



Corso Luigi Einaudi, 55 - Torino

Appunti universitari

Tesi di laurea

Cartoleria e cancelleria

Stampa file e fotocopie

Print on demand

Rilegature

NUMERO : 92

DATA : 28/04/2011

A P P U N T I

STUDENTE : Pignato

MATERIA : Analisi 2
Prof. Codegone

Il presente lavoro nasce dall'impegno dell'autore ed è distribuito in accordo con il Centro Appunti.

Tutti i diritti sono riservati. È vietata qualsiasi riproduzione, copia totale o parziale, dei contenuti inseriti nel presente volume, ivi inclusa la memorizzazione, rielaborazione, diffusione o distribuzione dei contenuti stessi mediante qualunque supporto magnetico o cartaceo, piattaforma tecnologica o rete telematica, senza previa autorizzazione scritta dell'autore.

ATTENZIONE: QUESTI APPUNTI SONO FATTI DA STUDENTIE NON SONO STATI VISIONATI DAL DOCENTE.
IL NOME DEL PROFESSORE, SERVE SOLO PER IDENTIFICARE IL CORSO.

RIPASSO

Studio di funzione:

$$w = x^2 - 4z \log x + xy^2z$$

$$1) \text{dom}(w) = \{x > 0, y, z \in \mathbb{R}\} \quad \text{DOMINIO}$$

$$2) \nabla w = \left(2x - \frac{4z}{x} + y^2z, 2xyz, -4\log x + xy^2z \right) \quad \text{GRADIENTE}$$

$$\frac{\partial w}{\partial x} \quad \frac{\partial w}{\partial y} \quad \frac{\partial w}{\partial z}$$

3) MATRICE HESSIANA

$$H = \begin{bmatrix} 2 + \frac{4z}{x^2} & 2yz & -\frac{4}{x} + y^2 \\ 2yz & 2xz & 2xy \\ -\frac{4}{x} + y^2 & 2xy & 0 \end{bmatrix}$$

DERIVATA DIREZIONALE

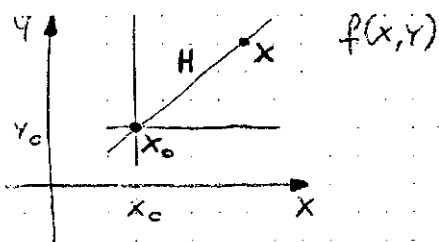
$$f(x, y, z) \quad \vec{V} = (v_1, v_2, v_3) \quad \|\vec{V}\| = 1$$

versore

$$\text{dati } x_0 = (x_0, y_0, z_0)$$

$$x = (x_0 + hv_1, y_0 + hv_2, z_0 + hv_3)$$

$$\frac{df}{dv} = \lim_{h \rightarrow 0} \frac{1}{h} \left\{ f(x_0 + hv_1, y_0 + hv_2, z_0 + hv_3) - f(x_0, y_0, z_0) \right\}$$



$$\lim_{\vec{H} \rightarrow (0,0,0)} \frac{w(\vec{x}_0 + \vec{H}) - w(\vec{x}_0)}{\|\vec{H}\|}$$

$\|\vec{H}\| \rightarrow 0$

w è DIFFERENZIABILE in x_0 se:

$$\lim_{\|\vec{H}\| \rightarrow 0} \frac{w(x_0 + \vec{H}) - w(x_0) - \nabla w(x_0) \cdot \vec{H}}{\|\vec{H}\|} = 0$$

$$\text{cioè se } w(x_0 + \vec{H}) = w(x_0) + \nabla w(x_0) \cdot \vec{H} + o(\|\vec{H}\|)$$

es. di funzione vettoriale

CURVA GEOMETRICA

$$\gamma(t) = \begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \quad \mathbb{R} \rightarrow \mathbb{R}^3$$

$$\begin{cases} x = 2 \cos t \\ y = 2 \sin t \\ z = 3t \end{cases} \quad t \in (0, 2\pi)$$

$$G(u, v) = \begin{cases} x = x(u, v) \\ y = y(u, v) \\ z = z(u, v) \end{cases} \quad \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

• COMPOSIZIONE di FUNZIONE

$$G(Y) = \begin{cases} z_1 = g_1(y_1, \dots, y_m) \\ \vdots \\ z_q = g_q(y_1, \dots, y_m) \end{cases}$$

$$y_1 = f_1$$

$$\vdots$$

$$y_m = f_m$$

↓

$$(G \circ F)(X) \quad \mathbb{R}^n \rightarrow \mathbb{R}^q$$

per esempio

$$f(x, y, z) = f(x(t), y(t), z(t)) \quad (f \circ \gamma)(t) \quad \mathbb{R} \rightarrow \mathbb{R}$$

↓

$$J_G(Y) = \begin{bmatrix} \frac{\partial g_1}{\partial y_1} & \frac{\partial g_1}{\partial y_2} & \dots & \frac{\partial g_1}{\partial y_m} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial g_q}{\partial y_1} & \frac{\partial g_q}{\partial y_2} & \dots & \frac{\partial g_q}{\partial y_m} \end{bmatrix}$$

↓

$$J_{G \circ F}(X) = J_G(X) \times J_F(X) \quad \text{prodotto righe per colonne}$$

REGOLA di DERIVAZIONE per un CAMPO SCALARE

$$J_f(X) = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{bmatrix}$$

$$J_\gamma(t) = \begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix}$$

$$J_{(f \circ \gamma)}(t) = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt} = \frac{d(f \circ \gamma)}{dt}$$

es. $MASSA = \int_a^b \rho(x(t), y(t), z(t)) \cdot \| \gamma'(t) \| dt$

$\rho(P)$
DENSITÀ

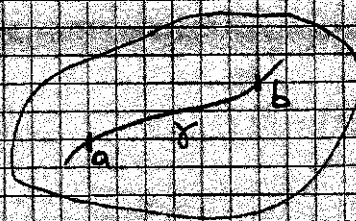
BARICENTRO $X_G = \frac{\int_a^b x(t) \rho(t) \cdot \| \gamma'(t) \| dt}{\int_a^b \rho(t) \cdot \| \gamma'(t) \| dt}$ massa

$G = \frac{\int_a^b P \rho(P) \cdot \| \gamma'(t) \| dt}{\int_a^b \rho(P) \cdot \| \gamma'(t) \| dt}$ se il filo è omogeneo $= \frac{\int_a^b P \| \gamma'(t) \| dt}{\int_a^b \| \gamma'(t) \| dt}$

● INTEGRALE DI LINEA

$\gamma(t) = (x(t), y(t), z(t)) \quad t \in [a, b]$

$F(P) = f_1(P) \hat{i} + f_2(P) \hat{j} + f_3(P) \hat{k}$



$\int F(P) dP \quad dP = (dx, dy, dz)$



$\int_{\gamma(a,b)} F(P) dP = \int_{\gamma(a,b)} [f_1(P) dx + f_2(P) dy + f_3(P) dz] =$

$= \int_{\gamma(a,b)} \left[f_1(x(t), y(t), z(t)) \frac{dx}{dt} dt + f_2(x(t), y(t), z(t)) \frac{dy}{dt} dt + f_3(x(t), y(t), z(t)) \frac{dz}{dt} dt \right] =$

L'integrale di linea è orientato, e secondo si determinano gli estremi di integrazione

es. 1 $F(P) = \frac{x}{x^2+y^2} \hat{i} + \frac{y}{x^2+y^2} \hat{j} + \hat{k}$

$\gamma(t) = (\cos t, \sin t, t) = \cos t \hat{i} + \sin t \hat{j} + t \hat{k} \quad t \in (0, 3\pi)$

ELICA $\rightarrow$

$$F(P) = \frac{\partial g(P)}{\partial x} \hat{i} + \frac{\partial g(P)}{\partial y} \hat{j} + \frac{\partial g(P)}{\partial z} \hat{k} = P_1(P) \hat{i} + P_2(P) \hat{j} + P_3(P) \hat{k}$$

$g(P)$ = FUNZIONE POTENZIALE DEL CAMPO $F(P)$

$$\int_{\gamma_1} F(P) dP = \int_{\gamma_2} F(P) dP \quad \forall \gamma(A,B)$$

Il LAVORO in un campo conservativo non dipende dal percorso ma solo dagli estremi del percorso

Dim. Hp: $\exists g(P) / F(P) = \text{grad } g(P)$

D = dom $F(P)$ è aperto connesso

$F(P)$ è continua

$$Th: \int_{\gamma} F(P) dP = g(B) - g(A)$$

$$\int_{\gamma(A,B)} F(P) dP \quad \gamma(t) = \begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \quad t \in [t_A, t_B]$$

$$= \int \left[P_1(x(t), y(t), z(t)) \frac{dx}{dt} dt + P_2(x(t), y(t), z(t)) \frac{dy}{dt} dt + P_3(x(t), y(t), z(t)) \frac{dz}{dt} dt \right]$$

$$= \int_{t_A}^{t_B} \left[\frac{\partial g(x(t), y(t), z(t))}{\partial x} \frac{dx}{dt} + \frac{\partial g(P(t))}{\partial y} \frac{dy}{dt} + \frac{\partial g(P(t))}{\partial z} \frac{dz}{dt} \right] dt =$$

$$= \int_{t_A}^{t_B} \frac{d g(P \circ \gamma(t))}{dt} dt = \left[g(P \circ \gamma(t)) \right]_{t_A}^{t_B} = g(B) - g(A)$$

$$\text{es } L_{(0,B)} = \int_0^B F \cdot dP = [xyz]_0^B = \frac{3\sqrt{3}}{27} - 0 = \frac{\sqrt{3}}{9}$$

$$F(P) = yz \hat{i} + xz \hat{j} + xy \hat{k} \quad B = \left(-\frac{\sqrt{3}}{3}, -\frac{\sqrt{3}}{3}, \frac{\sqrt{3}}{3} \right)$$

$$g(P) = xyz + C$$

quali altre POTENZIALI sarebbero andati bene?

Dim. 2) $\Rightarrow$ 1)

$$H_p: \int_{\gamma_1} F(P) dP = \int_{\gamma_2} F(P) dP$$

$$Th: \exists g(P) / F(P) = \text{grad } g(P)$$

$$g(P) = \int_{A(a,b,c)}^{P(x,y,z)} F(P) dP \rightarrow \frac{\partial g(P)}{\partial x} = f_1(x,y,z), \quad \frac{\partial g(P)}{\partial y} = f_2(x,y,z), \quad \frac{\partial g(P)}{\partial z} = f_3(x,y,z)$$

ne dimostro solo uno:

$$\lim_{h \rightarrow 0} \frac{1}{h} (g(x+h, y, z) - g(x, y, z)) = \lim_{h \rightarrow 0} \frac{1}{h} \left[\int_A^{(P+\Delta P)(x+h, y, z)} F(P) dP - \int_A^{P(x, y, z)} F(P) dP \right] =$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} \left[\int_{\gamma(A,P)} F(P) dP + \int_P^{P+\Delta P} F(P) dP - \int_{\gamma(A,P)} F(P) dP \right] =$$

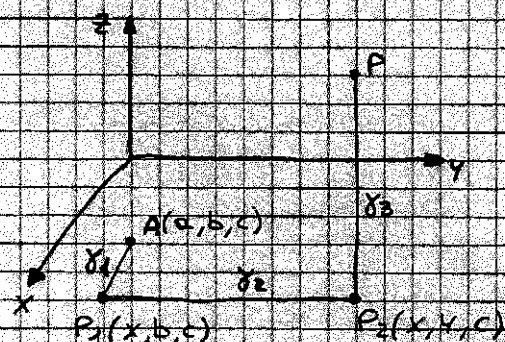
$$(P, P+\Delta P) = \begin{cases} x = x+h \\ y = y \\ z = z \end{cases} \quad \downarrow \quad = \lim_{h \rightarrow 0} \frac{1}{h} \int_0^h f_1(x+t, y, z) dt =$$

$$= \lim_{h \rightarrow 0} \frac{1}{h} \int_0^h f_1(x+\theta h, y, z) d(\theta h) \quad 0 \leq \theta \leq 1 \rightarrow = f_1(x, y, z)$$

per il TEOREMA DI L'HÔPITAL

la curva che unisce A - P DEVE $\in \mathbb{D}$

$$g(P) = \int_{A(a,b,c)}^{P(x,y,z)} F(P) dP$$



$$\gamma_1(t) = (t, b, c) \quad \gamma'_1 = (1, 0, 0)$$

$$\gamma_2(t) = (x, t, c) \quad \gamma'_2 = (0, 1, 0)$$

$$\gamma_3(t) = (x, y, t) \quad \gamma'_3 = (0, 0, 1)$$

$$g(P) = \int_{\gamma_1} + \int_{\gamma_2} + \int_{\gamma_3} = \int_a^x f_1(t, b, c) dt + \int_b^y f_2(x, t, c) dt + \int_c^z f_3(x, y, t) dt$$

CALCOLO del POTENZIALE

Dim.

$$\text{rot}(F(P)) = \left(\frac{\partial}{\partial y} \left(\frac{\partial g(P)}{\partial z} \right) - \frac{\partial}{\partial z} \left(\frac{\partial g(P)}{\partial y} \right) \right) \hat{i} + \left(\frac{\partial^2 g(P)}{\partial z \partial x} - \frac{\partial^2 g(P)}{\partial x \partial z} \right) \hat{j} + \left(\frac{\partial^2 g(P)}{\partial x \partial y} - \frac{\partial^2 g(P)}{\partial y \partial x} \right) \hat{k}$$

per il TEOREMA di SCHWARZ (inversione delle derivate):

$$\frac{\partial^2 g(P)}{\partial x \partial y} = \frac{\partial^2 g(P)}{\partial y \partial x} \rightarrow \text{rot}(F(P)) = (0, 0, 0) = \vec{0}$$

adesso devo verificare che, se $\text{rot} = \vec{0} \iff F(P) = \text{grad } g(P)$

$$\begin{aligned} \text{rot}(F(P)) &= \text{rot} \{ f_1(x, y) \hat{i} + f_2(x, y) \hat{j} + 0 \hat{k} \} = \\ &= \left[\frac{\partial}{\partial x} \left(\frac{x}{x^2+y^2} \right) - \frac{\partial}{\partial y} \left(-\frac{y}{x^2+y^2} \right) \right] \hat{k} = \left[\frac{x^2+y^2-2x^2}{(x^2+y^2)^2} + \frac{x^2+y^2-2y^2}{(x^2+y^2)^2} \right] \hat{k} = \frac{0}{(x^2+y^2)^2} \hat{k} = \vec{0} \end{aligned}$$



$$F(P) = \text{grad } g(P) \iff \begin{cases} \text{rot}(F(P)) = \vec{0} \\ \text{dom } F(P) \text{ connesso in } \mathbb{R}^3 \\ \text{semplicemente connesso} \\ \text{(senza buchi) in } \mathbb{R}^2 \end{cases}$$

• FUNZIONI IMPLICITE/ESPLICITE

$$g(x_1, x_2, \dots, x_n) = 0 \quad \text{implicita}$$

$$x_i = \varphi(x_1, x_2, \dots, x_n) \quad \text{esplicita}$$

• TEOREMA di DINI

$$g(x_1, x_2, \dots, x_n) = 0 \quad \mathbb{R}^n \rightarrow \mathbb{R}$$

$$H_P: g(x) = g(x_1, x_2, \dots, x_n) = 0$$

$$Th: x_i = f_i(x_1, x_2, \dots, x_n)$$

$$x_0 = (x_1^0, x_2^0, \dots, x_n^0) \rightarrow \begin{cases} g(x_0) = 0 \\ \frac{\partial g(x_0)}{\partial x_i} \neq 0 \end{cases}$$

ES 3) CAMPI e INTEGRALI di LINEA

$$\vec{f}(x,y) = \begin{pmatrix} xy \\ x^2+y^2 \end{pmatrix}$$

$$\int_{\gamma} \vec{f}(x,y) \cdot \vec{\tau} = \int_a^b f(\gamma(t)) \cdot \gamma'(t) dt$$

VERSO
TANGENTE

$$\vec{\tau} = \frac{\gamma'(t)}{\|\gamma'(t)\|}$$

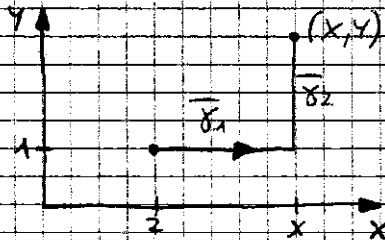
Calcolo del POTENZIALE:

$$\vec{f}(x,y) = \begin{pmatrix} 2xy \\ x^2+y^2 \end{pmatrix}$$

$$\frac{\partial f_2}{\partial x} = 2x$$

$$\frac{\partial f_1}{\partial y} = 2x$$

$$\text{rot } \vec{f} = 0$$



$$\gamma_1(t) = \begin{pmatrix} t \\ 1 \end{pmatrix} \quad 2 \leq t \leq x$$

$$\gamma_1'(t) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\gamma_2(t) = \begin{pmatrix} x \\ t \end{pmatrix} \quad 1 \leq t \leq y$$

$$\gamma_2'(t) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\int_2^x \begin{pmatrix} 2 \cdot t \cdot 1 \\ t^2 + 1^2 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} dt + \int_1^y \begin{pmatrix} 2x \cdot t \\ x^2 + t^2 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix} dt = \int_2^x 2t dt + \int_1^y (x^2 + t^2) dt =$$

$$= \left[t^2 \right]_2^x + \left[x^2 t + \frac{t^3}{3} \right]_1^y = x^2 - 4 + x^2 y + \frac{y^3}{3} - x^2 - \frac{1}{3}$$

$$\downarrow$$

$$g(x,y) = x^2 y + \frac{y^3}{3} + C$$

POTENZIALE

TEOREMA del DINI

$$g(x_1, x_2, \dots, x_n) = 0 \quad \mathbb{R}^n \rightarrow \mathbb{R}$$

$$H_p: x_0 = (x_1^0, x_2^0, \dots, x_n^0)$$

$$g(x_0) = 0$$

$$\frac{\partial g(x_0)}{\partial x_i} \neq 0$$

$$Th: x_i = f_i(x_1, x_2, \dots, x_n) \quad \mathbb{R}^{n-1} \rightarrow \mathbb{R}$$

COROLLARIO

$$1) \text{ c.s. in } x_0, \text{ sia } x_j = f_j(x_1, x_2, \dots, x_n)$$

↓

$$\nabla g(x_0) \neq (0, 0, 0)$$

$$2) \frac{\partial f_j}{\partial x_i} = - \frac{\frac{\partial g(x)}{\partial x_j}}{\frac{\partial g(x)}{\partial x_i}} \quad j \neq i$$

es. $y^2 + xz + z^2 - e^z - 4 = 0$

$$\frac{\partial g}{\partial z} = x + 2z - e^z \quad x_0 \begin{cases} x=0 \\ y=\sqrt{5} \\ z=0 \end{cases}$$

non so ricavare $z = f(x, y)$

però so ricavare $\frac{\partial f}{\partial x}$ e $\frac{\partial f}{\partial y}$

↓

$$\nabla g(x) = (z, 2y, x + 2z - e^z)$$

$$\frac{\partial f(x, y)}{\partial x} = - \frac{z}{x + 2z - e^z}$$

$$\frac{\partial f(x, y)}{\partial y} = - \frac{2y}{x + 2z - e^z}$$

date le premesse di prima passo esplicitate:

$$\begin{cases} x_1 = \varphi(x_{m+1}, \dots, x_n) \\ x_2 = \varphi(x_{m+1}, \dots, x_n) \\ \vdots \\ x_m = \varphi_m(x_{m+1}, \dots, x_n) \end{cases}$$

derivo e pongo = 0

cerco max e min liberi di $(w \circ \phi)$

$$\phi(x_{m+1}, \dots, x_n)$$

es. 1 $w = x^2 + y^2 + z^2$

$$\mathbb{R}^3 \rightarrow \mathbb{R}$$

$$x + y + z + 1 = 0 \rightarrow z = -1 - x - y$$

$$(w \circ z)(x, y) = x^2 + y^2 + (-1 - x - y)^2$$

$$\frac{\partial (w \circ z)}{\partial x} = 2x - 2(-1 - x - y) = 4x + 2y + 2 = 0$$

$$\frac{\partial (w \circ z)}{\partial y} = 2x + 4y + 2 = 0$$

↓ pongo a sistema

$$y = x = -\frac{1}{3} \quad P\left(-\frac{1}{3}, -\frac{1}{3}\right)$$

$$H_{(w \circ z)} = \begin{bmatrix} 4 & 2 \\ 2 & 4 \end{bmatrix} \rightarrow \det(H - \lambda I) = 0$$

$$\begin{aligned} \lambda_1 &= 6 \rightarrow P \text{ è MIN} \\ \lambda_2 &= 2 \end{aligned}$$

• MAX e MIN per funzioni a più variabili

guardando gli autovalori
e posso avere 3 casi:

1) tutti POSITIVI $\rightarrow$ MINIMO

2) tutti NEGATIVI $\rightarrow$ MASSIMO

3) + e - $\rightarrow$ FLESSO

$$\begin{cases} \frac{\partial w}{\partial x} \frac{\partial g}{\partial z} = \frac{\partial w}{\partial z} \frac{\partial g}{\partial x} \\ \frac{\partial w}{\partial y} \frac{\partial g}{\partial z} = \frac{\partial w}{\partial z} \frac{\partial g}{\partial y} \end{cases} \rightarrow \begin{cases} \frac{\partial w}{\partial x} = \lambda \frac{\partial g}{\partial x} \\ \frac{\partial w}{\partial y} = \lambda \frac{\partial g}{\partial y} \\ \frac{\partial w}{\partial z} = \lambda \frac{\partial g}{\partial z} \end{cases} \quad \nabla F = \lambda \nabla g$$

$$g(x, y, z) = 0$$

continuazione

es. 1

$$(x, y, z, \lambda) \begin{cases} 2x = \lambda \\ 2y = \lambda \\ 2z = \lambda \end{cases}$$

$$x + y + z + 1 = 0$$

es. 2

1) moltiplicatore di Lagrange

$$\begin{aligned} w(x, y) &= x^2 - xy + y^2 & n_{\text{incognite}} &= 2 & \nabla w &= (2x - y, -x + 2y) \\ \begin{cases} z = x^2 - xy + y^2 \\ x^2 + y^2 - 4 = 0 \end{cases} & & m_{\text{vincoli}} &= 1 & \nabla g &= (2x, 2y) \\ g(x, y) & & & & & \end{aligned}$$

$$\begin{cases} \nabla w = \lambda \nabla g \\ g(x, y) = 0 \end{cases} \rightarrow \begin{cases} 2x - y = 2\lambda x \\ -x + 2y = 2\lambda y \\ x^2 + y^2 - 4 = 0 \end{cases} \quad \lambda_1 = \frac{1}{2} \quad \lambda_2 = \frac{3}{2}$$

$$\downarrow$$

$$P_1(\sqrt{2}, \sqrt{2}) \quad P_2(-\sqrt{2}, -\sqrt{2}) \quad P_3(\sqrt{2}, -\sqrt{2}) \quad P_4(-\sqrt{2}, \sqrt{2})$$

$$\downarrow$$

$$\begin{aligned} w(P_1) = w(P_2) &= 2 & z &= \min w(g) \\ w(P_3) = w(P_4) &= 6 & 6 &= \max w(g) \end{aligned} \quad g(x, y) = 0$$

2) altra strada sostituzione

$$\text{esplicito } y \rightarrow y = \pm \sqrt{4 - x^2} \quad \text{e sostituisco} \rightarrow z = x^2 \pm \sqrt{4 - x^2} + (4 - x^2)$$

$$\text{da } g(x, y) \quad \text{in } w(x, y) \quad \text{deriva e ottengo i punti stazionari}$$

cambiamento di coordinate (inversione):

$$\mathbb{R}^n \rightarrow \mathbb{R}^n$$

$$Y = F(X) \rightarrow \begin{aligned} X &= (x_1, x_2, \dots, x_n) \\ Y &= (y_1, y_2, \dots, y_n) \end{aligned}$$

es. 1 $\mathbb{R}^2 \rightarrow \mathbb{R}^2$

$$\begin{cases} x = \rho \cos \theta \\ y = \rho \sin \theta \end{cases}$$

$$(p, \theta) \rightarrow (x, y)$$

$$\phi(x, y) = \begin{cases} \rho = \phi_1(x, y) \\ \theta = \phi_2(x, y) \end{cases}$$

• forma ESPLICITA / IMPLICITA:

$$F(X) - Y = 0 \rightarrow \begin{cases} f_1(x_1, x_2, \dots, x_n) - y_1 = 0 \\ \vdots \end{cases}$$

$\mathbb{R}^{2n}$

$$X = \phi(Y) \quad J(x, y) = (J_F(X) - I) \quad \phi(Y) = F^{-1}(X) \quad y = F(X) = (F \circ \phi)(Y) = F(\phi(Y))$$

$$\det J_F(X) \neq 0$$

$$J_Y = I \quad J_{F \circ \phi} = J_F J_\phi = I \quad J_\phi = J_F^{-1} = J_{F^{-1}}$$

↓
ATTINUAZIONE

es. 1

$$J(p, \theta) = \begin{bmatrix} \cos \theta & -\rho \sin \theta \\ \sin \theta & \rho \cos \theta \end{bmatrix} \quad \det J(p, \theta) = \rho \cos^2 \theta + \rho \sin^2 \theta = \rho$$

es. 2 "COMPOSIZIONE" di FUNZIONE CON VINCOLI

$$\begin{cases} w = f(x, y, z) \\ g_1(x, y, z) = 0 \\ g_2(x, y, z) = 0 \end{cases} \quad n=3 \quad m=2 \quad \begin{cases} y = \varphi_1(x) \\ z = \varphi_2(x) \end{cases} \quad \phi(x)$$

$$\det J = \begin{bmatrix} \frac{\partial g_1}{\partial y} & \frac{\partial g_1}{\partial z} \\ \frac{\partial g_2}{\partial y} & \frac{\partial g_2}{\partial z} \end{bmatrix} \neq 0 \quad \frac{\partial(g_1, g_2)}{\partial(y, z)}$$

$$\begin{cases} w = x^2 + y^2 + z^2 \\ z = 3x^2 - 4y^2 \\ x^2 + y^2 = 4 \end{cases} \quad \begin{cases} 3x^2 - 4y^2 - z = 0 \\ x^2 + y^2 - 4 = 0 \end{cases}$$

$\rightarrow$ n variabili
 m vincoli

$$\begin{cases} \nabla W = \lambda_1 \nabla g_1 + \dots + \lambda_m \nabla g_m \\ G(\cdot) = 0 \end{cases}$$

CONTINUAZIONE

es. 2

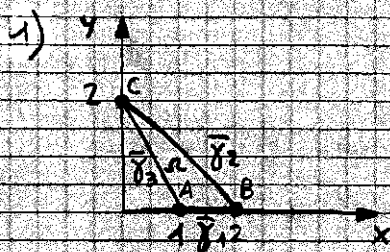
$$\nabla W = (2x, 2y, 2z)$$

$$\nabla g_1 = (6x, -8y, -1)$$

$$\nabla g_2 = (2x, 2y, 0)$$



$$\begin{cases} 2x = 6\lambda_1 + 2\lambda_2 \\ 2y = -8\lambda_1 + 2\lambda_2 \\ 2z = -\lambda_1 \\ 3x^2 - 4y^2 - z = 0 \\ x^2 + y^2 - 4 = 0 \end{cases}$$

es. POME

$$f(x,y) = 4x^2 + 3y^2$$

$$A(1,0)$$

$$B(2,0) \quad \Omega$$

$$C(0,2)$$

Cercate max e min di $f(x,y)$ nel triangolo ABC:

$$\nabla f = \vec{0} \rightarrow (0,0) \notin \Omega$$



$$\text{bordi di } \Omega = \bar{\gamma}_1 \cup \bar{\gamma}_2 \cup \bar{\gamma}_3$$

li parametrizzo:

$$\bullet \bar{\gamma}_1(t) = \begin{bmatrix} t \\ 0 \end{bmatrix} \quad 1 < t < 2 \rightarrow f(\bar{\gamma}_1(t)) = 4t^2 + 3 \cdot 0^2 = 4t^2 \quad \frac{df(\bar{\gamma}_1(t))}{dt} = 8t = 0 \quad t \notin \bar{\gamma}_1$$

$$\bullet \bar{\gamma}_2(t) = \begin{bmatrix} t \\ -(t-2) \end{bmatrix} \rightarrow f(\bar{\gamma}_2(t)) = 4t^2 + 3(-(t-2))^2 \quad \frac{df(\bar{\gamma}_2(t))}{dt} = 14t - 12 \quad t = \frac{6}{7}$$

$0 < t < 2$

$$P_2\left(\frac{6}{7}, \frac{8}{7}\right) \in \bar{\gamma}_2$$

b) SUL BORDO con il moltiplicatore di Lagrange
nei punti di max e min per $f(x,y)$ vincolati su $g(x,y)=1$

$$\begin{cases} \nabla f = \lambda \nabla g \\ g(x,y)=1 \end{cases} \rightarrow \begin{cases} \begin{bmatrix} 4x \\ 3+2y \end{bmatrix} = \lambda \begin{bmatrix} 4x+1 \\ 2y+\frac{5}{6} \end{bmatrix} \\ 2x^2+y^2+x+\frac{5}{6}y=1 \end{cases}$$

osservazione:

$$\begin{aligned} 4x+1 &\neq 0 \\ 2y+\frac{5}{6} &\neq 0 \end{aligned} \rightarrow \frac{4x}{4x+1} = \lambda = \frac{3+2y}{2y+\frac{5}{6}}$$

↓

$$4x\left(2y+\frac{5}{6}\right) = (4x+1)(3+2y) \rightarrow y = -\frac{13}{3}x - \frac{3}{2}$$

↓ sostituisco nel vincolo

$$2x^2 + \left(-\frac{13}{3}x - \frac{3}{2}\right)^2 + x + \frac{5}{6}\left(-\frac{13}{3}x - \frac{3}{2}\right) = 1$$

↓

$$x_1 = 0$$

$$x_2 = -\frac{1}{2}$$

$$y = -\frac{3}{2}$$

$$y_2 = \frac{2}{3}$$

$$P_1\left(0, -\frac{3}{2}\right) \quad P_2\left(-\frac{1}{2}, \frac{2}{3}\right)$$

$$f(P_1) = -\frac{9}{4} \quad f(P_2) = \frac{53}{18}$$

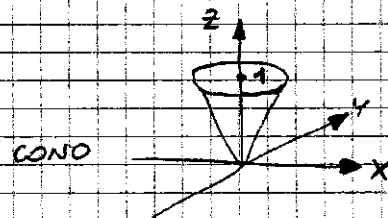
min

MAX

ES. 3 cercare MAX e min

$$f(x,y,z) = 2x + 2\sqrt{3}y + z^2$$

$$\text{vincolo} \begin{cases} g(x,y,z) = x^2 + y^2 - z^2 \leq 0 \\ 0 \leq z \leq 1 \end{cases}$$



$$a) \nabla f = \vec{0} \quad \begin{bmatrix} 2 \\ 2\sqrt{3} \\ 2z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{MAI}$$

$$b) \bullet \text{COPERCHIO} \quad \begin{cases} x^2 + y^2 < 1 \\ z = 1 \end{cases} \rightarrow f(x,y,1) = 2x + 2\sqrt{3}y + 1$$

$$\nabla f = \vec{0} \rightarrow \begin{bmatrix} 2 \\ 2\sqrt{3} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \text{MAI}$$

$$\begin{aligned} \rightarrow \begin{cases} z = \lambda 2x + \mu 0 \\ 2\sqrt{3} = \lambda 2y + \mu 0 \\ 2z = \lambda \cdot 0 + \mu \\ x^2 + y^2 - 1 = 0 \\ z - 1 = 0 \end{cases} & \rightarrow \begin{cases} y = \sqrt{3}x \\ x^2 + 3x^2 = 1 & x = \pm \frac{1}{2} \\ y = \pm \frac{\sqrt{3}}{2} & z = 1 \end{cases} \\ & P_2 \left(\frac{1}{2}, \frac{\sqrt{3}}{2}, 1 \right) \\ & P_3 \left(-\frac{1}{2}, -\frac{\sqrt{3}}{2}, 1 \right) \\ & O(0, 0, 0) \end{aligned}$$

$$f(P_2) = 5 \text{ MAX}$$

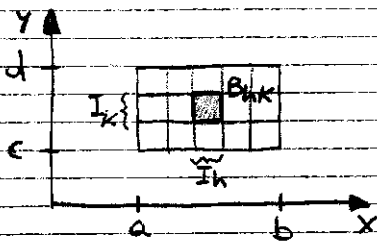
$$f(P_3) = -3 \text{ MIN}$$

$$f(O) = 0$$

• INTEGRALI di FUNZIONI a PIÙ VARIABILI

INTEGRALE DOPPIO

INTEGRALE DOPPIO su RETTANGOLI



$$[a, b] \times [c, d]$$

$$B_{hk} = I_h \times I_k$$

$$z = f(x, y) \quad \mathbb{R}^2 \rightarrow \mathbb{R} \quad \text{LIMITATA}$$

$$0 \leq z \leq f(x, y) \quad \vee \quad f(x, y) \leq z \leq 0$$

$\mathcal{D}$ insieme di tutte le suddivisioni B_{hk}

$$m_{hk} = \inf_{B_{hk}} f$$

$$M_{hk} = \sup_{B_{hk}} f$$

somme superiori e inferiori:

$$s = S(\mathcal{D}, f) = \sum_k \sum_h m_{hk} (x_h - x_{h-1})(y_k - y_{k-1})$$

$$S = S(\mathcal{D}, f) = \sum_k \sum_h M_{hk} (x_h - x_{h-1})(y_k - y_{k-1})$$

es. 1 $B = [0, \frac{\pi}{4}] \times [0, \frac{\pi}{2}]$

$$\begin{aligned} \iint_B \cos(x+y) \, dx \, dy &= \int_0^{\frac{\pi}{2}} \left(\int_0^{\frac{\pi}{4}} \cos(x+y) \, dx \right) dy = \int_0^{\frac{\pi}{2}} \left[\sin(x+y) \right]_{x=0}^{x=\frac{\pi}{4}} dy = \\ &= \int_0^{\frac{\pi}{2}} \left(\sin\left(\frac{\pi}{4}+y\right) - \sin y \right) dy = \left[-\cos\left(\frac{\pi}{4}+y\right) + \cos y \right]_0^{\frac{\pi}{2}} = \\ &= -\cos\left(\frac{\pi}{4}+\frac{\pi}{2}\right) + \cos \frac{\pi}{4} + \cos \frac{\pi}{2} - \cos 0 = -\cos \frac{3\pi}{4} + \frac{\sqrt{2}}{2} - 1 = \frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}} - 1 = \sqrt{2} - 1 \end{aligned}$$

si può risolvere anche integrando prima su y e poi su x

$B = [1, 2] \times [0, \pi]$ per verticali

es. 2 $\iint_B x \cos xy \, dx \, dy = \int_1^2 \left(\int_0^{\pi} x \cos xy \, dy \right) dx = \int_1^2 \left[\sin xy \right]_{y=0}^{y=\pi} dx =$

$$= \int_1^2 (\sin \pi x) dx = \left[-\frac{1}{\pi} \cos \pi x \right]_1^2 = -\frac{1}{\pi} - \left(+\frac{1}{\pi} \right) = -\frac{2}{\pi}$$

INSIEMI MISURABILI

$$\chi_{\Omega}(x) = \begin{cases} 1 & \text{se } x \in \Omega \\ 0 & \text{se } x \notin \Omega \end{cases} \quad \text{funzione caratteristica}$$

$\Omega \subset B$ B rettangolo

$$\iint_B \chi_{\Omega}(x) \, dx \, dy = \text{Area di } \Omega = |\Omega| = \iint_{\Omega} \chi_{\Omega}(x, y) \, dx \, dy = \iint_{\Omega} dx \, dy$$

INSIEMI di MISURA NULLA

$$A \subseteq \mathbb{R}^2 \quad |A| = \iint_A dx \, dy = 0$$

$\Omega \subseteq \mathbb{R}^2$ è MISURABILE $\iff \underbrace{\partial \Omega}_{\text{FRONTIERA DI } \Omega}$ ha misura nulla

f definita su Ω (insieme misurabile)

$$\hat{f}(x, y) = \begin{cases} f(x, y) & \text{se } x \in \Omega \\ 0 & \text{se } x \notin \Omega \end{cases}$$

b) $\Omega \subseteq \mathbb{R}^2$ sia ORIZZONTALMENTE CONVESSO, $\Omega \rightarrow \mathbb{R}$ CONTINUA
allora

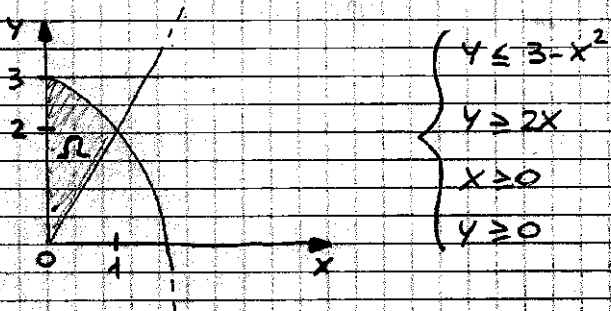
$$\iint_{\Omega} f(x,y) dx dy = \int_c^d \left(\int_{h_1(y)}^{h_2(y)} f(x,y) dx \right) dy$$

es.

$$\iint_{\Omega} (x+2y) dx dy$$

Ω è la regione del 1° quadrante ($x \geq 0, y \geq 0$), limitata dalle curve di equazione

$$y = 2x, \quad y = 3 - x^2, \quad x = 0$$



descriviamo Ω per VERTICALI:

$$\Omega = \left\{ (x,y) \in \mathbb{R}^2 / 0 \leq x \leq 1 \quad \vee \quad 2x \leq y \leq 3 - x^2 \right\}$$

se volessi descrivere per ORIZZONTALI:

$$\begin{cases} 0 \leq y \leq 2 & 0 \leq x \leq \frac{1}{2}y \\ 2 \leq y \leq 3 & 0 \leq x \leq \sqrt{3-y} \end{cases}$$

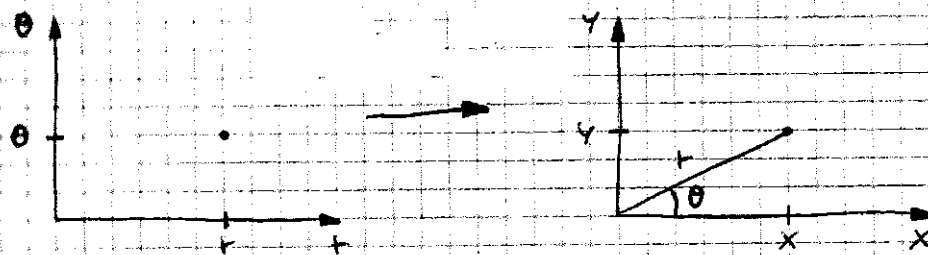
↓ svolgo per verticali

$$\iint_{\Omega} (x+2y) dx dy = \int_0^1 \left(\int_{2x}^{3-x^2} (x+2y) dy \right) dx = \int_0^1 \left[xy + y^2 \right]_{y=2x}^{y=3-x^2} dx =$$

$$= \int_0^1 \left[x(3-x^2) + (3-x^2)^2 - 2x^2 - 4x^2 \right] dx = \int_0^1 (3x - x^3 + 9 - 6x^2 + x^4 - 6x^2) dx =$$

$$= \int_0^1 (x^4 - x^3 - 12x^2 + 3x + 9) dx = \left[\frac{x^5}{5} - \frac{x^4}{4} - \frac{12}{3}x^3 + \frac{3}{2}x^2 + 9x \right]_0^1 = \frac{1}{5} - \frac{1}{4} - \frac{12}{3} + \frac{3}{2} + 9 =$$

CAMBIO di VARIABILI con COORDINATE POLARI nel PIANO (caso importante)



$$\begin{pmatrix} x \\ y \end{pmatrix} = \Phi(r, \theta) = \begin{pmatrix} r \cos \theta \\ r \sin \theta \end{pmatrix}$$

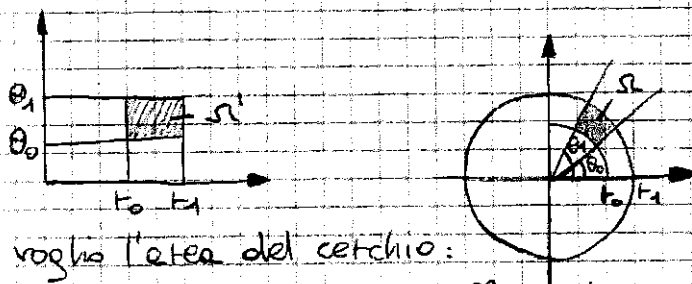
$$\det J\Phi = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$$

↓

$$\int_{\Omega} dx dy = \int_{\Omega'} r dr d\theta$$

$$\int_{\Omega} f(x, y) dx dy = \int_{\Omega'} f(\Phi(u, v)) |\det J\Phi(u, v)| du dv$$

es. 1 $\iint_{\Omega} dx dy$ $\Omega = \{x^2 + y^2 \leq r^2\}$



se voglio l'area del cerchio:

$$\iint_{\Omega} dx dy = \iint_{\Omega'} r dr d\theta = \int_0^{2\pi} d\theta \int_0^{r_0} r dr = [\theta]_0^{2\pi} \left[\frac{r^2}{2} \right]_0^{r_0} = 2\pi \frac{r_0^2}{2} = \pi r_0^2$$

se voglio calcolare un settore:

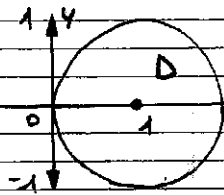
$$\iint_{\Omega} dx dy = \iint_{\Omega'} r dr d\theta = \int_{\theta_0}^{\theta_1} d\theta \int_{r_0}^{r_1} r dr = [\theta]_{\theta_0}^{\theta_1} \left[\frac{r^2}{2} \right]_{r_0}^{r_1} = (\theta_1 - \theta_0) \frac{(r_1^2 - r_0^2)}{2}$$

es. 3 $\iint_D \sqrt{x^2+y^2} \, dx \, dy$

$$D = \{(x,y) \in \mathbb{R}^2 / x^2+y^2-2x \leq 0\}$$

ricostruisco il quadrato:

$$(x-1)^2 - 1 + y^2 \leq 0 \rightarrow (x-1)^2 + y^2 \leq 1$$



coordinate polari

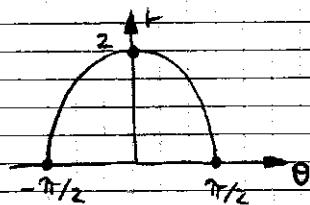
$$\phi: \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases} \quad \det |J\phi| = r$$

così $\bar{D}: r^2 \cos^2 \theta + r^2 \sin^2 \theta - 2r \cos \theta \leq 0$

$$r^2 - 2r \cos \theta \leq 0 \quad \text{per } r > 0$$

$$r(r - 2 \cos \theta) \leq 0$$

$\downarrow$
 $r = 2 \cos \theta$



per verticali

$$\iint_D \sqrt{x^2+y^2} \, dx \, dy = \iint_{\Omega'} \sqrt{r^2} \cdot r \, dr \, d\theta =$$

$$= \int_{-\pi/2}^{\pi/2} \left(\int_0^{2 \cos \theta} r^2 \, dr \right) d\theta = \int_{-\pi/2}^{\pi/2} \left[\frac{r^3}{3} \right]_0^{2 \cos \theta} d\theta = \int_{-\pi/2}^{\pi/2} \frac{8 \cos^3 \theta}{3} d\theta =$$

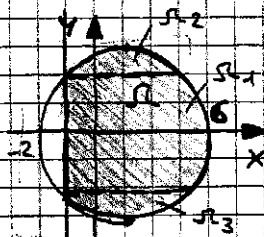
$$= \int_{-\pi/2}^{\pi/2} \frac{8}{3} (1 - \sin^2 \theta) \cos \theta \, d\theta \rightarrow \begin{matrix} t = \sin \theta \\ dt = \cos \theta \, d\theta \end{matrix} \rightarrow \int_{-1}^1 \frac{8}{3} (1 - t^2) dt =$$

$$= \left[\frac{8}{3} t - \frac{8}{9} t^3 \right]_{-1}^1 = \frac{16}{3} - \frac{16}{9} = \frac{32}{9}$$

es. 2

$$\iint_{\Omega} (2x+y-4) dx dy$$

$$\Omega: \begin{cases} x^2+y^2-4x \leq 12 & (x-2)^2+y^2=16 \\ x \geq 2-2\sqrt{2} & x=2-2\sqrt{2} \end{cases}$$



① per verticali:

$$\Omega = \left\{ (x,y) / -\sqrt{12-x^2+4x} \leq y \leq \sqrt{12-x^2+4x} \right. \\ \left. 2-2\sqrt{2} \leq x \leq 6 \right\}$$

$$\int_{2-2\sqrt{2}}^6 \left(\int_{-\sqrt{12-x^2+4x}}^{\sqrt{12-x^2+4x}} (2x+y-4) dy \right) dx \quad \text{+ MEGLIO}$$

② per orizzontali:

$$\Omega = \Omega_1 + \Omega_2 + \Omega_3$$

$$\Omega_1 = \left\{ (x,y) / 2-2\sqrt{2} \leq x \leq 2+\sqrt{16-y^2}, -2\sqrt{2} \leq y \leq 2\sqrt{2} \right\}$$

$$\Omega_2 = \left\{ (x,y) / 2-\sqrt{16-y^2} \leq x \leq 2+\sqrt{16-y^2}, 2\sqrt{2} \leq y \leq 4 \right\}$$

$$\Omega_3 = \left\{ (x,y) / 2-\sqrt{16-y^2} \leq x \leq 2+\sqrt{16-y^2}, -4 \leq y \leq -2\sqrt{2} \right\}$$

$$\begin{aligned} & \iint_{\Omega_1} (2x+y-4) dx dy + \iint_{\Omega_2} (2x+y-4) dx dy + \iint_{\Omega_3} (2x+y-4) dx dy = \\ & = \int_{-2\sqrt{2}}^{2\sqrt{2}} \left(\int_{2-2\sqrt{2}}^{2+\sqrt{16-y^2}} (2x+y-4) dx \right) dy + \int_{2\sqrt{2}}^4 \left(\int_{2-\sqrt{16-y^2}}^{2+\sqrt{16-y^2}} (2x+y-4) dx \right) dy + \\ & + \int_{-4}^{-2\sqrt{2}} \left(\int_{2-\sqrt{16-y^2}}^{2+\sqrt{16-y^2}} (2x+y-4) dx \right) dy = \dots \quad \text{PEGGIO} \end{aligned}$$

considerazioni:

• in $\mathbb{R}$

$w(x)$ è la densità di massa del filo

$\int_a^b w(x) dx$ è la massa del filo

• in $\mathbb{R}^2$

$w(x,y)$ è la densità di massa di S

$\iint_S w(x,y) dx dy$ è la massa di S

$\iint_S dx dy$ è l'area di S

se $w(x,y) = z \rightarrow \iint_S w(x,y) dx dy$ è un volume

• in $\mathbb{R}^3$

$f(x,y,z)$ è la densità di massa

$\iiint_V dx dy dz$ è un volume

$\iiint_V f(x,y,z) dx dy dz$ è la massa di V

• INTEGRALE TRIPLO

$$\overline{\iiint_V f dx dy dz} = \underline{\iiint_V f dx dy dz}$$

somme superiori

=
somme inferiori

FORMULE di RIDUZIONE per FILI PARALLELI

a) supponiamo che S sia convesso nella direzione z
(semplice o normale rispetto a z)

$$S = \{(x,y,z) \in \mathbb{R}^3 / (x,y) \in D \subseteq \mathbb{R}^2, g_1(x,y) \leq z \leq g_2(x,y)\}$$

il piano che cetco è normale a $\bar{N}$ e passante per $(1,0,0)$:

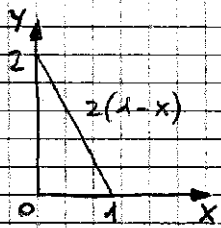
$$\bar{N} \cdot \begin{pmatrix} x-1 \\ y \\ z \end{pmatrix} = 0 \rightarrow 6(x-1) + 3y + 2z = 0 \rightarrow z = \frac{1}{2}(-6(x-1) - 3y)$$



$$z = -3x - \frac{3}{2}y + 3$$

$$\Omega = \left\{ (x,y) \in D / 0 \leq z \leq -3x - \frac{3}{2}y + 3 \right\}$$

$$\iiint_{\Omega} dx dy dz = \iint_D \left(\int_0^{-3x - \frac{3}{2}y + 3} dz \right) dx dy = \iint_D \left(-3x - \frac{3}{2}y + 3 \right) dx dy =$$



per
VERTICALI

$$= \int_0^1 \left(\int_0^{2(1-x)} \left(-3x - \frac{3}{2}y + 3 \right) dy \right) dx =$$

$$= \int_0^1 \left[-3xy - \frac{3}{2} \frac{y^2}{2} + 3y \right]_{y=0}^{y=2(1-x)} dx = \int_0^1 (-\cancel{6x} + 6x^2 - 3 + \cancel{6x} - 3x^2 + 6 - 6x) dx =$$

$$= \left[x^3 - 3x^2 + 3x \right]_0^1 = 1$$

FORMULE di RIDUZIONE per STRATI

d) Ω sia incontrato da tutti i piani paralleli al piano x,y con $a \leq z \leq b$

indichiamo con C_z l'intersezione di Ω con il piano parallelo al piano x,y e a quota z con $a \leq z \leq b$

allora:

$$\iiint_{\Omega} f(x,y,z) dx dy dz = \int_a^b \left(\iint_{C_z} f(x,y,z) dx dy \right) dz \quad \begin{array}{l} \text{per STRATI} \\ \text{PARALLELI a } x,y \end{array}$$

lo stesso vale per l'integrazione per STRATI PARALLELI ai piani y,z e x,z

$$\vec{\phi}(r, \theta, \varphi) = \begin{pmatrix} r \sin \theta \cos \varphi \\ r \sin \theta \sin \varphi \\ r \cos \theta \end{pmatrix}$$

$$|\det J \phi| = \left| \det \begin{pmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \theta & -r \sin \theta & 0 \end{pmatrix} \right| =$$

$$= |\cos(r^2 \sin \theta \cos \theta \cdot 1) + r \sin \theta(r \sin^2 \theta \cdot 1)| = r^2 \sin \theta \geq 0$$

VOLUME SFERA

$$S_L = x^2 + y^2 + z^2 \leq r^2$$

$$\iiint_{S_L} dx dy dz = \iiint_{S_L'} r^2 \sin \theta dr d\theta d\varphi = \int_0^{r_0} r^2 dr \int_0^\pi \sin \theta d\theta \int_0^{2\pi} d\varphi =$$

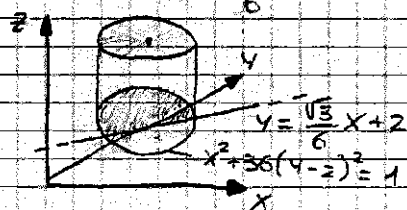
$$= \frac{r_0^3}{3} \cdot 2 \cdot 2\pi = \frac{4}{3} \pi r_0^3$$

es. POME

$$1) \Omega = \begin{cases} 0 \leq z \leq x^2 + 36(y-2)^2 \\ (x, y) \in D \end{cases}$$

$$D = \begin{cases} x^2 + 36(y-2)^2 \leq 1 \rightarrow \frac{x^2}{1} + \frac{(y-2)^2}{(\frac{1}{6})^2} = 1 \\ y \geq \frac{\sqrt{3}}{6}x + 2 \end{cases}$$

$$\iiint_{\Omega} dx dy dz = \text{per F.L.} \parallel z$$



$$\iint_D \left(\int_0^{x^2 + 36(y-2)^2} dz \right) dx dy = \iint_D [z]_0^{x^2 + 36(y-2)^2} dx dy = \iint_D (x^2 + 36(y-2)^2) dx dy =$$

cambio variabile $\begin{cases} u = x \\ v = y - 2 \\ v \geq \frac{\sqrt{3}}{6}u \end{cases} \rightarrow u^2 + 36v^2 = 1 \rightarrow \begin{cases} t = r \cos \theta \\ s = \frac{1}{6} r \sin \theta \end{cases}$

cambio coordinate $\begin{cases} u = t \\ v = \frac{1}{6}s \end{cases} \rightarrow t^2 + s^2 = 1$

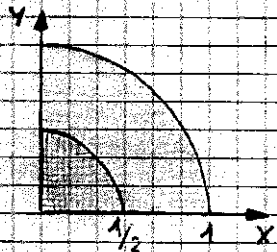
molte, prima con una parabola e poi una circonferenza

$$\frac{y}{x} = \frac{\sqrt{3}}{6} = \tan \alpha \\ \alpha = \arctan \frac{\sqrt{3}}{6}$$

$$\alpha \leq \theta \leq \alpha + \pi \\ J = \frac{1}{6} r$$

$z_0 = \text{cost}$ taglio la superficie con un piano z_0 .

$\sqrt{x^2+y^2} = \frac{1}{z_0} \rightarrow x^2+y^2 = \left(\frac{1}{z_0}\right)^2$ ogni piano che taglia individua una circonferenza di raggio $= \frac{1}{z_0}$.



Facciamo l'integrale per strati // al piano x,y

$$1 \leq z_0 \leq 2$$

$$C_z = \left\{ (x,y) \in \mathbb{R}^2 / x^2+y^2 \leq \frac{1}{z^2}, 1 \leq z \leq 2 \right\}$$

$$I = \int_1^2 \left(\iint_{C_z} xy \, dx \, dy \right) dz \rightarrow \begin{cases} x = r \cos \theta & 0 \leq \theta \leq \frac{\pi}{2} \\ y = r \sin \theta & 0 \leq r \leq \frac{1}{z} \end{cases}$$

$$\int_1^2 \left(\iint_{C'_z} \underbrace{r \cos \theta}_{x} \cdot \underbrace{r \sin \theta}_{y} \cdot \underbrace{\frac{1}{J}}_{\frac{1}{r}} \, dr \, d\theta \right) dz = \int_1^2 \left(\iint_{C'_z} r^3 \cos \theta \sin \theta \, dr \, d\theta \right) dz =$$

$$= \int_1^2 \left(\int_0^{1/z} r^3 \, dr \int_0^{\pi/2} \cos \theta \sin \theta \, d\theta \right) dz = \int_1^2 \left[\frac{r^4}{4} \right]_0^{1/z} \cdot \left[\frac{\sin^2 \theta}{2} \right]_0^{\pi/2} dz =$$

$$= \int_1^2 \frac{1}{4z^4} \cdot \frac{1}{2} dz = \left[\frac{1}{8} \cdot \frac{1}{(-3)z^3} \right]_1^2 = -\frac{1}{192} + \frac{1}{24} = \frac{4}{192}$$

es. 4 Calcolare il volume del solido di rotazione dato dalle seguenti eq. (intorno all'asse z)

$$\begin{cases} y^2 - z^2 \geq 0 & (y+z)(y-z) \geq 0 \\ y^2 + z^2 - 4 \leq 0 & z = \sqrt{y^2 - 4} \\ 2 \leq y \leq 3 \\ z \geq 0 \end{cases}$$

per Guldino

$$V = 2\pi y_G \iint_A dz \, dy = 2\pi \frac{\iint_A y \, dz \, dy}{\iint_A dz \, dy} \iint_A dz \, dy = 2\pi \iint_A y \, dz \, dy = \dots = \frac{2}{3} \pi (19 - 5\sqrt{5})$$

se avessi una funzione all'interno dell'integrale:

$$\int_{\Sigma} f(x, y, z) d\sigma = \iint_D f(\sigma_1(u, v), \sigma_2(u, v), \sigma_3(u, v)) \cdot \left\| \frac{\partial \sigma}{\partial u} \wedge \frac{\partial \sigma}{\partial v} \right\| du dv$$

OSSERVAZIONE

Se la superficie è descritta in modo esplicito

$$z = g(x, y)$$

es. $z = \sqrt{1-x^2-y^2}$

$$\bar{\sigma}(x, y) = \begin{pmatrix} x \\ y \\ g(x, y) \end{pmatrix}$$

$$\bar{\sigma}(x, y) = \begin{pmatrix} x \\ y \\ \sqrt{1-x^2-y^2} \end{pmatrix}$$

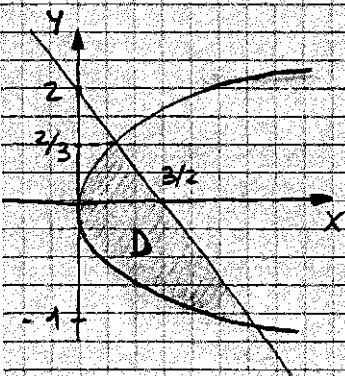
$$\frac{\partial \bar{\sigma}}{\partial x} = \begin{pmatrix} 1 \\ 0 \\ \frac{\partial g}{\partial x} \end{pmatrix}$$

$$\frac{\partial \bar{\sigma}}{\partial y} = \begin{pmatrix} 0 \\ 1 \\ \frac{\partial g}{\partial y} \end{pmatrix}$$

$$\rightarrow \|\bar{N}\| = \sqrt{1 + \left(\frac{\partial g}{\partial x}\right)^2 + \left(\frac{\partial g}{\partial y}\right)^2}$$

es. $\int_{\Sigma} yz d\sigma$

dove Σ è la superficie di eq. $z = \sqrt{x-y^2}$ che si proietta nel piano x, y nella regione delimitata dalla parabola $x = y^2$ e dalla retta $3x + y - 2 = 0$



$$\bar{\sigma}(x, y) = \begin{pmatrix} x \\ y \\ \sqrt{x-y^2} \end{pmatrix} \quad (x, y) \in D$$

$$\begin{aligned} \|\bar{N}\| &= \sqrt{1 + \left(\frac{1}{2\sqrt{x-y^2}}\right)^2 + \left(\frac{-2y}{2\sqrt{x-y^2}}\right)^2} = \sqrt{\frac{4x - 4y^2 + 1 + 4y^2}{4(x-y^2)}} \\ &= \sqrt{\frac{1+4x}{4(x-y^2)}} \end{aligned}$$

$$\int_{\Sigma} yz d\sigma = \iint_D y \sqrt{x-y^2} \cdot \frac{1}{2} \sqrt{\frac{1+4x}{x-y^2}} dx dy = \iint_D \frac{1}{2} y \sqrt{1+4x} dx dy \quad \text{per separabilità}$$

$$= \int_{-1}^{2/3} \left(\int_{y^2}^{2-y} \frac{y \sqrt{1+4x}}{2} dx \right) dy = \dots$$

$$\rightarrow \int_{\Sigma} \vec{f} \cdot \vec{N} d\epsilon = \int_{\Sigma_1} \vec{f} \cdot \vec{N} d\epsilon + \int_{\Sigma_2} \vec{f} \cdot \vec{N} d\epsilon + \int_{\Sigma_3} \vec{f} \cdot \vec{N} d\epsilon + \int_{\Sigma_4} \vec{f} \cdot \vec{N} d\epsilon$$

$$I_1 = \int_{\Sigma_1} \vec{f} \cdot \vec{N} d\epsilon = \iint_{D_1} \begin{pmatrix} \frac{x-y^2}{x^2 + \frac{1}{3}y^3} \\ \frac{0}{1} \end{pmatrix} \cdot \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} dx dy = \iint_{D_1} -4 dx dy = -4 \cdot \frac{1}{2} \pi (\sqrt{2})^2 = -4\pi$$

$$I_2 = \int_{\Sigma_2} \vec{f} \cdot \vec{N} d\epsilon = \iint_{D_2} \begin{pmatrix} \frac{z^3}{x^2 + \frac{1}{3}z^3 + 2} \\ 0 \\ 0 \end{pmatrix} \cdot \begin{pmatrix} 0 \\ -1 \\ 0 \end{pmatrix} dx dz = \iint_{D_2} -x^2 dx dz = \dots$$

$$I_3 = \int_{\Sigma_3} \vec{f} \cdot \vec{N} d\epsilon = \iint_{D_3} \begin{pmatrix} \frac{xy^2 + (\sqrt{2-x^2-y^2})^3}{x^2 + \frac{1}{3}y^3} \\ \frac{x^2 \sqrt{2-x^2-y^2} + \frac{1}{3}(\sqrt{2-x^2-y^2})^3 + 2}{1} \end{pmatrix} \cdot \vec{N} dx dy = \dots$$

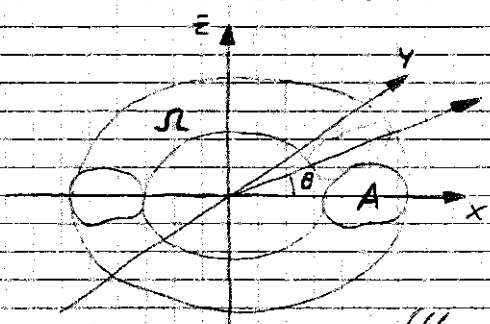
$$\vec{N} = \begin{pmatrix} -x \\ \sqrt{2-x^2-y^2} \\ -y \\ \sqrt{2-x^2-y^2} \\ 1 \end{pmatrix}$$

$$I_4 = \int_{\Sigma_4} \vec{f} \cdot \vec{N} d\epsilon = \iint_{D_4} \begin{pmatrix} \frac{xy^2 + (\sqrt{x^2+y^2})^3}{x^2 + \frac{1}{3}y^3} \\ \frac{x^2 \sqrt{x^2+y^2} + \frac{1}{3}(\sqrt{x^2+y^2})^3 + 2}{1} \end{pmatrix} \cdot \begin{pmatrix} x \\ \sqrt{x^2+y^2} \\ y \\ \sqrt{x^2+y^2} \\ 1 \end{pmatrix} dx dy = \dots$$

• TEOREMI di GULDINO

SOLIDI di ROTAZIONE

1°)



Se voglio il volume di Ω

$$\iiint_{\Omega} dx dy dz$$

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

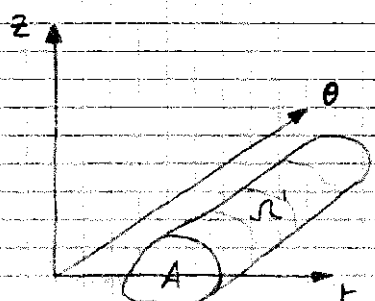
$$\iiint_{\Omega'} r dr d\theta dz =$$

fil // θ

$$|det J| = r = \sqrt{x^2 + y^2}$$

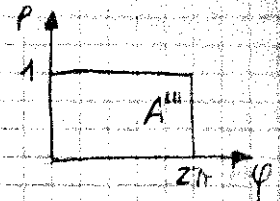
$$0 \leq \theta \leq 2\pi$$

$$(r, z) \in A$$

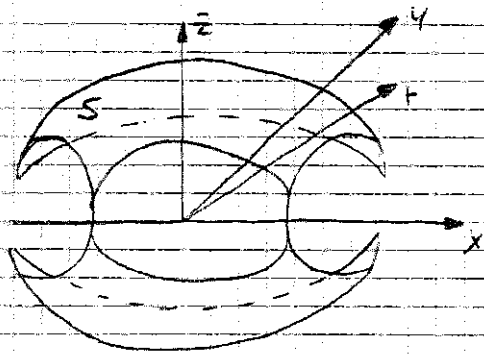


$$= \iint_A \left(\int_0^{2\pi} r d\theta \right) dr dz =$$

$$= 0 + 2\pi r_0 ab \left[\frac{r^2}{2} \right]_0^{2\pi} = 2\pi^2 r_0 ab = 2\pi r_0 \cdot \pi ab$$

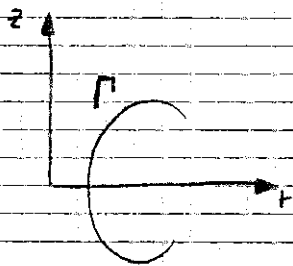


2°) SUPERFICI di ROTAZIONE



Si fa ruotare nello spazio intorno all'asse z una curva γ

$$\begin{cases} x = r \cos \varphi \\ y = r \sin \varphi \\ z = z \end{cases} \quad |\det J| = r$$

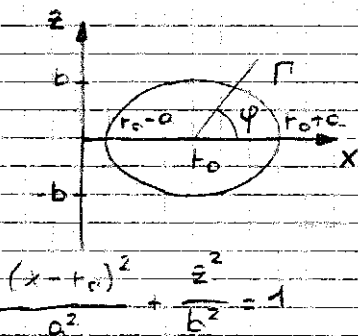


$$\gamma(t) = \begin{pmatrix} \gamma_1(t) \\ \gamma_2(t) \end{pmatrix} \quad \begin{cases} r = \gamma_1(t) \\ z = \gamma_2(t) \end{cases}$$

$$I = \int_{\gamma} dS = 2\pi \int_{\gamma} x dy = 2\pi \frac{\int_{\gamma} x dy}{\int_{\gamma} dy} \int_{\gamma} dy =$$

$$I = 2\pi x_E \cdot \int_{\gamma} \|\gamma'(\varphi)\| d\varphi \quad 2^{\circ} \text{ TEOREMA di GULDINO}$$

es. superficie di rotazione del TORO



$$I = \int_{\gamma} dS = 2\pi \int_{\gamma} x d\varphi \rightarrow$$

$$\gamma(\varphi) = \begin{cases} x - r_0 = a \cos \varphi \\ z = b \sin \varphi \end{cases} \rightarrow \gamma(\varphi) = \begin{pmatrix} a \cos \varphi + r_0 \\ b \sin \varphi \end{pmatrix} \rightarrow \gamma'(\varphi) = \begin{pmatrix} -a \sin \varphi \\ b \cos \varphi \end{pmatrix}$$

$$\|\gamma'(\varphi)\| = \sqrt{a^2 \sin^2 \varphi + b^2 \cos^2 \varphi}$$

$$\gamma(x) = \begin{pmatrix} x \\ \alpha(x) \end{pmatrix} \rightarrow \gamma'(x) = \begin{pmatrix} 1 \\ \alpha'(x) \end{pmatrix} \quad a \leq x \leq b$$

$$\int_{\gamma_1} f(x, y) dx = \int_a^b f(x, \alpha(x)) dx$$

$$- \int_{\gamma_4} f dx = - \int_a^b f(x, \beta(x)) dx$$

$$\int_{\partial D} f dx = \int_a^b f(x, \alpha(x)) dx - \int_a^b f(x, \beta(x)) dx$$

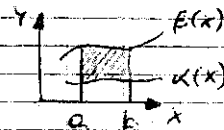
allo stesso modo si può dimostrare che

$$\iint_D \frac{\partial f}{\partial x} dx dy = \int_{\partial D} f dy$$

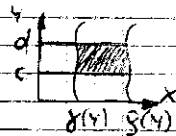
↓ quindi

1° TEOREMA nel PIANO $\mathbb{R}^2$

$$\iint_D \frac{\partial f(x, y)}{\partial y} dx dy = - \int_{\partial D} f(x, y) dx$$



$$\iint_D \frac{\partial f(x, y)}{\partial x} dx dy = \int_{\partial D} f(x, y) dy$$



Queste formule valgono per regioni generiche, e se vi sono dei buchi, si considerano con ∂D anche i bordi dei buchi.

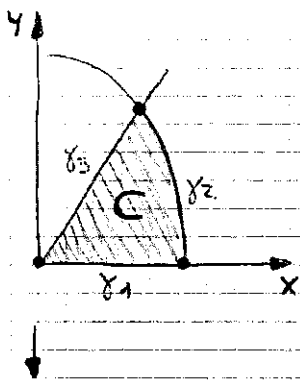
CONSEGUENZA del TEOREMA 1 in un CAMPO VETTORIALE

$$\vec{F}(x, y) = \begin{pmatrix} f_1(x, y) \\ f_2(x, y) \end{pmatrix}$$

$$\iint_D \frac{\partial f_2}{\partial x} dx dy = \int_{\partial D} f_2 dy$$

→ proviamo a sottrarre
membro a membro

$$\iint_D \frac{\partial f_1}{\partial y} dx dy = - \int_{\partial D} f_1 dx$$



$$\int_{\gamma} \vec{F} \cdot d\vec{P} = \int_{\gamma} \begin{pmatrix} -2y \\ 3x \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix} = \int_{\gamma} (-2y dx + 3x dy)$$

$$\int_{\gamma} \vec{F} \cdot d\vec{P} = \int_{\gamma_1} \vec{F} \cdot d\vec{P} + \int_{\gamma_2} \vec{F} \cdot d\vec{P} + \int_{\gamma_3} \vec{F} \cdot d\vec{P}$$

$$\textcircled{1} \vec{\gamma}_1(t) = \begin{pmatrix} t \\ 0 \end{pmatrix} \quad 0 \leq t \leq 2 \quad \vec{\gamma}_1' = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \rightarrow \int_{\gamma_1} \vec{F} \cdot d\vec{P} = \int_0^2 \begin{pmatrix} 0 \\ 3t \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} dt = 0$$

$$\textcircled{2} \vec{\gamma}_2(t) = \begin{pmatrix} 2 \cos t \\ 4 \sin t \end{pmatrix} \quad 0 \leq t \leq \frac{\pi}{4} \quad \vec{\gamma}_2' = \begin{pmatrix} -2 \sin t \\ 4 \cos t \end{pmatrix}$$

$$\int_{\gamma_2} \vec{F} \cdot d\vec{P} = \int_0^{\pi/4} \begin{pmatrix} -8 \sin t \\ 6 \cos t \end{pmatrix} \begin{pmatrix} -2 \sin t \\ 4 \cos t \end{pmatrix} dt = \int_0^{\pi/4} (16 \sin^2 t + 24 \cos^2 t) dt =$$

$$= \int_0^{\pi/4} (16 - 16 \cos^2 t + 24 \cos^2 t) dt = \int_0^{\pi/4} (16 + 8 \cos^2 t) dt = \int_0^{\pi/4} 16 + 8 \cdot \frac{1}{2} (1 + \cos 2t) dt = 5\pi + 2$$

$$\textcircled{3} \vec{\gamma}_3(t) = \begin{pmatrix} t \\ 2t \end{pmatrix} \quad 0 \leq t \leq \sqrt{2} \quad \vec{\gamma}_3' = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\int_{\gamma_3} \vec{F} \cdot d\vec{P} = - \int_0^{\sqrt{2}} \begin{pmatrix} -4t \\ 3t \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} dt = - \int_0^{\sqrt{2}} (-4t + 6t) dt = -2$$

$$\bar{I} = 0 + (5\pi + 2) - 2 = 5\pi \quad \text{Lavoro compiuto da } F \text{ lungo } \gamma$$

$$\oint_{\gamma} \begin{pmatrix} -2y \\ 3x \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix} = \iint_C \quad (\text{Formula di Green})$$

$$\iint_C \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \iint_C (3 - (-2)) dx dy = 5 \iint_C dx dy = 5\pi$$

$$\iint_C dx dy = \pi$$

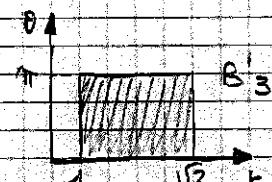
$$③ \int_{\Sigma_3} \vec{f} \cdot \vec{n} \, dS = \rightarrow \text{parametrizzazione esplicita } \vec{S}(x,y) = \begin{pmatrix} x \\ y \\ \sqrt{2-x^2-y^2} \end{pmatrix}$$

$$\|\vec{N}\| = \sqrt{1 + \left(\frac{-2x}{2\sqrt{2-x^2-y^2}}\right)^2 + \left(\frac{-2y}{2\sqrt{2-x^2-y^2}}\right)^2} \rightarrow \vec{N} = \begin{pmatrix} -x \\ -y \\ 1 \end{pmatrix}$$

$$\iint_{\Sigma_3} \vec{f} \cdot \vec{n} \, dS = \iint_{B_3} \left(2(x^2+y^2) \cdot \sqrt{2-x^2-y^2} + \frac{2}{3} \left(\sqrt{2-x^2-y^2} \right)^3 \right) dx dy =$$

passo a coordinate polari

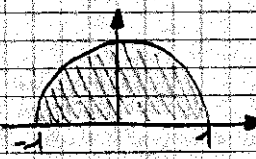
$$\begin{cases} x = r \cos \varphi \\ y = r \sin \varphi \end{cases} \quad J = r$$

$$\iint_{B'_3} \left(2r^2 \sqrt{2-r^2} + \frac{2}{3} \left(\sqrt{2-r^2} \right)^3 \right) r \, dr \, d\varphi =$$


$$= \pi \int_1^{\sqrt{2}} 2r^3 \sqrt{2-r^2} \, dr + \int_1^{\sqrt{2}} \pi r \left(\sqrt{2-r^2} \right)^3 \, dr =$$

sostituisco
 $2-r^2 = t$
 $dr = -\frac{1}{2} dt$

$$= \dots = \frac{16}{15} \pi$$

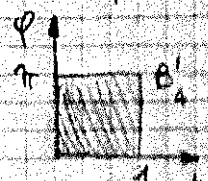
$$④ \int_{\Sigma_4} \vec{f} \cdot \vec{n} \, dS$$


$$z = \sqrt{x^2+y^2}$$

$$\rightarrow \iint_{B_4} \left(2(x^2+y^2) \sqrt{x^2+y^2} + \frac{2}{3} \left(\sqrt{x^2+y^2} \right)^3 \right) \cdot \begin{pmatrix} -\frac{\partial z}{\partial x} \\ -\frac{\partial z}{\partial y} \\ 1 \end{pmatrix} dx dy =$$

$$= \iint_{B_4} \left(2(x^2+y^2) \sqrt{x^2+y^2} + \frac{2}{3} \left(\sqrt{x^2+y^2} \right)^3 \right) dx dy = \iint_{B'_4} \left(2r^2 \cdot r + \frac{2}{3} r \right) r \, dr \, d\varphi =$$

$$= \pi \left[2 \frac{r^5}{5} + \frac{2}{3} \frac{r^5}{5} \right]_0^1 = \frac{2}{5} \pi + \frac{2}{15} \pi = \frac{8}{15} \pi$$



$$I = 0 + 0 + \frac{16}{15} \pi + \frac{8}{15} \pi = \frac{24}{15} \pi = \frac{8}{5} \pi$$

$$\iiint_V \operatorname{div} \vec{F}(x, y, z) \, dx \, dy \, dz = \int_{\partial V} \vec{F} \cdot \vec{n} \, dS$$

TEOREMA di GAUSS
o della DIVERGENZA in $\mathbb{R}^3$

$$\int_S \operatorname{rot} \vec{F} \cdot \vec{n} \, dS = \int_{\partial S} \vec{F} \cdot d\vec{P} \quad \text{TEOREMA di STOKES in } \mathbb{R}^3$$

OSSERVAZIONI

Prodotto di funzioni scalari

$$\iint_{\Omega} \frac{\partial(fg)}{\partial x} \, dx \, dy = \int_{\partial\Omega} fg \, dy$$

$$\iint_{\Omega} \frac{\partial(fg)}{\partial y} \, dx \, dy = - \int_{\partial\Omega} fg \, dx$$

da queste formule si ricava una formula di integrazione per parti in due variabili

$$\iint_{\Omega} \frac{\partial f}{\partial x} g \, dx \, dy = \int_{\partial\Omega} fg \, dy - \iint_{\Omega} f \frac{\partial g}{\partial x} \, dx \, dy$$

$$\iint_{\Omega} \frac{\partial f}{\partial y} g \, dx \, dy = - \int_{\partial\Omega} fg \, dx - \iint_{\Omega} f \frac{\partial g}{\partial y} \, dx \, dy$$

SERIE NUMERICHE

Supponiamo di fare la somma di un numero finito di numeri $a_1, a_2, \dots, a_n$:

$$a_1 + a_2 + \dots + a_n = \sum_{k=1}^n a_k = \frac{(n+1) \cdot n}{2} \quad \text{numeri interi successivi} \quad \text{FORMULA di GAUSS}$$

Vediamo un altro caso di somme finite con formula:

$$\sum_{k=0}^n \left(\frac{1}{2}\right)^k = 1 + \frac{1}{2} + \frac{1}{2^2} + \dots + \frac{1}{2^n} = \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}}$$

se

$\lim_{n \rightarrow +\infty} S_n = l \in \mathbb{R}$ si dice che la serie CONVERGE, e la somma è l

se

$\lim_{n \rightarrow +\infty} S_n = \begin{cases} +\infty \\ -\infty \\ \infty \end{cases}$ si dice che la serie DIVERGE $\begin{cases} + \\ - \\ \text{diverge} \end{cases}$

se

$\lim_{n \rightarrow +\infty} S_n = \text{NON ESISTE}$ (né finito, né infinito) si dice che la serie è INDETERMINATA o OSCILLANTE

es. 1

$$\sum_{n=0}^{+\infty} \left(\frac{1}{2}\right)^n = \lim_{n \rightarrow +\infty} S_n = \lim_{n \rightarrow +\infty} \frac{1 - \left(\frac{1}{2}\right)^{n+1}}{1 - \frac{1}{2}} = \frac{1}{1 - \frac{1}{2}} = 2 \quad \text{CONVERGE}$$

es. 2

$$\sum_{n=0}^{+\infty} 1^n = S_n = n+1 \xrightarrow{n \rightarrow +\infty} +\infty \quad \text{DIVERGE positivamente}$$

es. 3

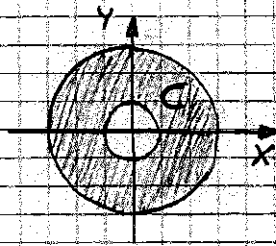
$$\sum_{n=0}^{+\infty} (-1)^n \rightarrow \text{OSCILLANTE} \rightarrow S_0=1 \quad S_1=0 \quad S_2=1 \quad S_3=0 \quad S_4=1 \dots$$

OSSERVAZIONI

$$r \neq 1 \quad \sum_{n=0}^{+\infty} r^n = \lim_{n \rightarrow +\infty} S_n = \lim_{n \rightarrow +\infty} \frac{1 - r^{n+1}}{1 - r} = \begin{cases} \frac{1}{1-r} & \text{se } |r| < 1 \\ +\infty & \text{se } r \geq 1 \\ \text{oscilla se } r = -1 \\ \text{diverge se } r < -1 \\ \text{oscilla} & \text{(oscilla tra valori sempre più grandi)} \end{cases}$$

$$\pm \vec{N} = \pm \begin{pmatrix} -\frac{\partial}{\partial x} 3\sqrt{x^2+y^2} \\ -\frac{\partial}{\partial y} 3\sqrt{x^2+y^2} \\ 1 \end{pmatrix}$$

svolgo il +



$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

$$C: \left(\frac{1}{3}\right)^2 \leq x^2 + y^2 \leq \left(\frac{2}{3}\right)^2$$

$$\int_{\Sigma} \text{rot } \vec{F} \cdot \vec{N} = \iint_C \begin{pmatrix} 0 \\ 0 \\ 2x - 3y^2 \end{pmatrix} \cdot \begin{pmatrix} - \\ - \\ 1 \end{pmatrix} dx dy = \iint_C (2 + \cos \theta - 3r^2 \sin^2 \theta) r dr d\theta =$$

$$= \int_{1/3}^{2/3} 2r^2 dr \int_0^{2\pi} \cos \theta d\theta - \int_{1/3}^{2/3} 3r^3 dr \int_0^{2\pi} \sin^2 \theta d\theta = \left[\frac{3}{4} r^4 \right]_{1/3}^{2/3} \cdot \left[\frac{1}{2} \theta - \sin \theta \cos \theta \right]_0^{2\pi} =$$

$$= - \left[\frac{16}{4} - \frac{1}{4} \right] \pi = - \frac{15}{4} \pi$$

GHE!

posso applicare STOKES e verificare

$$\int_{\Sigma} \text{rot } \vec{F} \cdot \vec{n} dS = \oint_{\partial \Sigma} \vec{F} \cdot d\vec{P} \quad d\vec{P} = \vec{r}$$

$$\gamma_1: \begin{cases} x^2 + y^2 = \left(\frac{2}{3}\right)^2 \\ z = 2 \end{cases}$$

$$\gamma_2: \begin{cases} x^2 + y^2 = \left(\frac{1}{3}\right)^2 \\ z = 1 \end{cases}$$

$$\gamma_1(t) = \begin{pmatrix} \frac{2}{3} \cos t \\ \frac{2}{3} \sin t \\ 2 \end{pmatrix} \quad \gamma_2(t) = \begin{pmatrix} \frac{1}{3} \cos t \\ \frac{1}{3} \sin t \\ 1 \end{pmatrix}$$

$$\int_{\partial \Sigma} \vec{F} \cdot d\vec{P} = \int_0^{2\pi} \begin{pmatrix} \frac{2}{3} \sin t \\ -\frac{2}{3} \cos t \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -\frac{2}{3} \sin t \\ \frac{2}{3} \cos t \\ 0 \end{pmatrix} dt - \int_0^{2\pi} \begin{pmatrix} \frac{1}{3} \sin t \\ -\frac{1}{3} \cos t \\ 0 \end{pmatrix} \cdot \begin{pmatrix} -\frac{1}{3} \sin t \\ \frac{1}{3} \cos t \\ 0 \end{pmatrix} dt =$$

$$= \int_0^{2\pi} \left(-\left(\frac{2}{3} \sin t\right)^4 + \left(\frac{2}{3} \cos t\right)^3 \right) dt - \int_0^{2\pi} \left(-\left(\frac{1}{3} \sin t\right)^4 + \left(\frac{1}{3} \cos t\right)^3 \right) dt = \dots = - \frac{5}{36} \pi$$

$$S_{2^n} > n \cdot \frac{1}{2} \xrightarrow{n \rightarrow +\infty} +\infty \quad \text{la serie DIVERGE}$$

TEOREMA della CONDIZIONE NECESSARIA (ma non sufficiente)

Sia

$$\sum_{n=1}^{+\infty} a_n \quad \text{una serie convergente, allora } a_n \text{ è infinitesimo}$$

cioè

$$\lim_{n \rightarrow +\infty} a_n = 0$$

Dim.

$$S_n = \sum_{k=1}^n a_k \quad S_{n-1} = \sum_{k=1}^{n-1} a_k \quad S_n = S_{n-1} + a_n$$

$$\underbrace{a_1 + a_2 + \dots + a_{n-1} + a_n}_{S_{n-1}} + a_n$$

$$\underbrace{\hspace{10em}}_{S_n}$$



$$\lim_{n \rightarrow +\infty} S_n = l \in \mathbb{R} \xrightarrow{n \rightarrow +\infty} a_n = S_n - S_{n-1} = l - l = 0$$

OSSERVAZIONE

La condizione non è sufficiente, cioè non è vero che

$$\lim_{n \rightarrow +\infty} a_n = 0 \not\Rightarrow \sum_{n=1}^{+\infty} a_n \text{ CONVERGE}$$

CONTROESEMPIO

$$\sum_{n=1}^{+\infty} \frac{1}{n} = +\infty$$

S_n converge perché, essendo i termini positivi, non può oscillare

$$0 \leq S_n \leq T_n \quad T_n \rightarrow +\infty$$

ra!
y)

es. $\sum_{n=1}^{+\infty} \frac{1}{n^2} = 1 + \frac{1}{4} + \frac{1}{9} + \dots + \frac{1}{n^2} + \dots$

$$\frac{1}{n \cdot n} = \frac{1}{n^2} < \frac{1}{n(n-1)} \quad n \geq 2$$

$$\sum_{n=2}^{+\infty} \frac{1}{n(n-1)} = 1 \quad \text{SERIE di MENGOLI}$$

due

$$\downarrow$$

$$\sum_{n=1}^{+\infty} \frac{1}{n^2} < 1 + \sum_{n=2}^{+\infty} \frac{1}{n(n-1)} = 2$$

Cosa si intende per DEFINITIVO nelle serie:

aggiungendo un numero finito di termini (positivi o negativi) non si cambia la qualità della serie, cioè il suo comportamento (convergenza, divergenza, oscillanza).
Una serie DEFINITIVAMENTE a TERMINI POSITIVI è quella serie che ha i termini $a_n \geq 0$ per $n \geq N$ con N opportuno.

Si può applicare il teorema del confronto alle serie definitivamente positive

$$1) \sum_{n=1}^{+\infty} a_n \quad a_n \geq 0 \text{ per } n \geq N$$

$$\rightarrow 0 \leq a_n \leq b_n \quad \forall n \geq N$$

$$2) \sum_{n=1}^{+\infty} b_n \quad b_n \geq 0 \text{ per } n \geq N$$

La convergenza di 2) $\Rightarrow$ convergenza di 1)

La divergenza di 1) $\Rightarrow$ divergenza di 2)

CRITERIO del CONFRONTO con un INTEGRALE

Hip: $\sum_{n=1}^{+\infty} a_n$ $a_n \geq 0$

e esiste una $f(x)$ continua per $x \geq 0$, decrescente e positiva tale che

$$f(n) = a_n$$

① $\int_1^{+\infty} f(x) dx$ CONVERGE

allora anche la serie $\sum_{n=1}^{+\infty} a_n$ CONVERGE

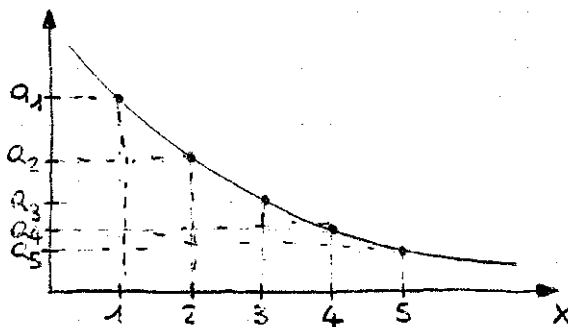
mentre se

→ vale anche il contrario

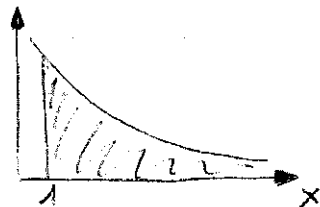
② $\int_1^{+\infty} f(x) dx$ NON CONVERGE

allora anche la serie $\sum_{n=1}^{+\infty} a_n$ NON CONVERGE

Dim.

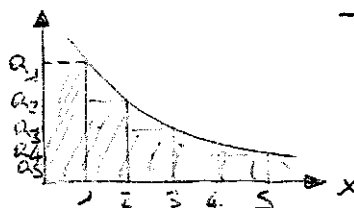


$$\int_1^{+\infty} f(x) dx$$



①

$$\sum_{n=2}^{+\infty} a_n$$



$$\rightarrow 0 \leq \sum_{n=2}^{+\infty} a_n \leq \int_1^{+\infty} f(x) dx$$

CONVERGE $\Leftarrow$ CONVERGE

non può divergere e non può oscillare, perché è a termini positivi

$$\sum_{n=1}^{+\infty} \frac{1}{n^2} \quad \text{CONVERGE} \quad \alpha = 2$$

Da questi ultimi due casi noti si deduce per confronto che:

$$\sum_{n=1}^{+\infty} \frac{1}{n^\alpha} \quad \text{CONVERGE} \quad \text{se } \alpha \geq 2 \quad \text{perché } \frac{1}{n^\alpha} \leq \frac{1}{n^2}$$

$$\sum_{n=1}^{+\infty} \frac{1}{n^\alpha} \quad \text{DIVERGE} \quad \text{se } 0 \leq \alpha \leq 1 \quad \text{perché } \frac{1}{n} \leq \frac{1}{n^\alpha} \quad 0 \leq \alpha \leq 1$$

Utilizziamo ora il criterio del CONFRONTO INTEGRALE per studiare i casi con

$$1 < \alpha < 2$$

$$\sum_{n=1}^{+\infty} \frac{1}{n^\alpha} \quad f(x) = \frac{1}{x^\alpha} \quad f(n) = \frac{1}{n^\alpha} \quad \alpha > 0$$

$$\int_1^{+\infty} \frac{1}{x^\alpha} dx = \quad \alpha > 0 \text{ e } \alpha \neq 1$$

$$= \left[\frac{1}{-\alpha+1} x^{-\alpha+1} \right]_1^{+\infty} = \frac{1}{1-\alpha} \quad \text{se } \alpha > 1$$

$$\rightarrow \sum_{n=1}^{+\infty} \frac{1}{n^\alpha} \quad \text{CONVERGE} \quad \text{se } \alpha > 1$$

$$= \left[\frac{1}{-\alpha+1} x^{-\alpha+1} \right]_1^{+\infty} = +\infty \quad \text{se } 0 < \alpha \leq 1$$

es. 1 $\sum_{n=1}^{+\infty} \frac{1}{\sqrt[10]{n}} = \sum_{n=1}^{+\infty} \frac{1}{n^{1/10}} \quad \text{DIVERGE} \quad 0 < \frac{1}{10} < 1$

es. 2 $\sum_{n=1}^{+\infty} \frac{1}{\sqrt[6]{n^5}} = \sum_{n=1}^{+\infty} \frac{1}{n^{5/6}} \quad \text{CONVERGE} \quad 1 < \frac{6}{5}$

2° caso $|c| < 1$

$\forall \varepsilon > 0$ e prendiamo ε in modo che $1 + \varepsilon < 1$

$$1 - \varepsilon < \frac{a_{n+1}}{a_n} < 1 + \varepsilon < 1$$

$$a_{n+1} < q a_n < q^2 a_{n-1} < \dots < q^k a_n$$

$\sum_{n=1}^{+\infty} q^k a_n$ serie geometrica di $r = q$ o $0 < q < 1$

converge $\Rightarrow$ converge anche la serie

CRITERIO della RADICE

Hp: $\sum_{n=1}^{+\infty} a_n$ $a_n \geq 0$

$$\lim_{n \rightarrow +\infty} \sqrt[n]{a_n} = l$$

allora se

$l < 1$ CONVERGE

$l > 1$ DIVERGE

$l = 1$ il criterio non funziona

Dim. Analoga alla precedente, ci si riconduce al confronto definitivo con una serie geometrica

es. $\sum_{n=0}^{+\infty} \frac{n}{e^n}$ $a_n = \frac{n}{e^n}$

$$\lim_{n \rightarrow +\infty} \sqrt[n]{\frac{n}{e^n}} = \lim_{n \rightarrow +\infty} \frac{\sqrt[n]{n}}{e} = \frac{1}{e} < 1 \quad \text{la serie converge}$$

$$\lim_{n \rightarrow +\infty} \sqrt[n]{n} = \lim_{n \rightarrow +\infty} e^{\log \sqrt[n]{n}} = \lim_{n \rightarrow +\infty} e^{\frac{1}{n} \log n} = e^0 = 1$$

se $\sum_{n=1}^{+\infty} (-a_n) = - \sum_{n=1}^{+\infty} a_n$ $a_n \geq 0$

SERIE a SEGNI ALTERNI

$$\sum_{n=0}^{+\infty} (-1)^n a_n = \quad a_n > 0$$

$$= a_0 - a_1 + a_2 + \dots + (-1)^n a_n + \dots$$

CRITERIO di LEIBNIZ per le serie a segni alterni

$$H_p: \sum_{n=1}^{+\infty} (-1)^{n+1} a_n \quad a_n > 0$$

① $a_n \xrightarrow{n \rightarrow +\infty} 0$ condizione necessaria: a_n infinitesimo

② $a_{n+1} < a_n \quad \forall n \rightarrow$ decrescita

allora la serie CONVERGE

inoltre, se indichiamo con S la somma della serie si ha:

$$|S - S_n| \leq a_{n+1}$$

↓

$$S_n = \sum_{k=1}^n (-1)^{k+1} a_k$$

es. 1 $\sum_{n=1}^{+\infty} (-1)^{n+1} \frac{1}{n}$ serie armonica a segni alterni

① $\frac{1}{n} \xrightarrow{n \rightarrow +\infty} 0$

② $\frac{1}{n+1} < \frac{1}{n}$ i termini senza segno sono decrescenti

↓

la serie CONVERGE

$$|S - S_9| = \left| 1 - \frac{1}{2} + \frac{1}{3} - \frac{1}{4} + \frac{1}{5} - \frac{1}{6} + \frac{1}{7} - \frac{1}{8} + \frac{1}{9} - S \right| \leq \frac{1}{10}$$

$$S = \log 2$$

$$\rightarrow \int \frac{1}{x^\alpha} = \begin{cases} \log(x) & \text{se } \alpha=1 \\ \frac{1}{-\alpha+1} \cdot \frac{1}{x^{\alpha-1}} & \alpha \neq 1 \end{cases} \quad \text{se } \alpha > 1 \quad \text{CONVERGE}$$

$$\sum_{n=1}^{+\infty} \frac{\sqrt[7]{n^4 + 3n^3 - 2n^2 + 5}}{\sqrt[3]{n^7 + 8n^2 - 3}} \quad \text{e termini positivi}$$

CONFRONTO ASINTOTICO

$$\frac{\sqrt[7]{n^4 + 3n^3 - 2n^2 + 5}}{\sqrt[3]{n^7 + 8n^2 - 3}} \xrightarrow{n \rightarrow +\infty} 1$$

$$\frac{n^{4/7}}{n^{7/3}}$$

$$\frac{n^{4/7}}{n^{7/3}} = \frac{1}{n^{7/3 - 4/7}} = \frac{1}{n^{37/21}} \quad \alpha = \frac{37}{21} > 1 \quad \text{CONVERGE}$$

es. 3

$$\sum_{n=2}^{+\infty} \frac{5}{7n \log^2 n} = \frac{5}{7} \sum_{n=2}^{+\infty} \frac{1}{n \log^2 n}$$

$$\lim_{n \rightarrow +\infty} \frac{\frac{1}{n \log^2 n}}{\frac{1}{n^\alpha}} = \frac{n^\alpha}{n \log^2 n}$$

il confronto asintotico non porta da nessuna parte

$$\alpha > 1 \quad \alpha \leq 1$$

qui funziona il confronto con un integrale improprio

$$f(x) = \frac{1}{x \log^2 x} \rightarrow \int_2^{+\infty} \frac{1}{x \log^2 x} dx = \begin{matrix} t = \log x \\ dt = \frac{1}{x} \end{matrix}$$

$$= \int_{\log 2}^{+\infty} \frac{1}{t^2} dt = \left[-\frac{1}{t} \right]_{\log 2}^{+\infty} = \frac{1}{\log 2} \quad \text{CONVERGE} \Rightarrow \text{anche la serie CONVERGE}$$

$$\left(\frac{2n+1}{2n+3}\right)^{2n} = \left(1 + \frac{-2}{2n+3}\right)^{2n} = \left(1 + \frac{-2}{2n+3}\right)^{2n+3} \underbrace{\left(1 + \frac{-2}{2n+3}\right)^3}_{n \rightarrow +\infty = 1} =$$

$$= \left(1 + \frac{-2}{2n+3}\right)^{2n+3} = \left[\left(1 + \frac{1}{\frac{2n+3}{-2}}\right)^{\frac{2n+3}{-2}}\right]^{-2} \xrightarrow{n \rightarrow +\infty} \frac{1}{e^2}$$

che è simile a

$$\lim_{n \rightarrow +\infty} \left(1 + \frac{1}{x}\right)^{1/x} = e$$



$$\lim_{n \rightarrow +\infty} \frac{a_{n+1}}{a_n} = \frac{1}{e^2} < 1 \quad \text{CONVERGE}$$

es. 6

$$\sum_{n=0}^{+\infty} (-1)^n \frac{n^2 + 2n + 5}{n^3 + 2n^2 + 3n + 7}$$

serie a segni alterni

$$a_n \xrightarrow{n \rightarrow +\infty} 0$$

$a_n \approx \frac{1}{n}$ per $n \rightarrow +\infty$ se non ci fossero i segni alterni divergerebbe

INVECE

$$\frac{n^2 + 2n + 5}{n^3 + 2n^2 + 3n + 7} > \frac{(n+1)^2 + 2(n+1) + 5}{(n+1)^3 + 2(n+1)^2 + 3(n+1) + 7} \quad \text{CONVERGE}$$

es. 7

$$\sum_{n=2}^{+\infty} (-1)^n \frac{1}{\sqrt[n]{n+1}} \quad \text{segni alterni}$$

$$a_n \xrightarrow{n \rightarrow +\infty} 0$$

$$\frac{1}{\sqrt[n]{n+1}} > \frac{1}{\sqrt[n+1]{n+1+1}} \quad \forall n \geq 2 \quad \text{CONVERGE}$$

INTEGRALI

1) CURVILINEO $\int_Y F(\gamma(t)) \cdot \|\gamma'(t)\| dt$ 2) LINEA $\int_Y F(\gamma(t)) \gamma'(t) dt$

3) SUPERFICIE $\int_{\Sigma} dS = \iint_D \left\| \frac{\partial \mathbf{S}}{\partial u} \wedge \frac{\partial \mathbf{S}}{\partial v} \right\| du dv$ posso avere una f nell'integrale
 o parametrizzata, o $z = f(x, y)$

$$\sqrt{1 + \frac{\partial f^2}{\partial x^2} + \frac{\partial f^2}{\partial y^2}}$$

NORMALE $\begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & 1 \end{vmatrix} = \left(\frac{\partial x}{\partial u}, \frac{\partial x}{\partial v}, 1 \right)$

4) FLUSSO: viene dato $F(x, y, z)$ (campo), e una Σ parametrizzata o $z = g(x, y)$

$$\rightarrow \phi = \iiint_{\Sigma} \operatorname{div} F \, dx dy dz = \iint_{\Sigma} \vec{F} \cdot \vec{n} \, dS$$

ricordarsi di sostituire nel campo $z = g(x, y)$ o la parametrizzazione

5) FLUSSO DEL ROTORE: dato $F(x, y, z)$ e Σ parametrizzata o $z = g(x, y)$

$$\phi = \iint_{\Sigma} \operatorname{rot} \vec{F} \cdot \vec{n} \, dS = \int_{\text{LINEA}} F \, ds$$

• CAMBIO di COORDINATE:

2D 1) polari $\begin{cases} x = p \cos \theta + x_0 \\ y = p \sin \theta + y_0 \end{cases}$
 $\det |J| = p$

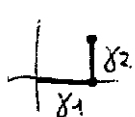
2) ellittiche $\begin{cases} x = a \cos \theta + x_0 \\ y = b \sin \theta + y_0 \end{cases}$
 $\det |J| = ab$

3D 3) sferiche $\begin{cases} x = p \sin \varphi \cos \theta \\ y = p \sin \varphi \sin \theta \\ z = p \cos \varphi \end{cases}$
 $\det |J| = p^2 \sin \varphi$

4) cilindriche $\begin{cases} x = p \cos \theta \\ y = p \sin \theta \\ z = t \end{cases}$
 $\det |J| = p$

• POTENZIALI

viene dato il campo $F(x, y)$, parametrizzo una generica curva che unisce due punti



$$\gamma_1 = \begin{cases} x = t & x' = 1 \\ y = 0 & y' = 0 \\ t \in [0, x] \end{cases}$$

$$\gamma_2 = \begin{cases} x(t) = x & x' = 0 \\ y = t & y' = 1 \\ t \in [0, y] \end{cases}$$

$$\int_{\text{LINEA}} F \, ds = \int_{\gamma_1} + \int_{\gamma_2}$$

CAMPO CONSERVATIVO:

$$\operatorname{rot} F = 0$$

$$D = \mathbb{R}^2, \mathbb{R}^3$$

semplicemente
connesso

$$\text{LAVORO } L = U(B) - U(A)$$

3) FUNZIONI

$$\lim_{n \rightarrow +\infty} f_n(x) = f(x) \xrightarrow{\text{converge puntualmente}} \lim_{n \rightarrow +\infty} \sup (f_n(x) - f(x)) = 0$$

$$= (f_n(x) - f(x))^+ = 0 \quad \text{trovo una } x, \text{ verifico che sia MAX, sostituisco in } f_n(x) \text{ e faccio il lim}$$

se $\lim_{n \rightarrow +\infty} \sup (f_n(x)) = 0$ la serie converge naturalmente (punt. e unif.)

WEIERSTRASS : $|f_n(x)| \leq M_n$ se $\sum_{n=1}^{+\infty} M_n$ converge
serie numerica $\Downarrow$
 $f_n(x)$ converge totalmente

4) POTENZE

criterio del RAPPORTO o RADICE, $\lim_{n \rightarrow +\infty} \frac{a_{n+1}}{a_n} / \sqrt[n]{a_n} = L$ $R = \frac{1}{L}$

su $(-R, R)$ la serie converge assolut. e punt.

studio poi gli estremi di $(-R, R)$ per vedere se l'insieme è chiuso

→ la serie converge uniformemente in $(a, b) \subset (-R, R)$
 $0 < a < b < R$

5) FOURIER

data serie a tratti, calcolo la serie di Fourier:

$$S_n(x) = a_0 + \sum_{n=1}^{\infty} a_n \cos(nx) + b_n \sin(nx)$$

caso generale:

$$a_0 = \frac{1}{T} \int_0^T f(x) dx \quad a_n = \frac{2}{T} \int_0^T f(x) \cos(n \frac{2\pi}{T} x) dx \quad b_n = \frac{2}{T} \int_0^T f(x) \sin(n \frac{2\pi}{T} x) dx$$

f pari:

$$a_0 = \frac{2}{T} \int_0^{T/2} f(x) dx \quad a_n = \frac{4}{T} \int_0^{T/2} f(x) \cos(n \frac{2\pi}{T} x) dx \quad b_n = 0$$

f dispari:

$$a_n = 0 \quad a_0 = 0 \quad b_n = \frac{4}{T} \int_0^{T/2} f(x) \sin(n \frac{2\pi}{T} x) dx$$

1) TEOREMA FUNZIONI DIFFERENZIABILI

f Differenziabile in x_0 se $\bar{e}$ $\begin{cases} \text{continua} \\ \text{derivate} \\ \text{parziali} \\ \text{direzionali} \end{cases}$
(sia di classe C^1)

P : cioè se $\lim_{\|H\| \rightarrow 0} \frac{\omega(x_0+H) - \omega(x_0) - \nabla \omega(x_0)H}{\|H\|} = 0$

Dim.

$$\frac{\partial f}{\partial v} = \lim_{h \rightarrow 0} \frac{\omega(x_0 + hv) - \omega(x_0)}{h} \quad hv = H$$

considero

$$\rightarrow \omega(x_0 + H) - \omega(x_0) = \nabla \omega(x_0)H + o(\|H\|)$$

sostituisco nel numeratore del lim:

$$\lim_{h \rightarrow 0} \frac{\nabla \omega(x_0) \cdot hv}{h} + \frac{o(\|h\|)}{h} = \nabla \omega(x_0)v + 0$$

$$\rightarrow \frac{\partial f}{\partial v} = \nabla \omega(x_0)v$$

2) LAVORO non dipende dal PERCORSO

$$H_p: \exists g(P)/F(P) = \text{grad } g(P)$$

$D = \text{dom } F(P)$ $\bar{e}$ aperto connesso

$F(P)$ continua

$$Th: \int_{\gamma(A,B)} F(P) dP = g(B) - g(A)$$

$$\int_{\gamma(A,B)} F(P) dP = \gamma(t) = \begin{cases} x = x(t) \\ y = y(t) \\ z = z(t) \end{cases} \quad t \in [t_A, t_B]$$

$\downarrow$

$$\begin{aligned} & \int \left[f_1(P(t)) \frac{dx}{dt} dt + f_2(P(t)) \frac{dy}{dt} dt + f_3(P(t)) \frac{dz}{dt} dt \right] = \\ & = \int_{t_A}^{t_B} \left[\frac{\partial g(P(t))}{\partial x} \frac{dx}{dt} + \frac{\partial g(P(t))}{\partial y} \frac{dy}{dt} + \frac{\partial g(P(t))}{\partial z} \frac{dz}{dt} \right] dt = \\ & = \int_{t_A}^{t_B} \frac{dg(P \circ \gamma(t))}{dt} dt = \left[g(P \circ \gamma(t)) \right]_{t_A}^{t_B} = g(B) - g(A) \end{aligned}$$

5) CRITERIO DI POTENZIALE

$$H_p: F(P) = \text{grad } g(P)$$

$$Th: \text{rot}(F(P)) = (0, 0, 0)$$

calcolo il $\text{rot}(F(P))$:

$$\begin{aligned} \text{rot}(F(P)) &= \left(\frac{\partial f_3}{\partial y} - \frac{\partial f_2}{\partial z} \right) \hat{i} + \left(\frac{\partial f_1}{\partial z} - \frac{\partial f_3}{\partial x} \right) \hat{j} + \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right) \hat{k} = \\ &= \left(\frac{\partial}{\partial y} \left(\frac{\partial g(P)}{\partial z} \right) - \frac{\partial}{\partial z} \left(\frac{\partial g(P)}{\partial y} \right) \right) \hat{i} + \left(\frac{\partial^2 g(P)}{\partial z \partial x} - \frac{\partial^2 g(P)}{\partial x \partial z} \right) \hat{j} + \left(\frac{\partial^2 g(P)}{\partial x \partial y} - \frac{\partial^2 g(P)}{\partial y \partial x} \right) \hat{k} \end{aligned}$$

per il teorema della inversione delle derivate:

$$\frac{\partial^2 g(P)}{\partial x \partial y} = \frac{\partial^2 g(P)}{\partial y \partial x} \Rightarrow \text{rot}(F(P)) = (0, 0, 0) = \vec{0}$$

6) TEOREMA del DINI (1)

$$\text{data } g(x_1, x_2, \dots, x_n) = 0 \quad \mathbb{R}^n \rightarrow \mathbb{R}$$

$$H_p: x_0 = (x_1^0, x_2^0, \dots, x_n^0)$$

$$Th: x_i = f_i(x_1, x_2, \dots, x_n) \\ \mathbb{R}^{n-1} \rightarrow \mathbb{R}$$

$$g(x_0) = 0$$

$$\frac{\partial g(x_0)}{\partial x_i} \neq 0$$

c.s. $\nabla g(x_0) \neq \vec{0}$ per esplicitare una funzione

7) TEOREMA del DINI (2)

$$\text{sia } \nabla g(x_0) \neq \vec{0} \quad \text{e} \quad x_j = f(x_1, x_2, \dots, x_n)$$

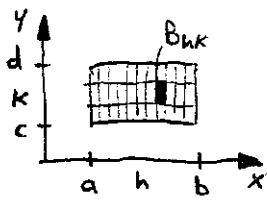
allora

$$Th: \frac{\partial f_i}{\partial x_j} = - \frac{\frac{\partial g(x)}{\partial x_j}}{\frac{\partial g(x)}{\partial x_i}} \quad j \neq i$$

Dim.

$$(g \circ f_i)(x_1, x_2, \dots, x_n) = 0 \rightarrow \frac{\partial (g \circ f_i)}{\partial x_i} = \frac{\partial g}{\partial x_i} + \frac{\partial g}{\partial x_j} \frac{\partial f_i}{\partial x_i} = 0 \rightarrow \frac{\partial f_i}{\partial x_j} = - \frac{\frac{\partial g}{\partial x_j}}{\frac{\partial g}{\partial x_i}}$$

10) INTEGRALE di RIEMANN



$$B = \{(x,y) / a \leq x \leq b, c \leq y \leq d\}$$

$$D: [a,b] \times [c,d]$$

$$B_{hk} = I_h \times I_k$$

adesso definisco l'altezza (del volume)

$$z = f(x,y) \quad \text{LIMITATA}$$

definiamo l'altezza max e min:

$$m_{hk} = \inf_{B_{hk}} f \quad M_{hk} = \sup_{B_{hk}} f$$

somme sup. e inf.:

$$s = s(D, f) = \sum_k \sum_h m_{hk} (x_h - x_{h-1})(y_k - y_{k-1})$$

$$S = S(D, f) = \sum_k \sum_h M_{hk} (x_h - x_{h-1})(y_k - y_{k-1})$$

integrale sup. e inf.:

$$\int_B f = \inf_D S(D, f) \quad \int_B f = \sup_D s(D, f)$$

$$\int_B f \leq \int_B f$$

se c'è uguaglianza la f si dice
Riemann integrabile su B

11) TEOREMA di GULDINO (1) SOLIDI di ROTAZIONE

$$\iiint_{\Omega} dx dy dz$$

coordinate
cilindriche

$$\Omega': \begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$



$$\iiint_{\Omega'} r dr d\theta dz = \iint_A \left(\int_0^{2\pi} r d\theta \right) dr dz = 2\pi \iint_A r dr dz \quad r = x$$

$$= 2\pi \iint_A x dx dz = 2\pi \frac{\iint_A x dx dz}{\iint_A dx dz} \iint_A dx dz \rightarrow I = 2\pi X_G \cdot \iint_A dx dz$$

X_G

$$\begin{aligned} \underline{\text{dim.}} \textcircled{2} \quad \int_{\Omega} \frac{\partial f_3}{\partial z} dx dy dz &= \int_{\Omega} dx dy \left[f_3 \right]_{\alpha(x,y)}^{\beta(x,y)} = \\ &= \int_{\Omega} f_3(x,y,\beta(x,y)) dx dy - \int_{\Omega} f_3(x,y,\alpha(x,y)) dx dy \end{aligned}$$

$$\textcircled{1} = \textcircled{2} \quad \text{C.V.D.}$$

14) TEOREMA di GREEN

$$H_p: \vec{F} = f_1(x,y)\hat{i} + f_2(x,y)\hat{j} \in \mathbb{C}^1$$

Ω piana, chiusa, limitata, semiconvessa

γ chiusa, regolare a tratti, orientata

$$a \leq x \leq b$$

$$\alpha(x) \leq y \leq \beta(x)$$

$$Th: \oint_{\gamma} \vec{F} \cdot d\vec{P} = \int_{\Omega} \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right) dx dy$$

$$\oint_{\gamma} f_1(x,y) dx + f_2(x,y) dy = \int_{\Omega} \left(\frac{\partial f_2}{\partial x} - \frac{\partial f_1}{\partial y} \right) dx dy$$

$\textcircled{1}$
 $\textcircled{2}$

$$\underline{\text{dim.}} \textcircled{1} \quad \int_{\gamma} f_1(x,y) dx = \int_{\gamma_1} f_1(x,y) dx + \int_{\gamma_2} f_1(x,y) dx =$$

$(y=\alpha(x))$
 $(y=\beta(x))$

$$\begin{aligned} &= \int_a^b f_1(x, \alpha(x)) dx + \int_b^a f_1(x, \beta(x)) dx = \\ &= \int_a^b f_1(x, \alpha(x)) dx - \int_a^b f_1(x, \beta(x)) dx \end{aligned}$$

$$\underline{\text{dim.}} \textcircled{2} \quad - \int_{\Omega} \frac{\partial f_1}{\partial y} dx dy = - \int_a^b \left[f_1(x,y) \right]_{\alpha(x)}^{\beta(x)} dx =$$

$$= \int_a^b f_1(x, \alpha(x)) dx - \int_a^b f_1(x, \beta(x)) dx$$

$$\textcircled{1} = \textcircled{2} \quad \text{C.V.D.}$$

18) CONFRONTO ASINTOTICO

 $\varepsilon = \text{epsilon}$ $\sum = \text{pro} \sum (\sigma) = \text{sigma}$

$$\text{Hp: } \sum_1^{\infty} a_n, \sum_1^{\infty} b_n \quad a_n \geq 0, b_n \geq 0 \quad \forall n > N$$

$$\lim_{n \rightarrow +\infty} \frac{a_n}{b_n} = l \neq 0, \infty \quad l \in \mathbb{R}$$

Th: $\sum a_n$ e $\sum b_n$ hanno lo stesso comportamento

Dim. $\varepsilon > 0, \exists n_0 / \forall n > n_0, 1 - \varepsilon < \frac{a_n}{b_n} < 1 + \varepsilon$

$$\rightarrow b_n(1 - \varepsilon) < a_n < b_n(1 + \varepsilon)$$

$$\rightarrow (1 - \varepsilon) \sum_1^{\infty} b_n < \sum_1^{\infty} a_n < (1 + \varepsilon) \sum_1^{\infty} b_n$$

$(1 \pm \varepsilon)$ è un numero finito e non influisce nel comportamento della serie

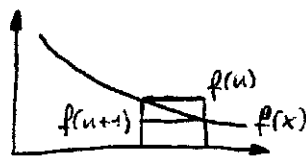
le serie hanno lo stesso comportamento

19) CONFRONTO INTEGRALE

$$\text{Hp: } \sum_1^{\infty} a_n, a_n > 0 \quad \forall n$$

$$f(x) / a_n = f(n) \quad f(x) \text{ monotona decrescente}$$

$$\text{Th: } \sum_1^{\infty} f(n) \quad \text{①}, \int_1^{\infty} f(x) dx \quad \text{②} \quad \text{se conv. ②, conv. ①}$$



$$f(n) \geq f(x) \geq f(n+1) \rightarrow \int_n^{n+1} f(n) dx \geq \int_n^{n+1} f(x) dx \geq \int_n^{n+1} f(n+1) dx$$

svolgo l'integrale:

$$f(n)(n+1 - n) \geq \int_n^{n+1} f(x) dx \geq f(n+1)$$

$$\rightarrow \sum_{k=1}^{+\infty} f(k) \geq \int_1^{\infty} f(x) dx \geq \sum_{k=2}^{+\infty} f(k+1)$$

ripeto lo stesso procedimento da 1 a n+1 per ottenere le $\sum_1^n$ e $\int_1^{n+1}$ e poi applico il $\lim_{n \rightarrow +\infty}$

sostituisco $k+1 = m \rightarrow \sum_{k=1}^{+\infty} f(k) \geq \int_1^{\infty} f(x) dx \geq \sum_{m=2}^{+\infty} f(m)$

l'indice di sommatoria è ∞ untre

$$\sum_{k=1}^{\infty} f(k) \geq \int_1^{\infty} f(x) dx \geq \sum_{k=2}^{\infty} f(k)$$

22) TEOREMA ASSOLUTA CONVERGENZA

$$Hp: \sum_{n=1}^{\infty} |a_n| \text{ conv.}$$

$$Th: \sum_{n=1}^{\infty} a_n \text{ conv.}$$

$$\underbrace{\sum_{n=1}^{\infty} |a_n|}_{\text{conv. per ipotesi}} = \sum_{n=1}^{\infty} \frac{\overset{①}{|a_n| + a_n}}{2} + \sum_{n=1}^{\infty} \frac{\overset{②}{|a_n| - a_n}}{2}$$

$\Rightarrow$ converge il secondo membro e quindi anche $\sum_{n=1}^{\infty} a_n$

① somma dei termini positivi

② somma dei termini negativi

$$\textcircled{1} \begin{cases} = a_n & \text{se } a_n > 0 \\ = 0 & \text{se } a_n < 0 \end{cases}$$

$$\textcircled{2} \begin{cases} = -a_n & \text{se } a_n < 0 \\ = 0 & \text{se } a_n > 0 \end{cases}$$

23) $f_n(x)$ continue e unif. e $S_n(x)$

$$Hp: \sum_{n=0}^{\infty} f_n(x) \text{ con } f_n(x) \text{ continue}$$

unif. a $S(x)$ in $\bar{I}_n$

$$Th: S(x) \text{ continua}$$

formula

Hp:

$$\cdot \varepsilon_n > 0, \exists n_0 / \sup_{x \in \bar{I}_n} |S(x) - S_n(x)| < \varepsilon_n$$

$$\cdot \varepsilon_c > 0, \exists \delta / \forall x \in (x_0 - \delta, x_0 + \delta), |f_n(x) - f_n(x_0)| < \varepsilon_c$$

Dim.

$$|S(x) - S(x_0)| = \text{aggiungo e tolgo } s_n(x)$$

$$= |S(x) + s_n(x) - s_n(x) - S(x_0) + s_n(x_0) - s_n(x_0)| =$$

$$\rightarrow |(S(x) - s_n(x)) - (S(x_0) - s_n(x_0)) + (s_n(x) - s_n(x_0))| \leq$$

$$\leq |(S(x) - s_n(x))| + |S(x_0) - s_n(x_0)| + |s_n(x) - s_n(x_0)| \leq$$

$$\leq 2\varepsilon_n + \varepsilon_c \leq \varepsilon$$

24) CRITERIO di WEIERSTRASS

$$Hp: \sum_{n=0}^{\infty} f_n(x) / \forall x \in [a, b], \forall n |f_n(x)| < M_n$$

$$\sum_{n=0}^{\infty} M_n \text{ converge}$$

$$Th: \sum_{n=0}^{\infty} f_n(x) \text{ converge}$$