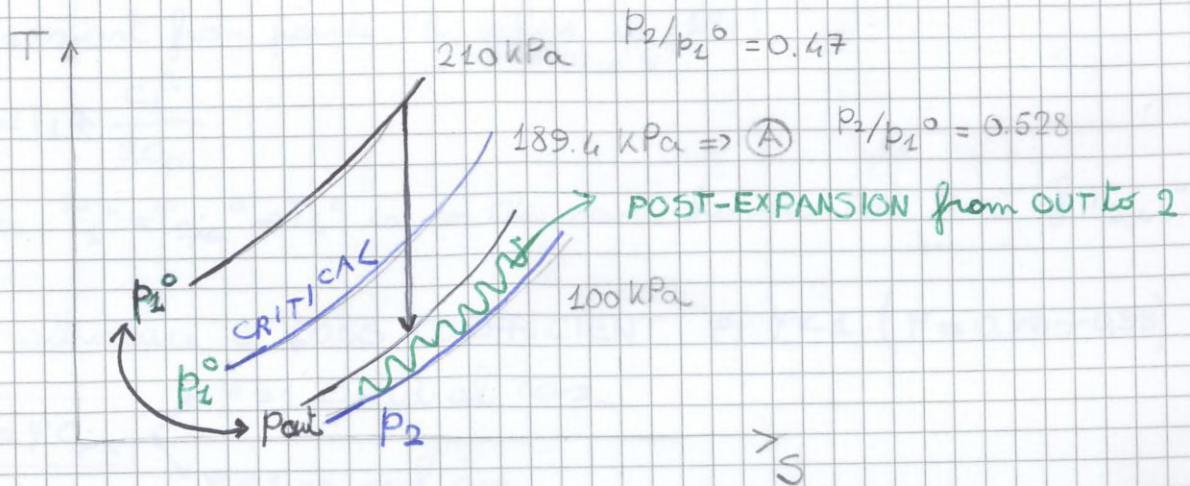
whose maximum value is 0.528

$$\left(\frac{p_{out}}{p_1^{\circ}} \right)^{\frac{k-1}{k}} \Rightarrow$$

$$T_{out} = 416.67 \text{ K}$$

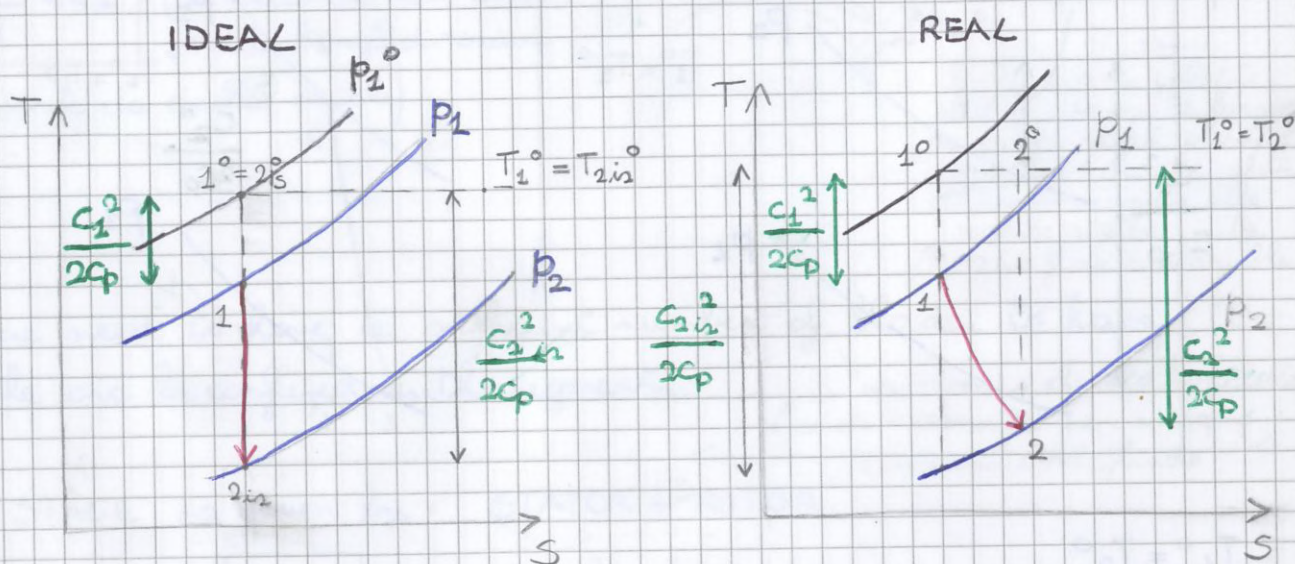
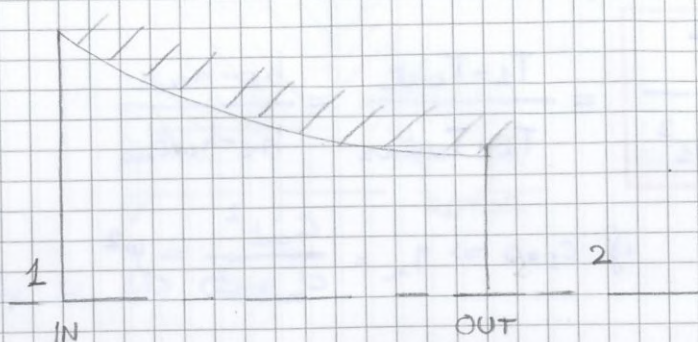
$$c_{out} = \sqrt{kRT_{out}} = 409.17 \frac{m}{s}$$

$$p_1^{\circ} = p_2 / 0.528 = 189.6 \text{ MPa}$$



NOZZLE EFFICIENCY

The evolutions we've considered in a nozzle have always been considered as IDEAL; but this is not the case:



$$\begin{aligned} dQ &= 0 \\ dL_w &= 0 \Rightarrow dS = 0 \Rightarrow S = \text{const.} \end{aligned}$$

$$\Rightarrow \begin{cases} T^\circ = \text{const.} \\ p^\circ = \text{const.} \end{cases}$$

$$\begin{aligned} dQ &= 0 \Rightarrow dS \neq 0 \\ dL_w &\neq 0 \end{aligned}$$

$$\Rightarrow \begin{cases} T^\circ = \text{const.} \\ p^\circ \neq \text{const.} \end{cases}$$

D.) Let's start from point 1; where is 1° ?

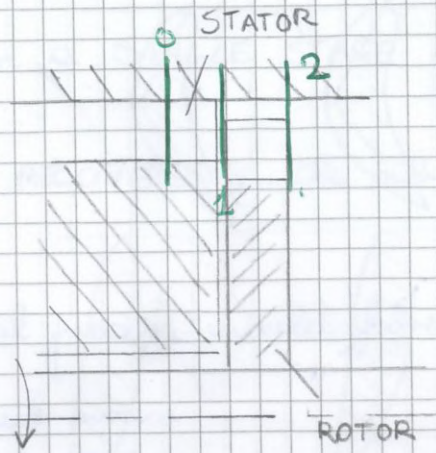
$$T_1^\circ = T_1 + \frac{c_1^2}{2c_p}$$

since $T_1^\circ = T_{2, \text{is}}^\circ \Rightarrow T_1^\circ$ is on the same horizontal line of $T_{2, \text{is}}^\circ$

R.) We introduce a LOSS COEFFICIENT φ ; $\varphi < 1$ ($\varphi = 0.96 \div 0.98$)

$$c_2 = \varphi c_{2, \text{is}} \begin{cases} \varphi = 1 \Rightarrow \text{ideal case} \\ \varphi < 1 \Rightarrow \text{real case} \end{cases}$$

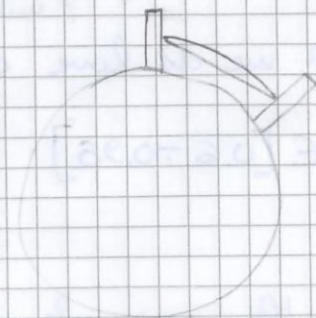
TURBINE STAGE



Is it really a 2D case?

It is if

- 1) $\frac{l}{d} \ll 1$ (in modo da non avere perdite lungo direzioni diverse da quella assiale)



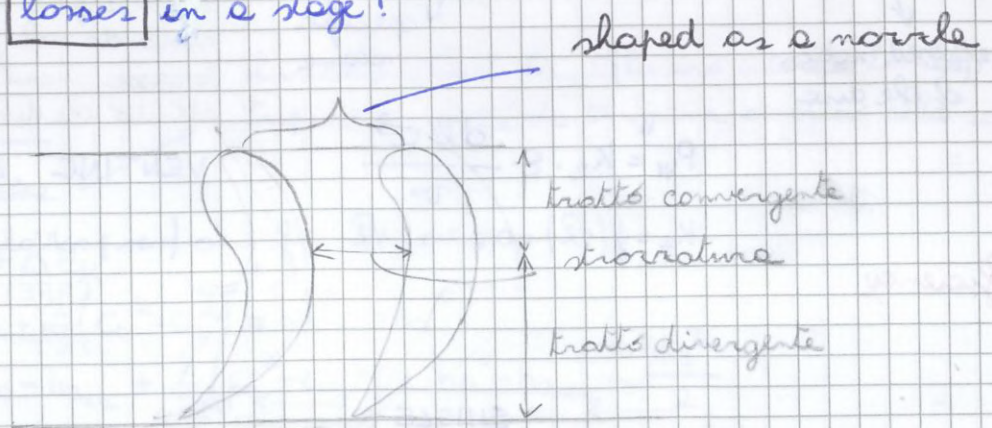
il numero di palette alto fa ritenere la lunghezza periferica del condotto delimitato da due palette consecutive uguale alla radice e alla punta
 $\uparrow \Rightarrow$ 2D flow is allowable

- 2) we need to have a sufficient number of blades to have the arc be confused with segment.

un numero elevato di palette è anche necessario per evitare l'inversione del fluido.

Q STAGE is given by: STATOR + ROTOR.

What are the losses in a stage?



- $C_1 = \varphi \cdot C_{1is}$, $\varphi = f(\text{Re, shape of blades, roughness...})$
 $\varphi \in [0.9 \div 0.98]$

Let us suppose we have the same final kinetic energy

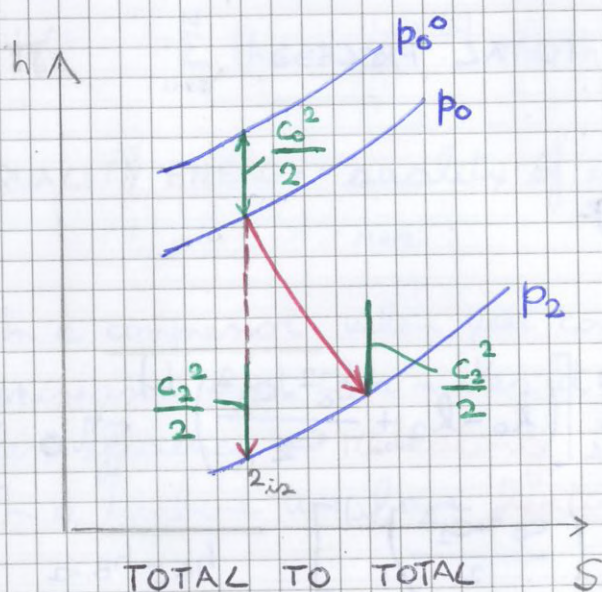
$\left(\frac{c_2^2}{2}\right)$: LOSS for a SINGLE STAGE

$\left(\frac{c_2^2}{2}\right)$: TO BE RECOVERED in the subsequent stage for a MULTI-STAGE

therefore an ideal process would have: $c_{2,is} = 0$

an ideal process
has NO LOSS

We define the TOTAL TO STATIC EFFICIENCY η_{TS} and the TOTAL TO TOTAL EFFICIENCY η_{TT}



MOTOR CONVENTION $\eta_{TT} = \frac{L_i}{L_{i,MEAL}}$

it is also called L_{i2} (lavoro interno limite), isentropico a parità di termine cinetici alle scorie

$L_i = \Delta h + \Delta E_k$

(0-2) $L_i = h_0 - h_2 + \frac{1}{2}(c_0^2 - c_2^2) = h_0^0 - h_2^0$

(0-2_{is}) $L_{i,ideal} = h_0 - h_{2,is} + \frac{1}{2}(c_0^2 - c_2^2) = h_0^0 - h_{2,is} - \frac{c_2^2}{2}$

$\eta_{TT} = \frac{h_0^0 - h_2^0}{h_0^0 - h_{2,is} - \frac{c_2^2}{2}}$

since the outlet velocity of one stage is the same as the inlet velocity of the subsequent one, we have:

$$\sum_{i=1}^N \frac{c_0^2 - c_2^2}{2} = \frac{c_A^2 - c_B^2}{2} \approx 0$$

So we get:

$$\eta_{\oplus} = \eta_{\oplus}^{(i)} \cdot \left[\frac{\sum_{i=1}^N (h_0 - h_{2, is})^{(i)}}{h_A - h_{B, is}} \right] = \eta_{\oplus}^{(i)} \cdot \underbrace{\prod_{i=1}^N 1.1}_{1.1}$$

it is always greater than 1 because

$$\sum_{i=1}^N (h_0 - h_{2, is})^{(i)} > h_A - h_{B, is}$$

because in isobaric nel diagramma h, s divergono

QUALITY ENERGY: quality of energy is greater at high temperature = res.

In a compressor when you compress a gas its temperature increases and this makes it expand and so the compression has less efficiency \Rightarrow **reheating**.

In a turbine we have **heating**

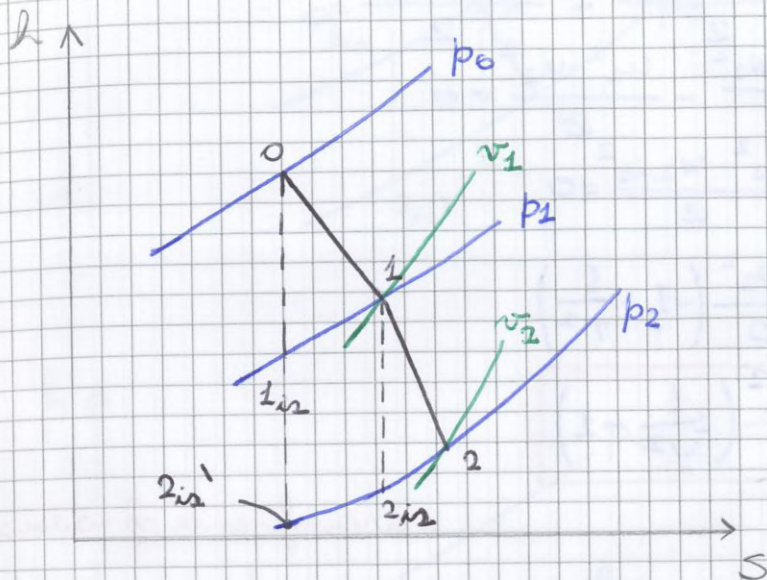
ACTION AND REACTION TURBINES

ACTION: no expansion in the impeller = the expansion drop occurs only in the distributor

REACTION: expansion is divided between the impeller and distributor

$$h_2 = h_{2, is} + \frac{\left(\frac{c_2}{\psi}\right)^2 - c_1^2}{2}$$

$$h_2 = h_{2, is} + \frac{c_1^2}{2} \left(\frac{1}{\psi^2} - 1 \right)$$



remark that point $2_{is}'$ is the same point which was called 2_{is} before

$$(1-2_{is}) \quad \cancel{\Delta} - Li = \Delta h + \Delta E_k + \cancel{\Delta E_g} + \Delta E_w$$

adiabatic compressible
 \Downarrow flow
 $= 0$ $= 0$

- FIXED OBSERVER (you do not have any centrifugal force term)

$$-Li = \Delta h + \Delta E_k$$

it is quite difficult to apply such an equation to the ideal case; so we prefer using a relative reference of frame

- MOVING FRAME OR REFERENCE

$$Li = 0, \Delta E_w \neq 0$$

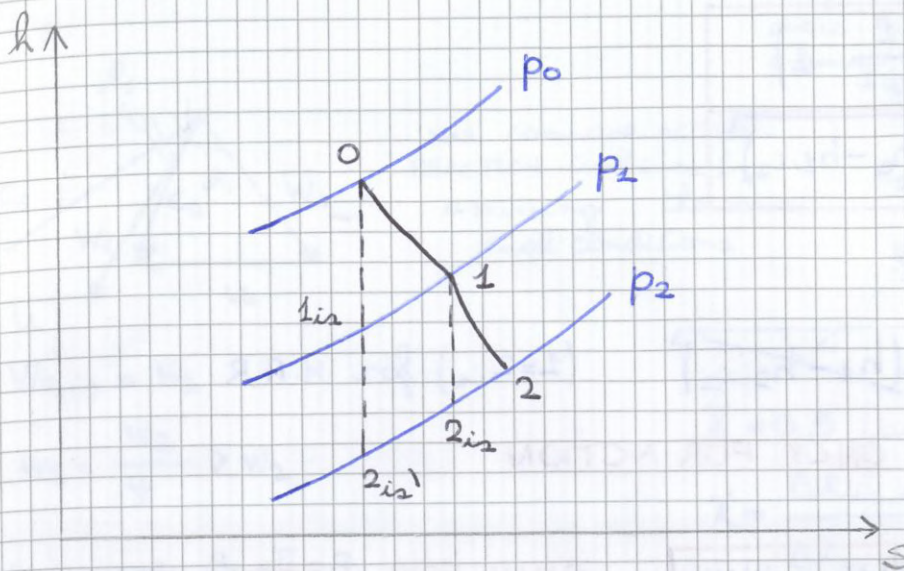
$$\Rightarrow \Delta E_k + \Delta E_w + \Delta h = 0$$

$$h_2 - h_{2, is} + \frac{w_1^2 - w_{2, is}^2}{2} - \underbrace{\left(\frac{u_2^2 - u_2^2}{2} \right)}_{\Delta E_w} = 0$$

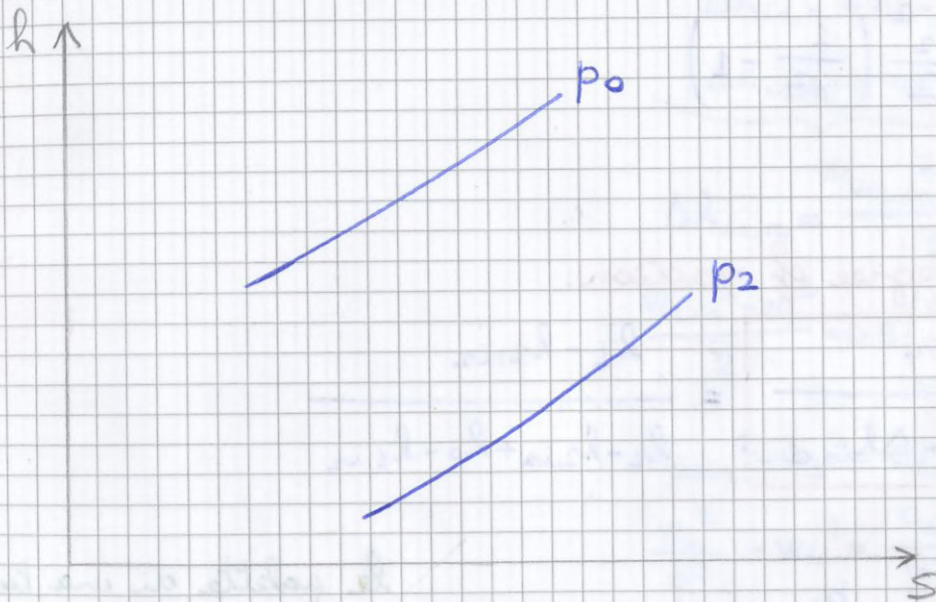
for a constant d blade $u_1 = u_2 \Rightarrow$

$$h_2 - h_{2, is} + \frac{w_1^2 - w_{2, is}^2}{2} = 0 \quad \text{IMPELLER}$$

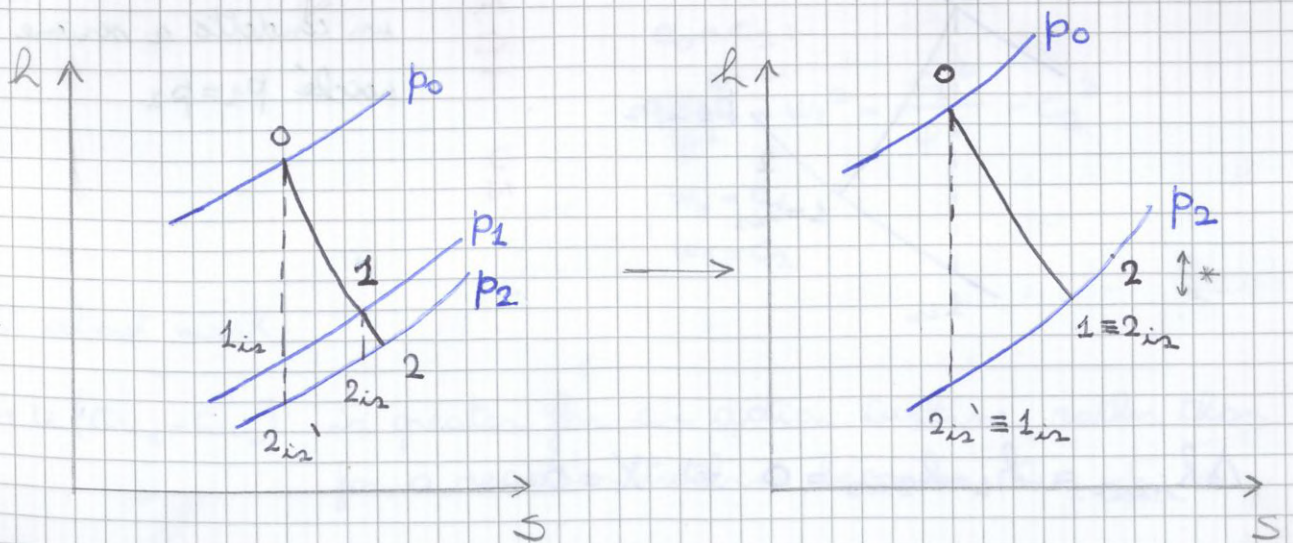
ACTION TURBINE



reaction turbine

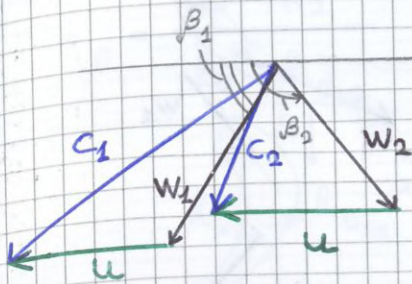


action turbine



you have an EXPANSION in the distributor from 0 to 1 and then an ISOBARIC PROCESS from 1 to 2

ACTION



$$W_{2, is} = W_1$$

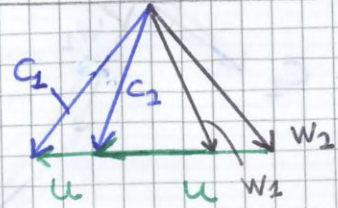
$$W_1 = \frac{W_2}{\psi} > W_2$$

we assume $\beta_2 = \pi - \beta_1$

REACTION

in questo caso ovviamente dobbiamo avere $l_1 \neq l_2$ perché se fosse $l_1 = l_2$ avremmo $\rho_1 = \rho_2$ che non è possibile

we compare ACTION-REACTION turbines by assuming the same final conditions



$$\chi = 0.5 \text{ (assumption)}$$

$$\chi = \frac{\Delta h_{is,r}}{\Delta h_{is,r} + \Delta h_{is,d}}$$

$$\Delta h_{is,r} = h_1 - h_{2, is} = \frac{W_{2, is}^2 - W_1^2}{2}$$

$$\Delta h_{is,d} = h_0 - h_{1, is} = \frac{C_{1, is}^2 - C_0^2}{2}$$

$$\Delta h_{is,r} = \frac{W_{2, is}^2 - W_1^2}{2} = 0.5 (\Delta h_{is,r} + \Delta h_{is,d})$$

$$\frac{W_{2, is}^2 - W_1^2}{2} = 0.5 \left(\frac{W_{2, is}^2 - W_1^2}{2} + \frac{C_{1, is}^2 - C_0^2}{2} \right)$$

$$W_{2, is}^2 - W_1^2 = C_{1, is}^2 - C_0^2$$

$$\frac{W_2^2}{\psi^2} - W_1^2 = \frac{C_1^2}{\psi^2} - C_0^2$$

we assume $\psi = \varphi$ and since

$$C_0 = C_2:$$

$$\frac{W_2^2}{\psi^2} - W_1^2 = \frac{C_1^2}{\psi^2} - C_2^2$$

unica
soluzione
possibile

$$\begin{cases} W_2 = C_1 \\ W_1 = C_2 \end{cases}$$

What about work:

$L_i = u(C_{u1} - C_{u2})$ is greater for an action turbine rather than for a reaction turbine because $C_{u1} \text{ action} > C_{u1} \text{ reaction}$

$C_{u2} \text{ reaction}$

↳ the TOTAL TO STATIC EFFICIENCY:

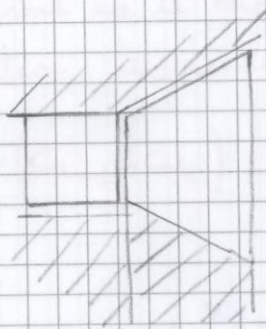
$$\eta_{\theta} = \frac{h_0^{\circ} - h_2^{\circ}}{h_0^{\circ} - h_{2is}^{\circ}} < \eta_{\oplus}$$

$$\downarrow$$

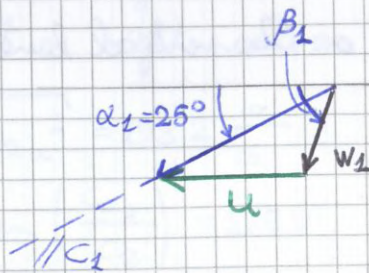
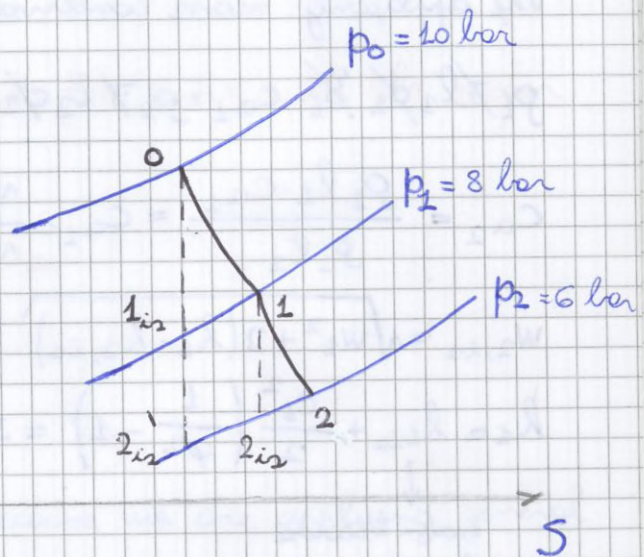
$$h_{2is}^{\circ} = h_{2is}^{\circ} \text{ because } c_{2is} = 0$$

Exercises

5.1)	p_0	p_2	p_2
	t_0	ψ	ψ
	c_0	α_1	l_2
	m	l_1	$d = \text{const}$
		u	



h



From a Mollier diagram we can read h_0 and h_{1s} :

$$h_0 = 3268 \text{ kJ/kg}$$

$$h_{1s} = 3204 \text{ kJ/kg}$$

This is a REACTION TURBINE, so:

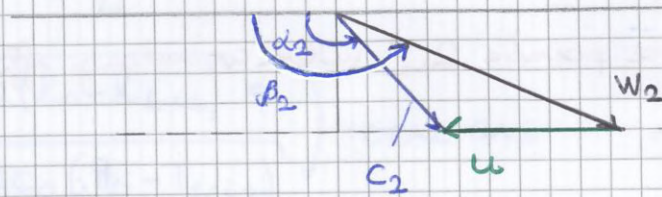
I cannot use OBVIOUSLY the ideal gas equation but we read v_1 and v_2 on the Mollier's diagram:

$$v_1 = 0.35 \text{ m}^3 \cdot \text{kg}^{-1}$$

$$v_2 = 0.45 \text{ m}^3 \cdot \text{kg}^{-1} \quad (\text{after calculating } h_2 = h_{2, \text{is}} + \frac{w_2^2}{2} \left(\frac{1}{\psi^2} - 1 \right) = 314.6 \frac{\text{kJ}}{\text{kg}})$$

$$\Rightarrow Ca_2 = Ca_1 \cdot \frac{v_2 l_1}{v_1 l_2} = 160.6 \text{ m} \cdot \text{s}^{-1}$$

We have 3 pieces of information; hence:



A turbine is a MOTOR MACHINE; so the work with the motor convention has to be positive:

$$L_i = u(c_{u1} - c_{u2}) > 0 \Rightarrow c_{u1} > c_{u2}$$

So:

$$\beta_2 = \pi - \arcsin \left(\frac{w_{2u}}{w_2} \right) = 156.22^\circ$$

$$c_{2u} = w_2 \cos \beta_2 + u = -116.1 \frac{\text{m}}{\text{s}} \quad (\text{because we are applying general equations regardless whether we know the position of } c_2 \text{ in the left or right portion of the vertical line})$$

$$c_2 = \sqrt{c_{2a}^2 + c_{2u}^2} = 198.2 \frac{\text{m}}{\text{s}}$$

$$\alpha_2 = \pi - \arcsin \left(\frac{c_{2a}}{c_2} \right) = 125.9^\circ$$

The power is given by:

$$\dot{P}_i = \dot{m} L_i$$

$$L_i = u(c_{u1} - c_{u2}) = 108.73 \frac{\text{kJ}}{\text{kg}}$$

$$\dot{m} = \psi_1 \pi d_1 l_1 \cdot Ca_1 \cdot \frac{1}{v_1}, \quad \psi_1 = 0.98$$

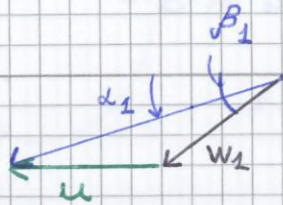
$$u = \pi d_1 n$$

The internal power is:

$$P_i = \dot{m} L_i =$$

$$= \zeta_1 d_1 l_1 \cdot \pi c_{a1} \cdot \frac{1}{v_1} \cdot u (c_{u1} - c_{u2})$$

\downarrow ideal gas \downarrow velocity components



$$c_{1,is} = \sqrt{c_0^2 + 2(h_0 - h_{1,is})} = \sqrt{c_0^2 + 2c_p(T_0 - T_{1,is})}$$

IDEAL GAS

$$\left\{ \frac{R}{K} \Rightarrow c_p = c_v + R = \frac{c_p}{K} + R \Rightarrow c_p \left(1 - \frac{1}{K}\right) = R \Rightarrow c_p = \frac{R}{1 - \frac{1}{K}} = 1008 \frac{\text{J}}{\text{kg} \cdot \text{K}}$$

$$T_{1,is} = T_0 \cdot \left(\frac{p_1}{p_0}\right)^{\frac{K-1}{K}} = 555.68 \text{ K} \rightarrow \text{remark } p v^K = \text{const is for ISOENTROPIC, not just for adiabatic}$$

$$c_{1,is} = \sqrt{c_0^2 + 2c_p(T_0 - T_{1,is})} = 620.7 \text{ m} \cdot \text{s}^{-1}$$

$$c_1 = \varphi \cdot c_{1,is} = 603.9 \text{ m} \cdot \text{s}^{-1}$$

$$h_1 = h_{1,is} + \frac{c_1^2}{2} \left(\frac{1}{\varphi^2} - 1\right)$$

$$T_1 = T_{1,is} + \frac{c_1^2}{2c_p} \left(\frac{1}{\varphi^2} - 1\right) = 562.7 \text{ K}$$

$$v_1 = \frac{RT_1}{p} \Rightarrow \dot{m} = \zeta_1 \cdot \pi l_1 d_1 c_1 \sin \alpha_1 \cdot \frac{p_1}{RT_1} = 38.6 \text{ kg} \cdot \text{s}^{-1}$$

Then:

$$u = \pi \cdot \frac{\dot{m}}{60} d = 157.1 \text{ m} \cdot \text{s}^{-1}$$

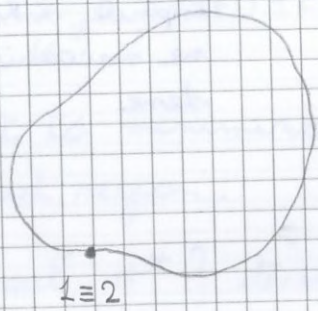
$$w_{1a} = c_1 \sin \alpha_1 = 138.1 \text{ m} \cdot \text{s}^{-1}$$

$$w_{1u} = c_1 \cdot \cos \alpha_1 - u = 222.4 \text{ m} \cdot \text{s}^{-1}$$

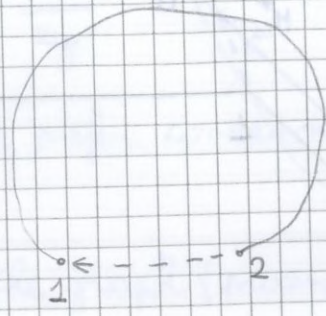
$$w_1 = \sqrt{w_{1a}^2 + w_{1u}^2} = 261.8 \text{ m} \cdot \text{s}^{-1}$$

STEAM PLANTS

A CYCLE is a transformation which brings the system from an initial to a final condition which are equal.

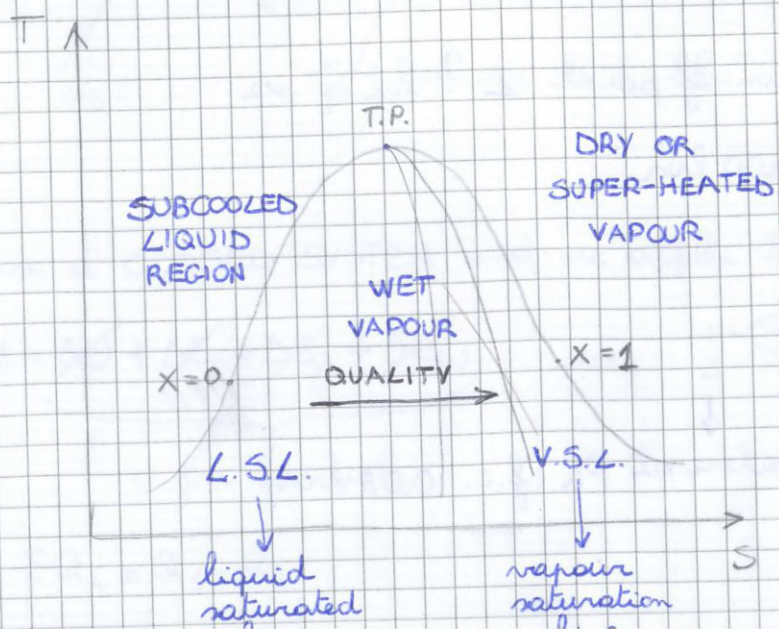
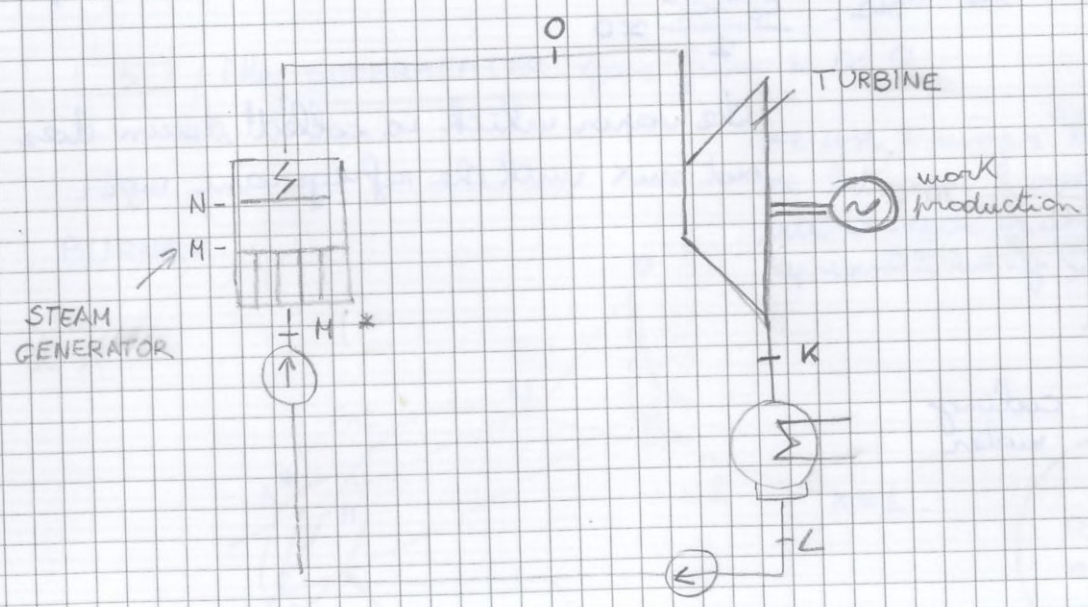


same fluid performing the transformation
CYCLE



REFERENCE CYCLE
it is not the same fluid performing the transformation

RANKINE-HIRN CYCLE



$$L_i = \int v dp + \Delta E_k + L_w \quad (\Delta E_g = \Delta E_w = 0)$$

perform the integration and solving we get a much higher value

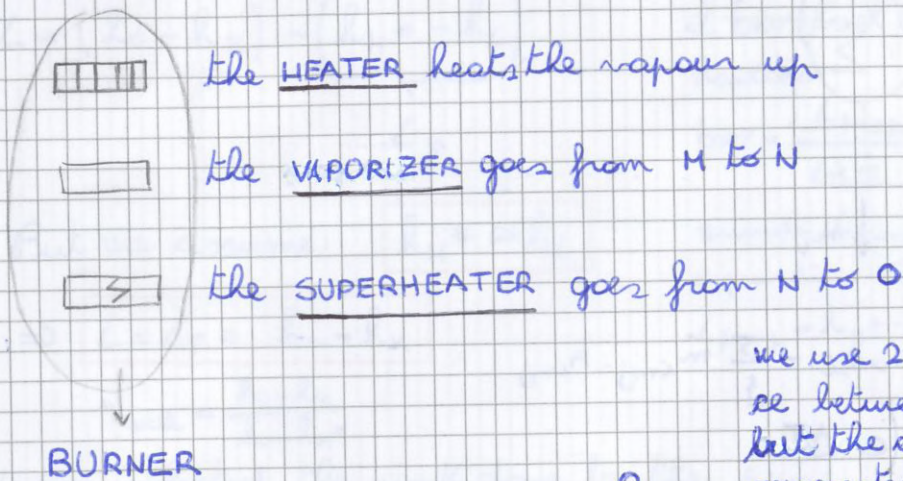
$$L_i = \frac{\Delta p}{\rho} + L_w, \quad \text{supposing } L_w = 10\% L_i$$

$$L_i = \frac{(100 - 0.05) \cdot 10^5}{10^3} + 0.1 L_i \Rightarrow L_i \approx 11 \frac{\text{kJ}}{\text{kg}}$$

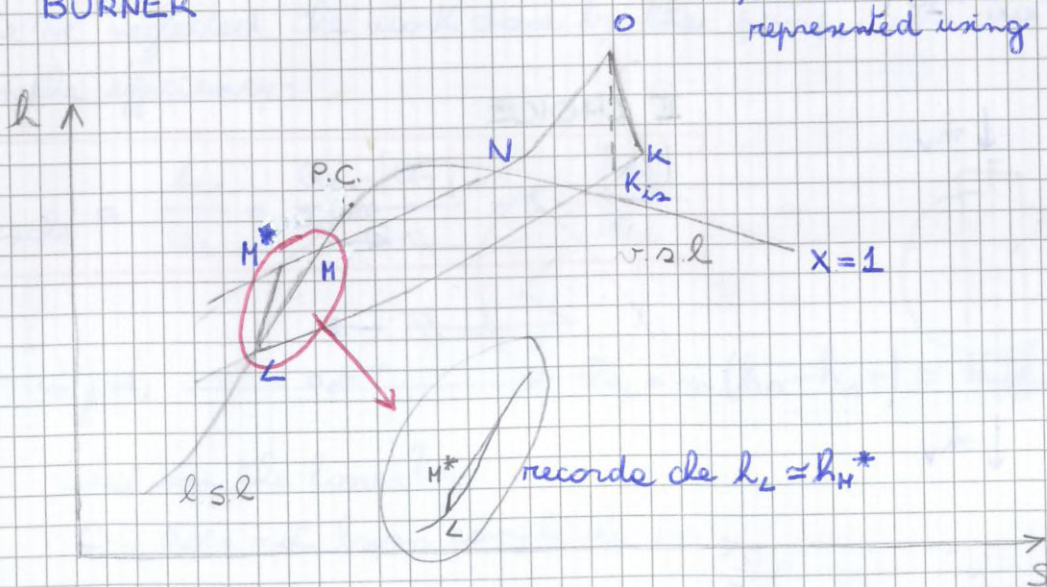
We want to minimize $L_i \Rightarrow$ so we prefer condensing up to the liquid region.

What about H^* ? it is shown in the graph (process has $L_w \neq 0$)

Then



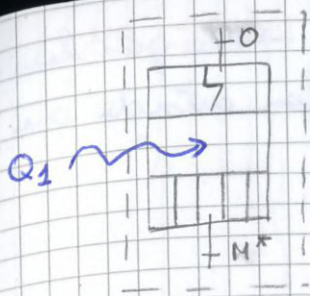
we use 2 pumps because of distance between burner and condenser but the cycle is conventionally represented using just 1 pump.



We use a CLOSED SYSTEM and we apply 1st l. of T.

$$Q - L = \underbrace{\Delta U + \Delta E_k + \Delta E_g + \Delta E_w}_0 \text{ for a cycle}$$

$$L = \sum_i Q_i = Q_1 - Q_2$$



$$Q_1 = \Delta h = h_0 - h_{H^*}$$

Then

$$L = Q_1 - Q_2 =$$

$$= (h_0 - h_{H^*}) - (h_K - h_L) = (h_0 - h_K) + (h_L - h_{H^*})$$

$$L = (h_0 - h_K) - \underbrace{(h_{H^*} - h_L)}_{L_p}$$

But we assume: $h_{H^*} \approx h_L$

$$\Rightarrow L = L_T = h_0 - h_K$$

$$\eta_{\text{cycle}} = \frac{h_0 - h_K}{h_0 - h_{H^*}}$$

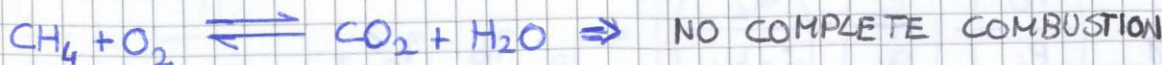
We've neglected the work done by the pump; now we take them in the efficiency:

$$\eta_{\text{cycle}} = \frac{L_T}{Q_1} = \frac{Q_1 - |Q_2|}{Q_1} = 1 - \frac{|Q_2|}{Q_1}$$

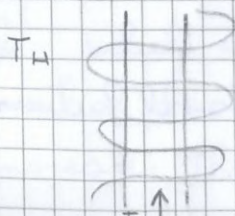
$$\dot{m}_f H_i \longrightarrow \dot{Q}_1 = \dot{m}(h_0 - h_{H^*}) \approx \dot{m}(h_0 - h_L)$$

what are the losses?

- CH_4 does not burn completely in:



- losses due to heat exchange through a finite ΔT



$$T_H - T_L \neq dT$$

entropy increases because for the system heat is absorbed through a finite difference in temperature

08/04